



MICROCHIP

Digitally Enhanced Analog Power Control

*Presented by:
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Agenda

- **Digital Power Benefits**
- **Paying the Price for Digital Power**
 - Has this limited the growth?
- **Bridging the Gap from Analog to Digital or Digital to Analog?**
- **Introducing Digitally Enhanced Power Analog Solutions “DEPA”**
- **DEPA Applications**
 - POL, LED Lighting, Battery Chargers and Intelligent DC/DC Converters
- **Demo’s**



Digital Power Benefits

- **Communication**
- **Flexible Configuration**
 - UVLO, Startup, Shutdown
- **Flexible Fault Handling**
 - Over-Current, Over Voltage, Short Circuit
- **Intelligent**
 - Adapts to Changing Environments
 - Adapts to different Loads
- **Reports Status and Diagnostics**
- **Increases Integration?**

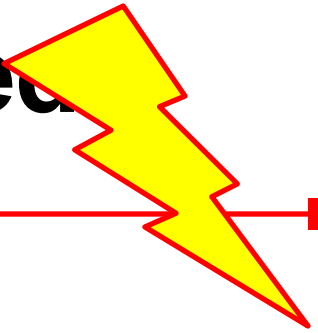


Price of Digital Power

- **What's the cost?**
 - Complexity, Speed and Integration
- **Sense V_{OUT} / I_{PK} / V_{IN} ?**
- **Dynamic Performance / Transient Response**
- **A/D Sampling Speed**
- **Hardware PWM Resolution**
 - Example
- **Is Digital Control Digital Power?**
- **Digitally Enhanced Power Analog**
 - Analog Power Drawbacks



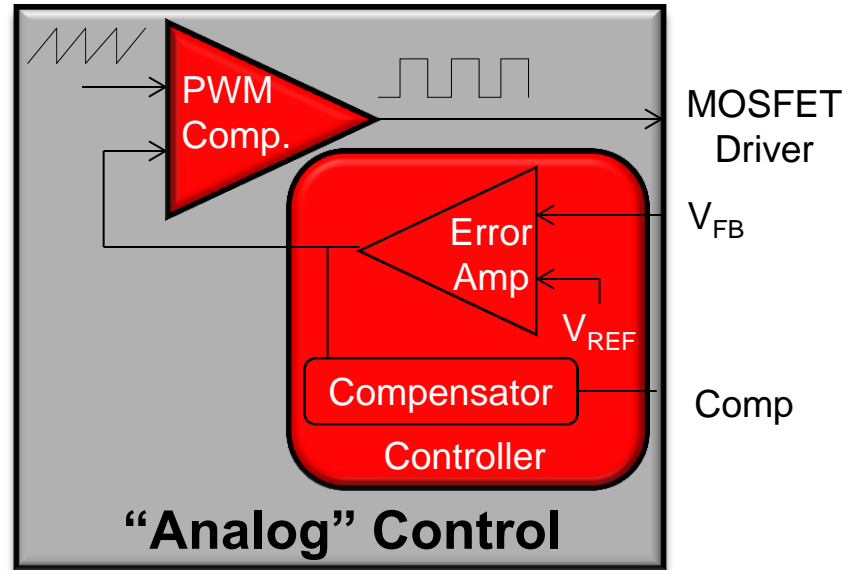
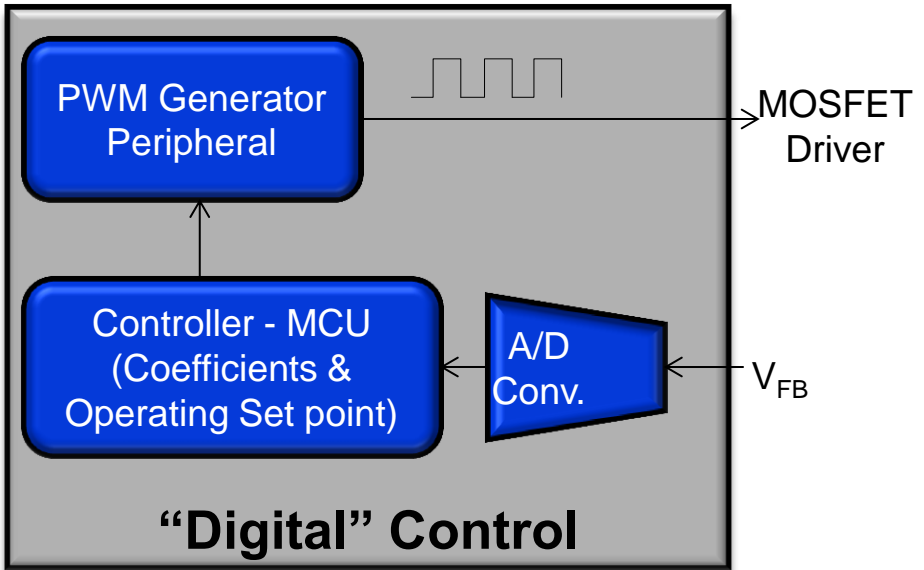
What is Digitally-Enhanced Power Analog?



In Power Conversion Control...

Digital Control
Techniques

Analog Control
Techniques



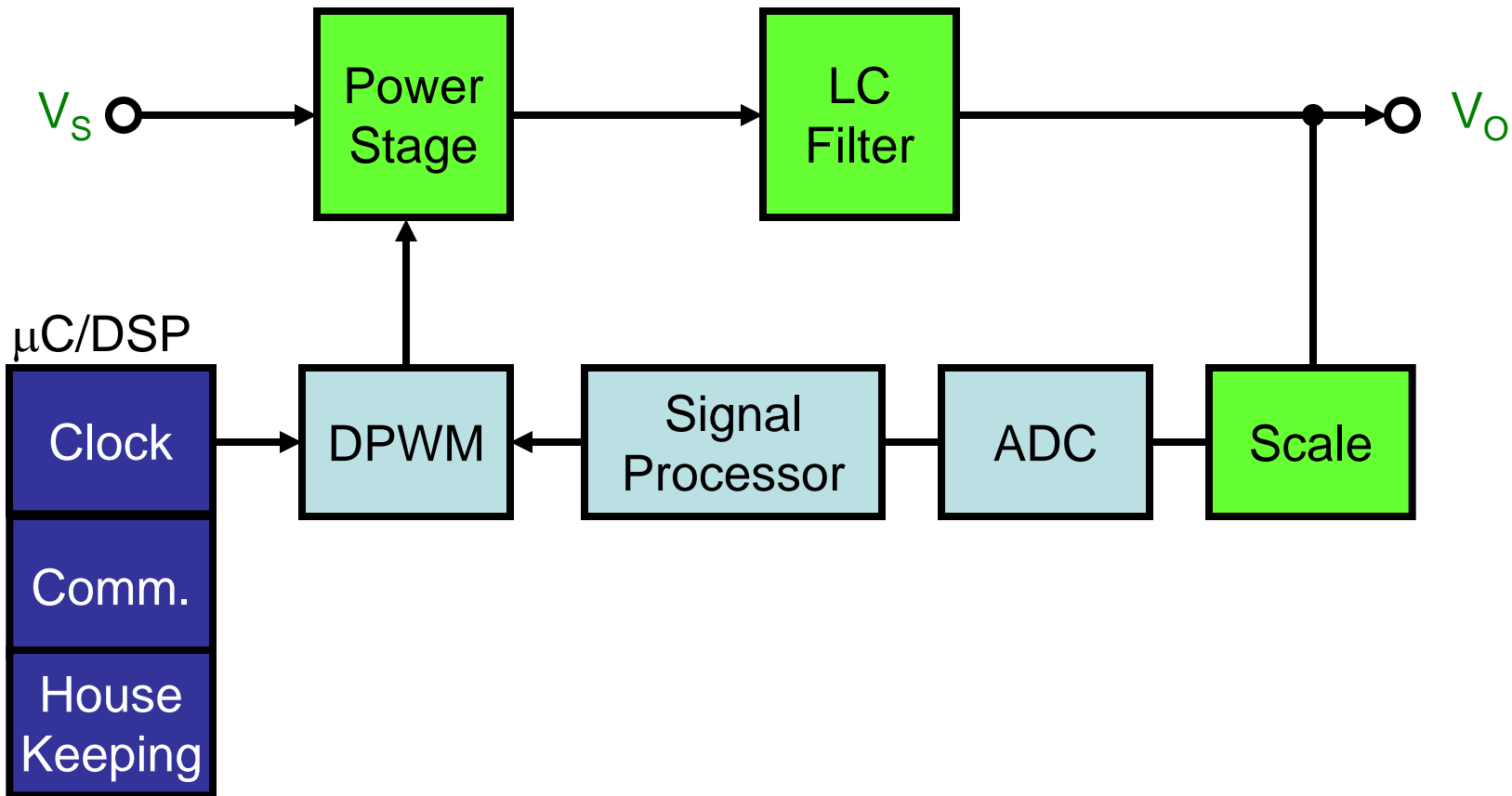


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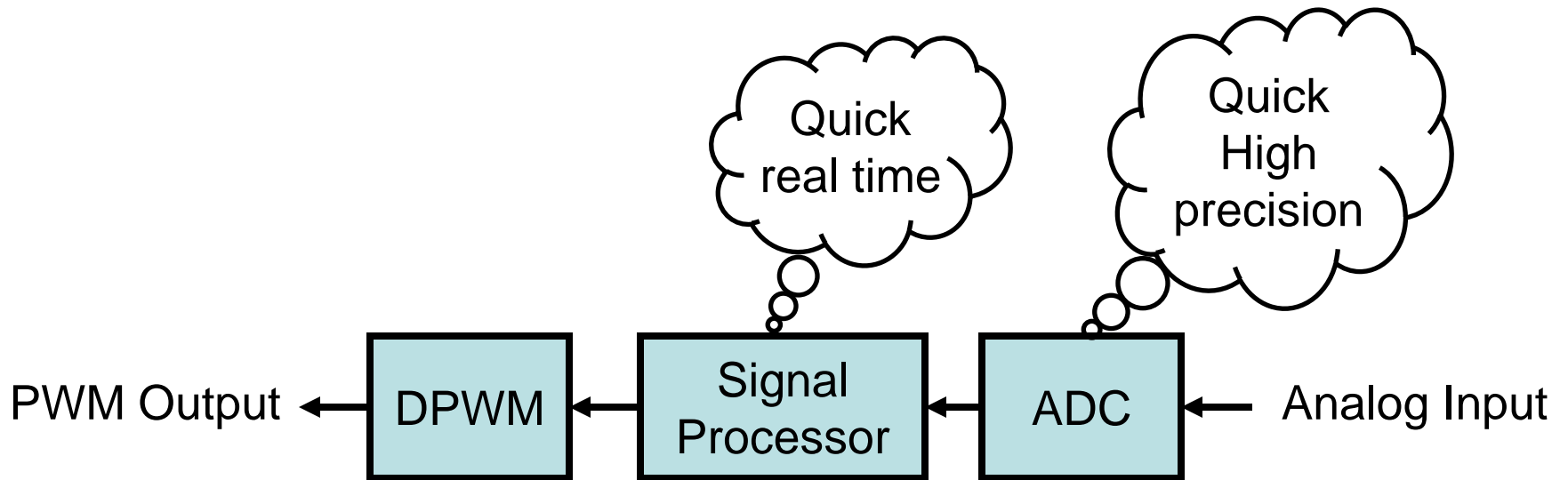
Digital Loop Closure

Digital Loop Closure

- Digital Control



Digital Control





Digital Control

● Analog-to-Digital Converter

- Produces digital data that represents output voltage and / or current
- Resolution and ADC reference voltage set the precision to which the output can be maintained
 - Finite resolution leads to quantization effects



Digital Control

● Digital Pulse Width Modulator

- Performs same drive signal generation as its analog counterpart
- Does so by “calculating” and then “timing” the desired ON and OFF periods
 - Finite resolution leads to quantization effects



Digital Control

- **Quantization Effects - A digital phenomenon**

- Analog control provides “infinite” resolution
 - Limited by loop gain, thermal effects, and system noise
- Digital control provides a finite set of discrete “set points” resulting from the resolution of the “quantizing elements” in the system
 - Two elements in this represented example: ADC and DPWM



Digital Control

● Quantization Effects - ADC

- Resolution is defined as the number of states that can be uniquely represented
 - n bit resolution can assume 2^n states
- ADC resolution ensures that the set point tolerance can be met

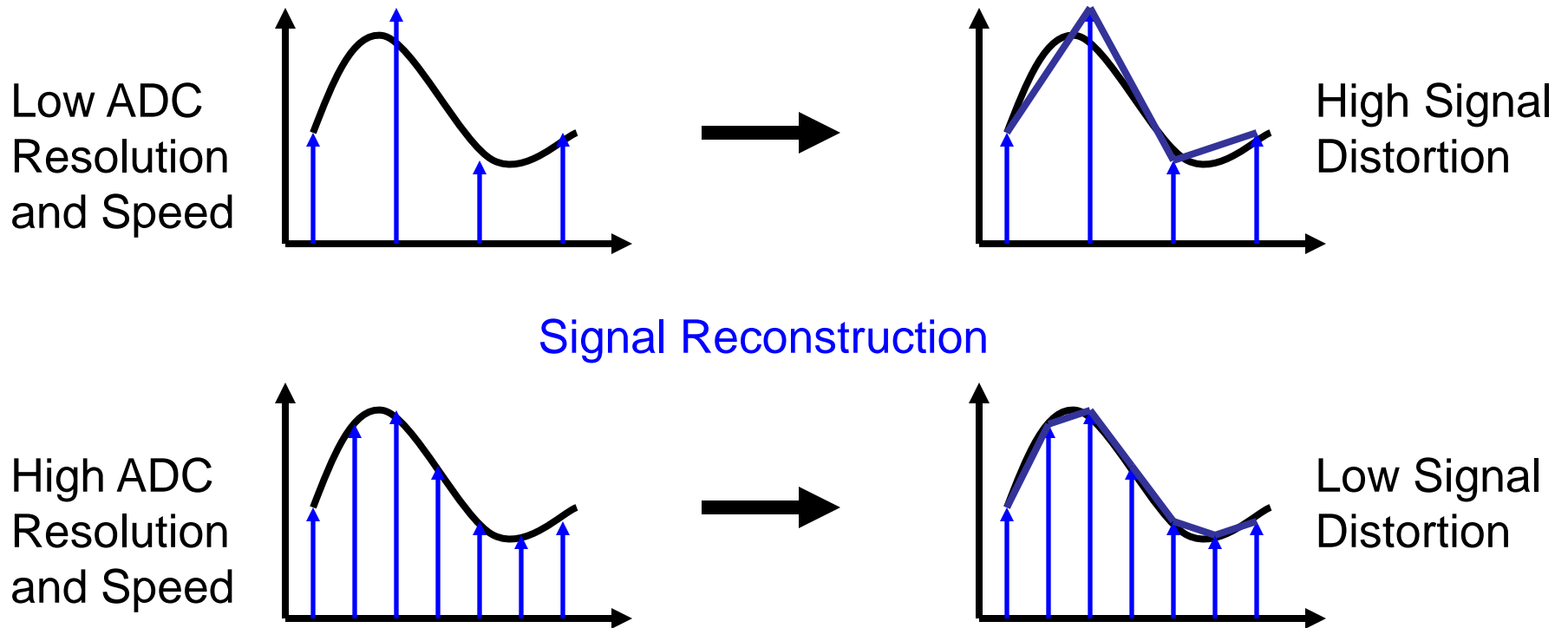
Example:

$$V_O = 3.3V \pm 1\%$$

$$\text{Required resolution} = \Delta V_O = 1\%$$

$$\begin{aligned} \text{ADC bits required} = n &= \text{int} [\log_2(V_O / \Delta V_O)] \\ &= \text{int} [\log_2(100)] = 7 \end{aligned}$$

● Quantization Effects - ADC



● Quantization Effects - DPWM

- Minimum required number of DPWM states equals 2^{n+1}
 - If less, the system will appear to hunt for a stable output value
- System clock sets the maximum number of bits that can be generated in a fixed time period

Example 1: ADC Resolution = 7 Required DPWM resolution = 8
Desired switching frequency = 1MHz
Required system clock = 1MHz * 2^8 = **256MHz !!**

Maximum switching speed = 30MHz / 2^7 = **234kHz**



Digital Control

- **“Control” Law Processor**
 - Typically a PI or PID (Proportional Integral Derivative) style
 - Controls dc level and dynamic response characteristics of the control loop
 - Represented as mathematical coefficients; manipulated to adjust system performance
 - Translates digital representation of output voltage into pulse duration (duty cycle) information used by the DPWM
 - Does not affect the resolution of the system



Digital Control

● Advantages

- “Tunable” system on-the-fly
- Independent of thermal drift, aging, and component tolerance limitations
- Precise control loop related parameters

● Disadvantages

- Quantization errors
- Limited system switching frequency



Has Digital Control Slowed the Adoption of Digital Power?

- **“Non-Digital Power Applications”**
 - Point of Load Converters
 - Limited in Power, Size, Cost and Efficiency are highly valued
 - DC/DC LED Drivers
 - Application Drives Feature Set
 - Dimming / Diagnostics / Binning / Temp Comp
 - DC/DC Battery Charging
 - Intelligence, Programmability, Wide Range of Power
 - **“Smart DC/DC Converters”**



Bridging the Gap

- **What's Wrong with Analog Solutions?**
 - No Flexibility
 - No Adaptability
 - No Communication
- **No Intelligence...**



Adding Intelligence to Analog

- **Unique Technology**
- **Design Tools / Programmers**
- **PIC Micro...Mid Range Core Versatility**
- **Add Analog Process**
 - Different than Digital Process
- **Add High Voltage Capability**
- **Add NDMOS for Efficiency**
- **Add Proprietary Integrated Features**



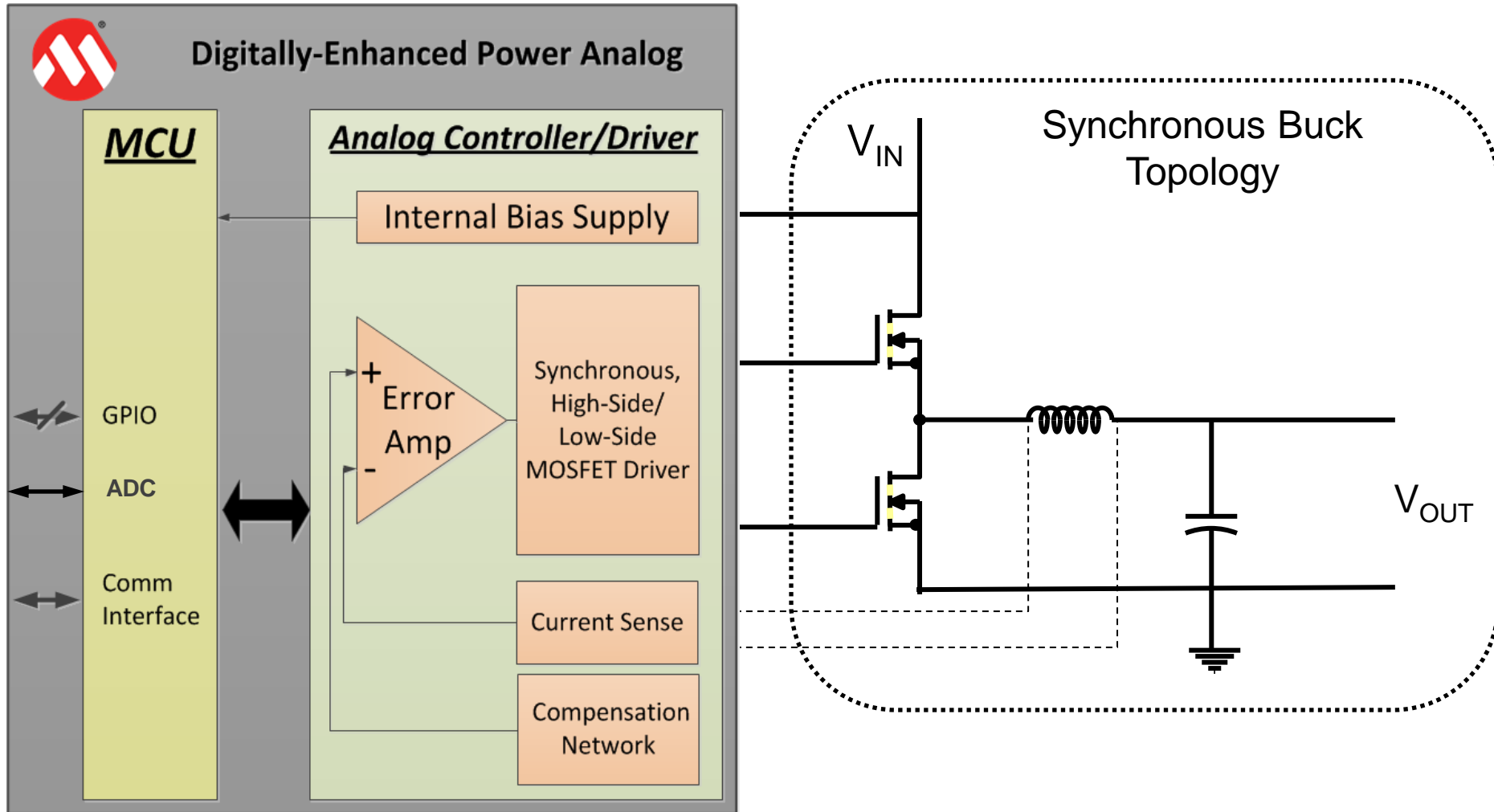
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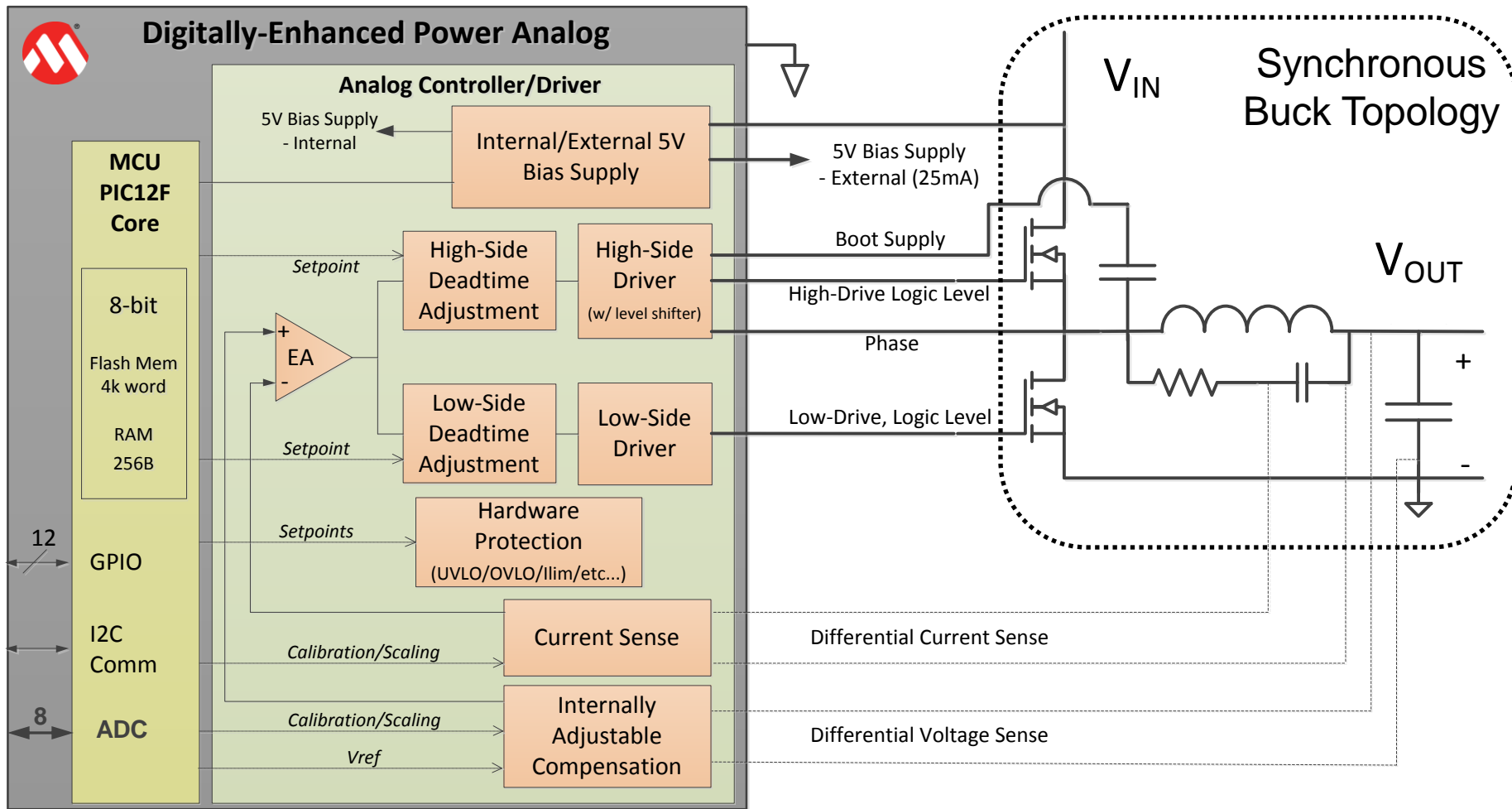
**Digitally Enhanced Power Analog
Controller with Integrated
Synchronous Driver**

Digitally Enhanced Power Controller

Basic Solution Architecture



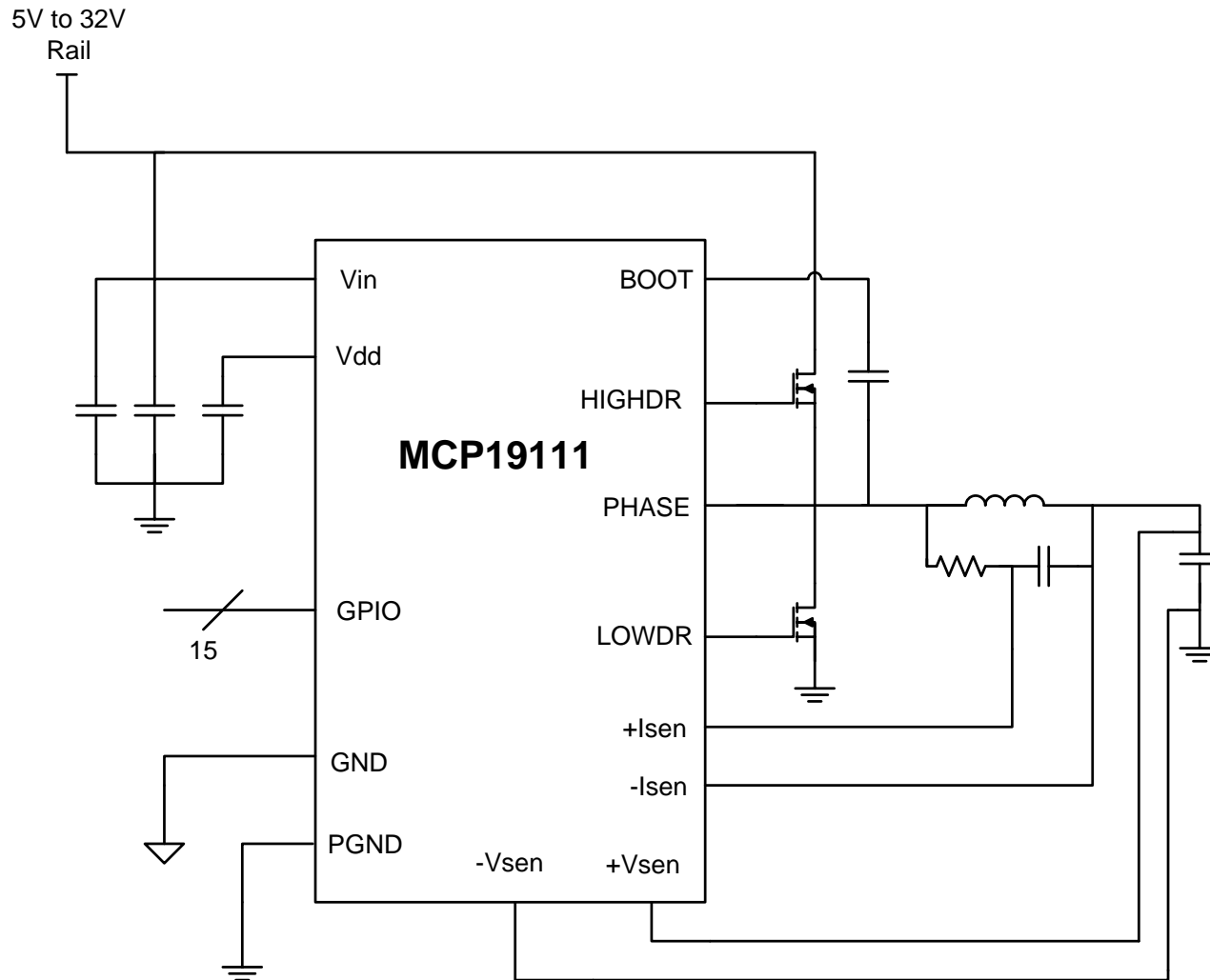
MCP19111 Synchronous Buck High/Low-Side Topology Support





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Simplified Schematic



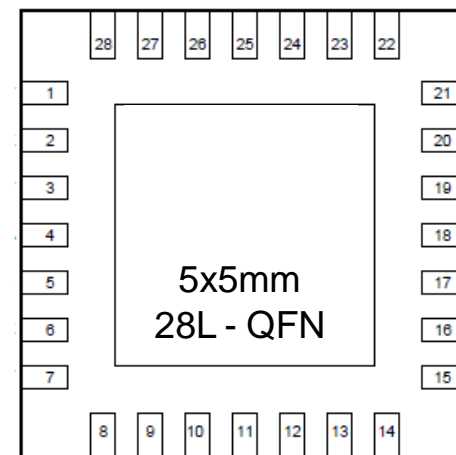
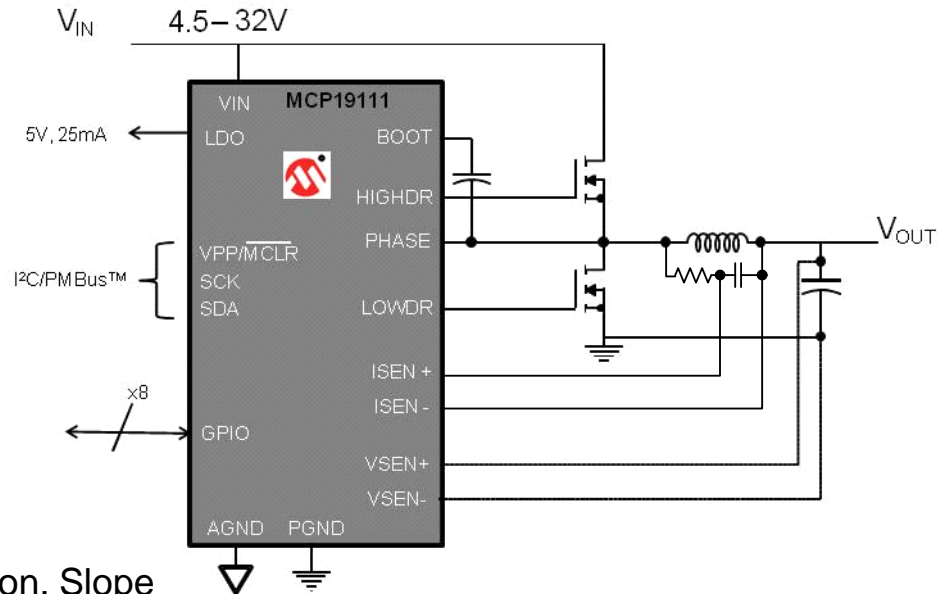


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Digitally Enhanced Power Analog Controller

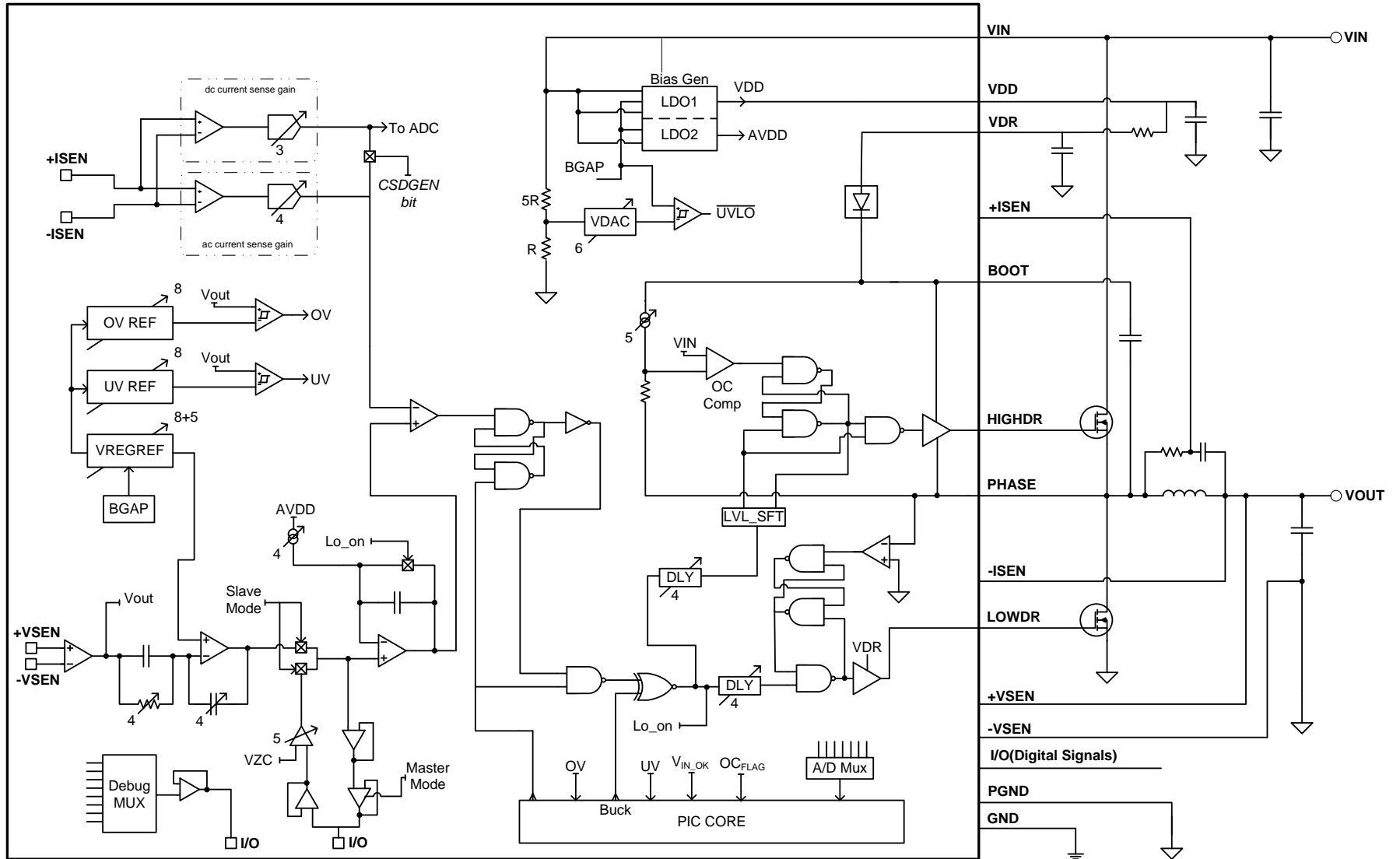
Single Phase Synchronous Buck

- V_{IN} Range: 4.5V to 32V
- V_{OUT} Range: 0.5V to 3.6V
 - Greater with output divider
- Coarse and Fine V_{REF} DAC
- Integrated MOSFET Driver:
 - Logic-Level Drive (5V)
 - 2A Source/4A Sink Drive Current
- Programmable Analog Controller:
 - Switching Freq: 100kHz to 1.6MHz
 - **Analog Control:** Control Loop Compensation, Slope Compensation, Peak Current Limit (Level & LEB Delay), **Gate Drive Deadtime**
 - **Thresholds:** V_{IN} UVLO, I_{OUT} CS Amp Gain, Soft-Start Rate, V_{OUT} Setpoint, V_{OUT} Trim, V_{OUT} OV/UV,
 - **Measure:** V_{IN} , V_{OUT} , Internal Temp + 8 Ext Ch
 - Master/Slave Mode → Multi-phase operation
- Programmable Digital Core:
 - Midrange Core (2 MIPS), 4kW Self-Write Flash, 256B RAM
 - (2) 16-bit Timers, (1) 8-bit Timer, (1) PWM, 12 GPIO
 - MSSP w/Enhanced PMBus Support



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Block Diagram





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Device Communication



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Communication

- **I²C™ Communication**
 - Open drain clock and data lines
- **SMBus Alert Pin**
 - GBP4 open drain pin
- **Two address registers**
 - Device specific address register
 - SMBus alert address register
 - When activated, device will respond to either address
- **Have a PMBus stack in the MPLAB X project**



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MCP19111 Calibration



Calibration Words

- **16 Calibration words at 2080h-208Fh**
 - Read only, they are not erased with program memory.
 - Contains calibration for amplifier offsets, band gap, temperature measurement, oscillator, output differential amplifier.
 - Calibration words 2080h to 2083h need to be moved to specific SFRs.
 - DOVCAL, OSCCAL, VROCAL, BGRCAL, TTACAL, ZROCAL



Calibration Word Read Example

REGISTER 4-3: CONFIG – CALIBRATION WORD 1 (ADDRESS: 2080h)

U-0	U-0	R/P-1	R/P-1	R/P-1	R/P-1	U-0	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1
—	—	DOV3	DOV2	DOV1	DOV0	—	FCAL6	FCAL5	FCAL4	FCAL3	FCAL2	FCAL1	FCAL0
bit 13													bit 0

V_{OUT} Differential Amp Offset

Oscillator Calibration

	197h
OSCCAL	198h
DOVCAL	199h
TTACAL	19Ah
BGRCAL	19Bh
VROCAL	19Ch
ZROCAL	19Dh
	19Eh



Calibration Word Read Example

```
banksel    PMADRH
movlw     0x20
movwf     PMADRH           ; MS Byte of Program Address to read
movlw     0x80
movwf     PMADRL           ; LS Byte of Program Address to read
bsf       PMCON1, CALSEL
bsf       PMCON1, RD       ; Program Memory read
nop       ; First instruction after memory read executes
nop       ; instruction here is ignored as memory is read
           ; in 2nd cycle after read
```

```
movf      PMDATH, W       ; W = MS Byte of Program Memory
banksel   DOVCAL
movwf     DOVCAL         ; Move W to DOVCAL
```

```
banksel   PMDATL
movf      PMDATL, W      ; W = LS Byte of Program Memory
banksel   OSCCAL
movwf     OSCCAL        ; Move W to OSCCAL
```



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Assisting System Development



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Bench Test Mode

- **Ability to look at internal signals**
 - 17 different circuit nodes
 - Multiplexer and buffer
 - BUFFCON register controls signals
 - Alternate GPIO pin function



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Virtual Probe Details

- bit 4-0 **ANSEL<4:0>**: MUX Control bits
- 00000* = Voltage proportional to current in the inductor
 - 00001* = Demanded current plus the added slope comp ramp
 - 00010* = Input to current loop, output of the demand mux
 - 00011* = Band gap reference
 - 00100* = Reference voltage for the VREG output
 - 00101* = Internal version of the VREG output
 - 00110* = RE_FRACT_PART
 - 00111* = Analog voltage proportional to internal temperature
 - 01000* = Internal ground of current measurement circuitry
 - 01001* = Reference for over voltage comparator
 - 01010* = Reference for under voltage comparator
 - 01011* = Output of the error amplifier
 - 01100* = Demanded current from remote master
 - 01101* = Demanded current modified by the slave gain amplifier
 - 01110* = 1/12 divided down VIN
 - 01111* = DC Inductor Current
 - 11101* = OC Reference



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Minimal Register Configuration



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Basic Set-up Code

; Configuring the switching frequency

```
banksel T2CON
clrf    T2CON
clrf    TMR2
clrf    PWMPHL      ; no phase shift
movlw  0x13
movwf  PWMRL      ; max allowed duty cycle ~ 75%
movlw  0x19
movwf  PR2        ; switching frequency ~ 300kHz
bsf    T2CON, 2    ; enable Timer2
```

; Configuring the device

```
banksel PE1
clrf    PE1
movlw  b'00001001'
movwf  ABECON      ; enable current measurement
                        & control loop

banksel VZCCON
movlw  0x80
movwf  VZCCON
```

>; Configuring analog SFRs


```
banksel VINLVL
movlw  0x9A
movwf  VINLVL      ; set UVLO to about 11V
movlw  0x88
movwf  DEADCON     ; set driver dead time
movlw  0x0D
movwf  CMPZCON     ; set compensation values
movlw  0x32
movwf  SLPCRCON    ; set slope compensation
movlw  0x05
movwf  CSGSCON     ; set current sense AC gain
banksel OVCCON
movlw  0x71        ; set Vout = 1.8V
movwf  OVCCON
movlw  0x80        ; enable Vout DAC
movwf  OVFCN
banksel ATSTCON
bcf    ATSTCON, 0  ; enable driver
```



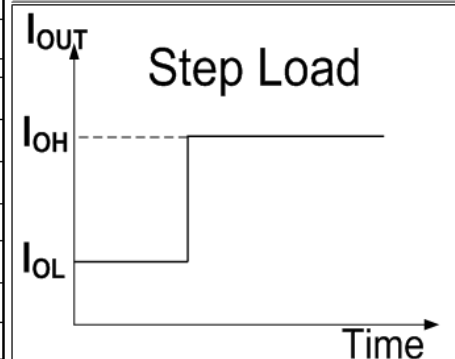
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MCP19111 Design Tools

MCP19111 Excel Design Tool

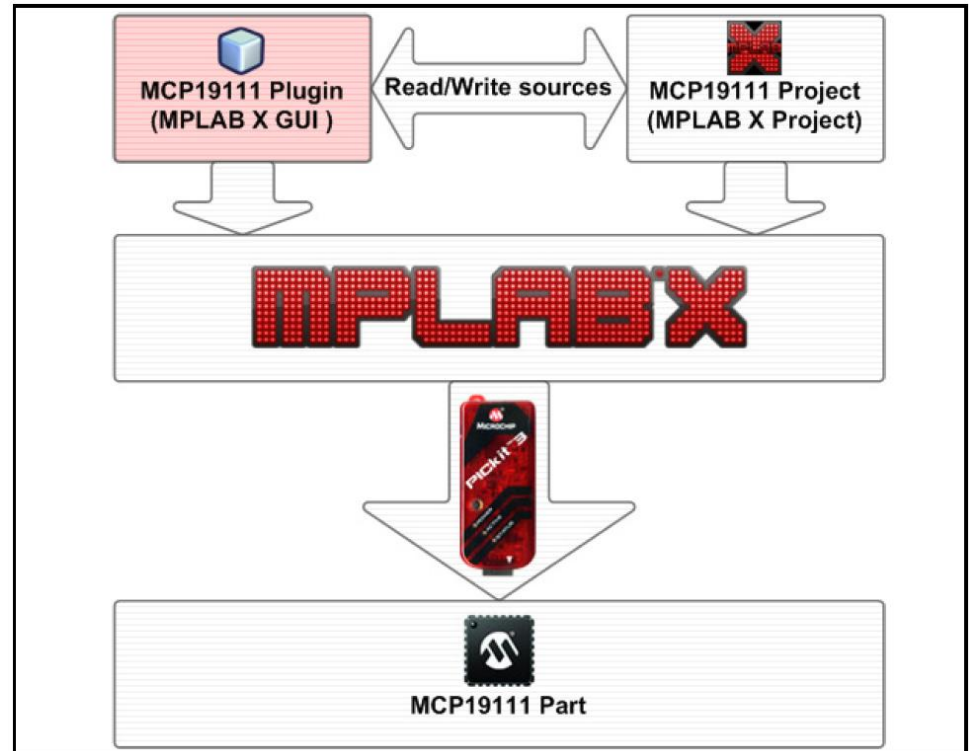
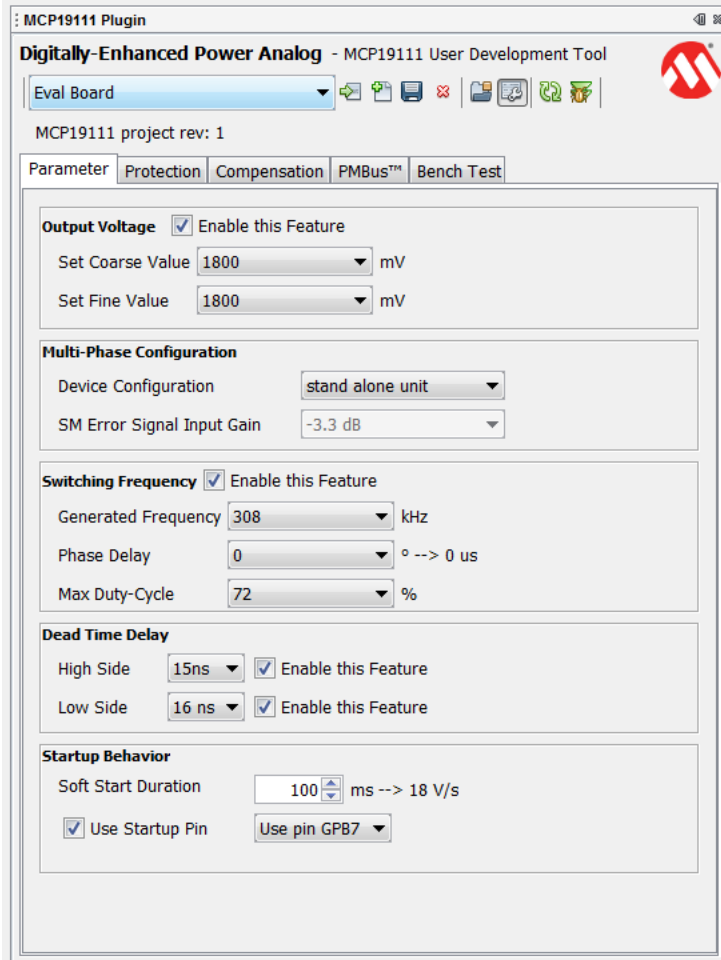
 MICROCHIP				
MCP19111 DESIGN ANALYZER				
Input Parameters for Design				
Parameter	Designator	Value	Units	Notes
Input Voltage	V_{IN}	12	V	$4.5 \leq V_{IN} \leq 30$
Output Voltage	V_{OUT}	1.8	V	$0.6 \leq V_{OUT} \leq 3.6$
Output Current	I_{OUT}	30	A	$0 \leq I_{OUT} \leq 30$
Switching Frequency	F_s	300	kHz	$100 \leq F_s \leq 1200$
Input Voltage Ripple	V_{RIN}	100	mV	
Minimum Input Voltage	V_{IN_MIN}	9	V	$4.5 \leq V_{IN_MIN} \leq V_{IN}$
Step Load Parameters				
High Output Current	I_{OH}	7.5	A	
Low Output Current	I_{OL}	2.5	A	
Output Voltage Overshoot		100	mV	

Use Default EVAL Board Components and Compensation



Use Recommended Components and Compensation

MCP19111 Programming GUI





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**Digitally Enhanced Power
Analog Applications**

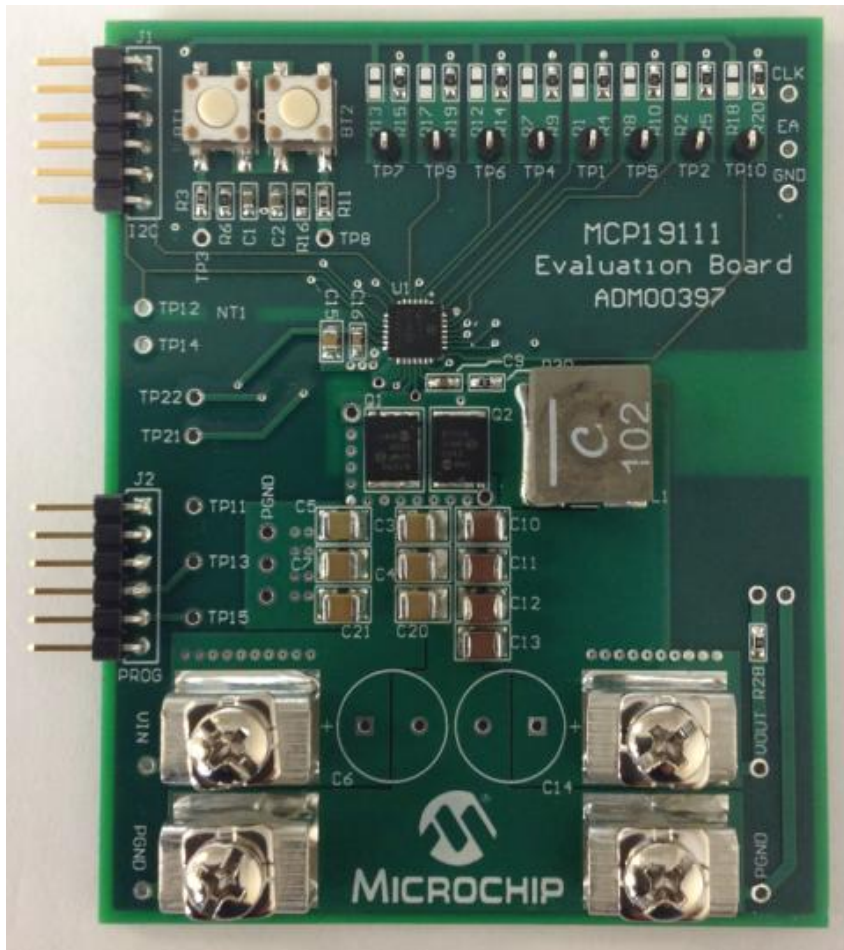


Point of Load or “POL”

- **5V to 24V Inputs**

- Low V_{OUT} , High I_{OUT} Applications
- Memory, Processors, FPGA, etc..
- Small Geometries (sub 1.8V Power)
- Current from 3A to 30A+

MCP19111 Eval Board and POL Converter Board



- $V_{IN} = 6V$ to $16V$
- $I_{OUT} = 30A$ with airflow
- $F_{SW} = 100kHz$ to $1.2MHz$
- **Programmable Features**
 - Switching Frequency
 - Output Voltage
 - Fine and Course
 - Dead Time
 - Output OV and UV
 - Over Current Protection
 - Compensation
 - Current Sense Gain



MCP19111 Eval Board and POL Converter Board

- **MCP87XXX Series MOSFETs**
 - MCP87050 HS MOSFET – 5.0m Ω $R_{DS(ON)}$
 - MCP87018 LS MOSFET – 1.8m Ω $R_{DS(ON)}$
- **Optimized PCB Layout**
 - Short, wide traces for all power paths
 - Vin, P_{gnd}, PHASE, Gate Drive, BOOT, etc.
 - Split ground plane
 - Input/Output ceramic capacitors



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Switching Frequency Control

- **Controlled by writing to PR2 register**
 - TMR2 counts up to reach PR2
 - Adjustable from 100kHz to 1.6MHz
 - Larger FETs may require external regulator on V_{DR} at very high switching frequencies.

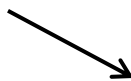
EQUATION 3-2: GATE DRIVE CURRENT

$$I_{DRIVE} = (Q_{gHIGH} + Q_{gLOW}) \times F_{SW}$$

Where:

- I_{DRIVE} is the current required to drive the external MOSFETs
- Q_{gHIGH} is the total gate charge of the high-side MOSFET
- Q_{gLOW} is the total gate charge of the low-side MOSFET
- F_{SW} is the switching frequency

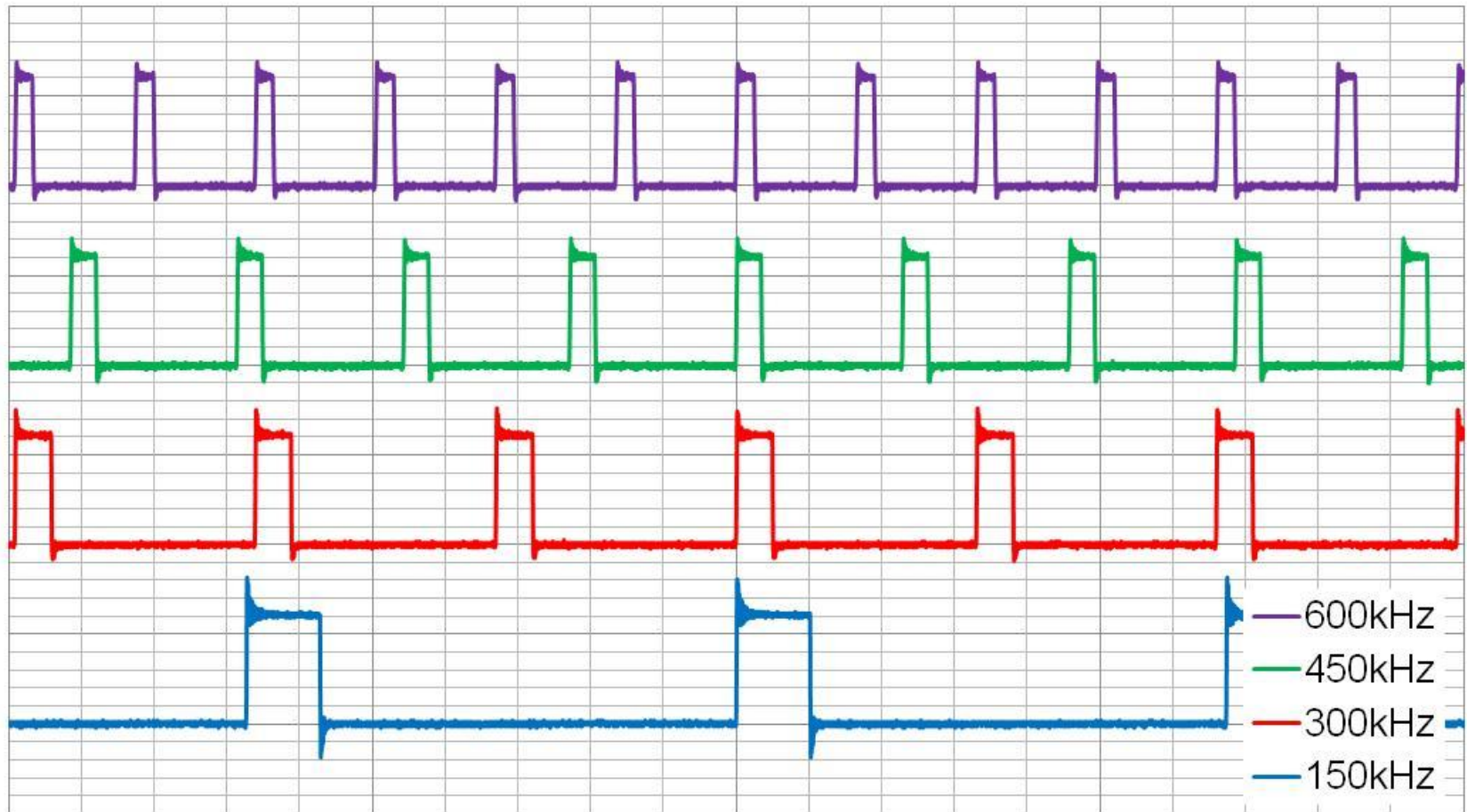
From the MCP19111 Datasheet





MCP19111 Waveforms

Switching Frequency Control



0.00E+00

5.00E-06

1.00E-05

1.50E-05

2.00E-05

Time (s)

600kHz

450kHz

300kHz

150kHz



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Over Current Protection

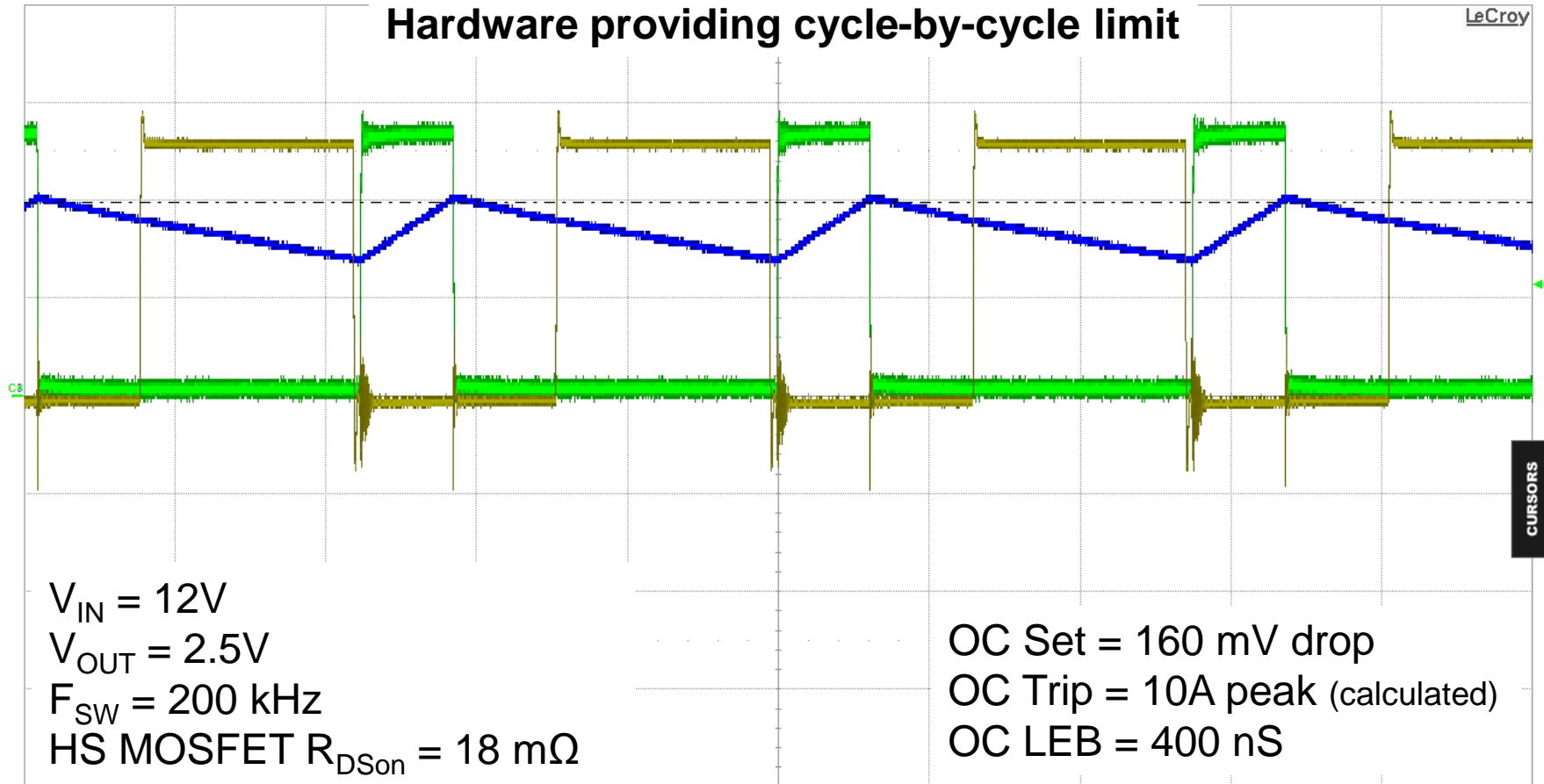
- **Voltage drop across high-side MOSFET sensed**
 - Cycle-by-cycle peak current limit
 - Controlled by writing to OCCON register
 - Adjustable range: 160mV to 625mV drop
 - Leading edge blanking of 114nS, 213nS, 400nS, 780nS
 - When OC occurs, OCIF Flag is set, hardware resets
- **Customized fault handling**
 - User's firmware dictates procedure
 - Ex. Restart 3 times, if fault still exists then shutdown



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Cycle by Cycle OC Protection

Hardware providing cycle-by-cycle limit



$V_{IN} = 12V$
 $V_{OUT} = 2.5V$
 $F_{SW} = 200\text{ kHz}$
HS MOSFET $R_{DSon} = 18\text{ m}\Omega$

OC Set = 160 mV drop
OC Trip = 10A peak (calculated)
OC LEB = 400 nS

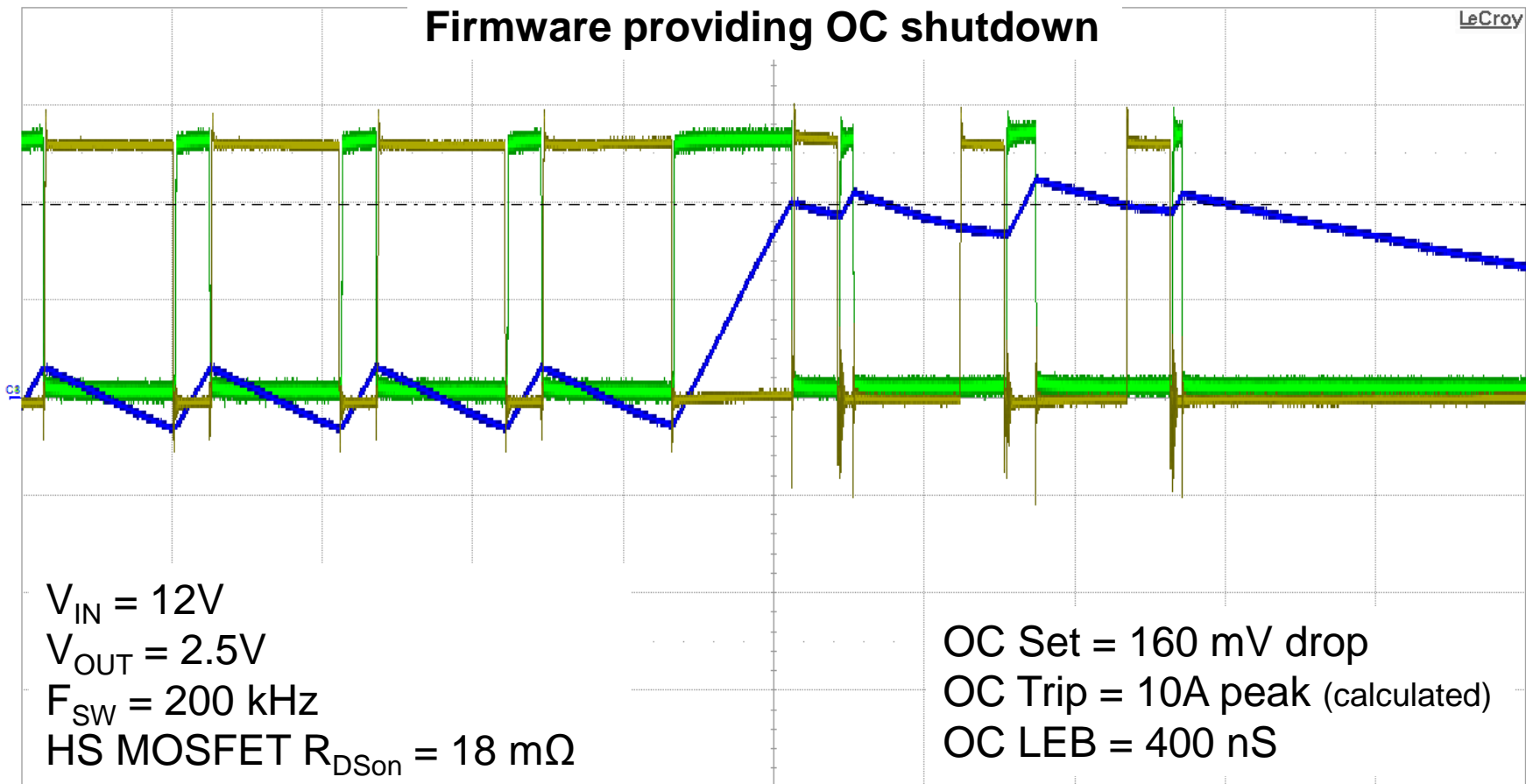
C1	DCIM	C3	BWL DC	C4	DSU DIF
2.00 V/div	5.00 A/div	2.00 V/div	0.00 A ofst	2.00 V/div	0 mV offset
0 mV offset					
3.96 V	9.90 A	3.96 V			

Tbase	0.00 μ S	Trigger	C4 DC
	2.00 μ S/div	Stop	2.28 V
400 kS	20 GS/s	Edge	Positive

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Output Short Circuit

Firmware providing OC shutdown



C1	DC1M	C3	BWL DC	C4	DSW DIF
2.00 V/div	5.00 A/div	2.00 V/div	0.00 A ofst	2.00 V/div	0 mV offset
0 mV offset					
3.96 V	9.90 A	3.96 V			

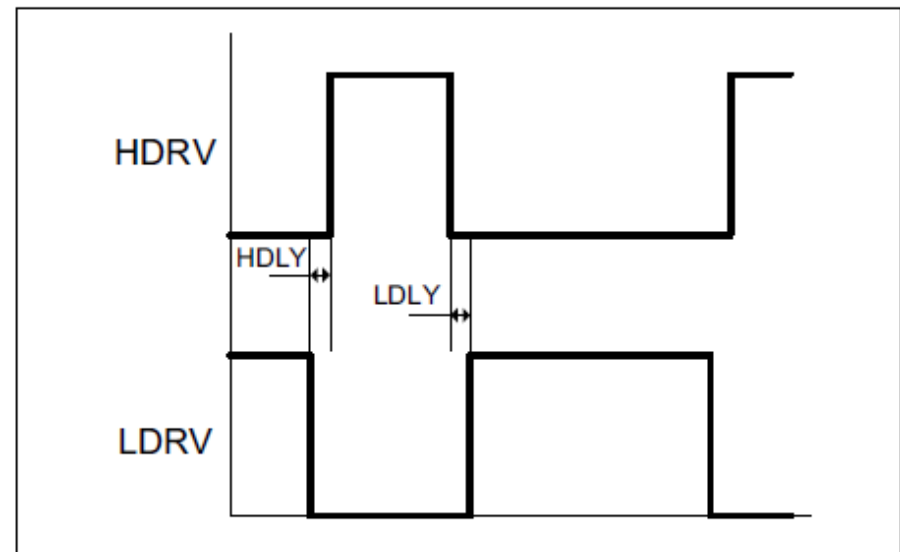
Timebase	0.0 μ S	Trigger	C3 DC
	5.00 μ S/div	Stop	7.65 A
1 MS	20 GS/s	Edge	Positive

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Dead Time Control

- **Controlled by writing to DEADCON register**
 - 4 bits for HDLY, adjustable from 11nS to 71nS
 - 4 bits for LDLY, adjustable from 4nS to 64nS
 - Very important to optimize efficiency, especially with High Speed (Low Parasitic Capacitance) MOSFETs

FIGURE 6-2: MOSFET DRIVER DEAD TIME

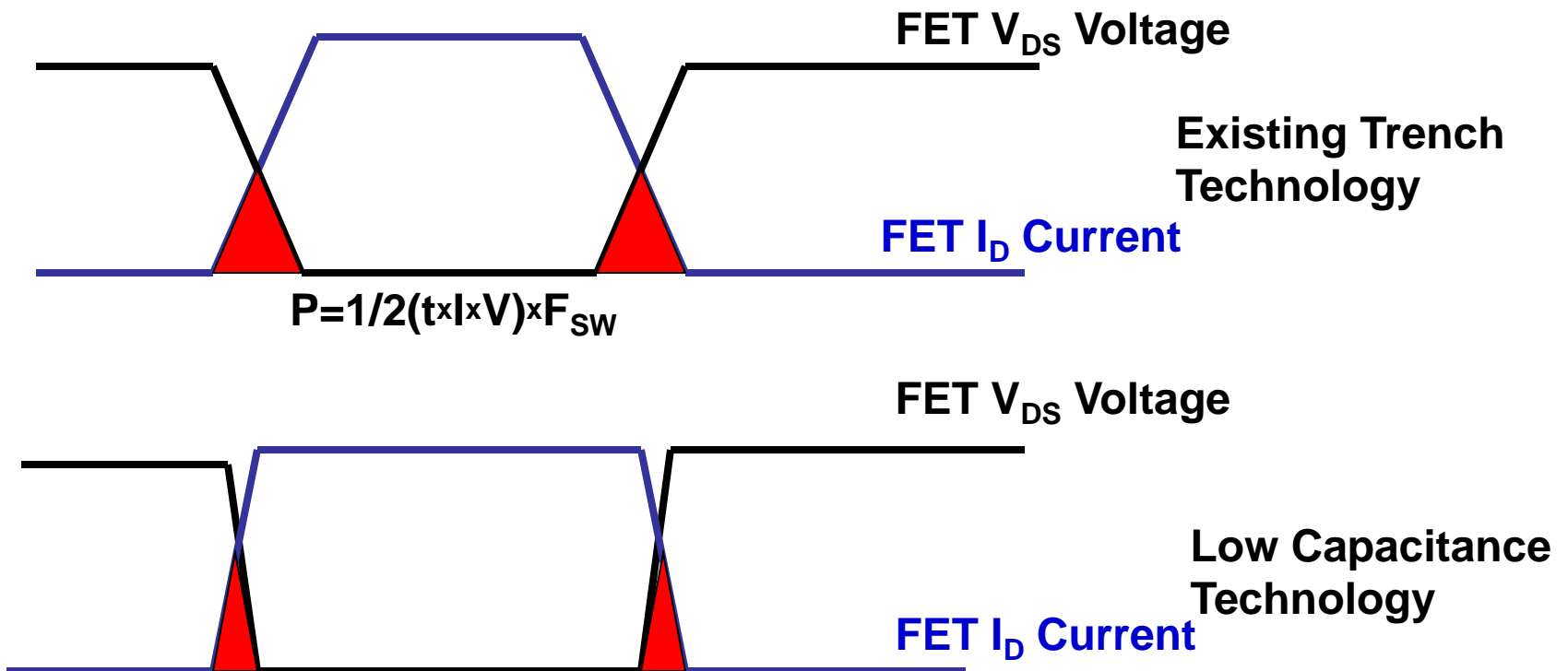


From the MCP19111 Datasheet



MOSFET Switching Loss

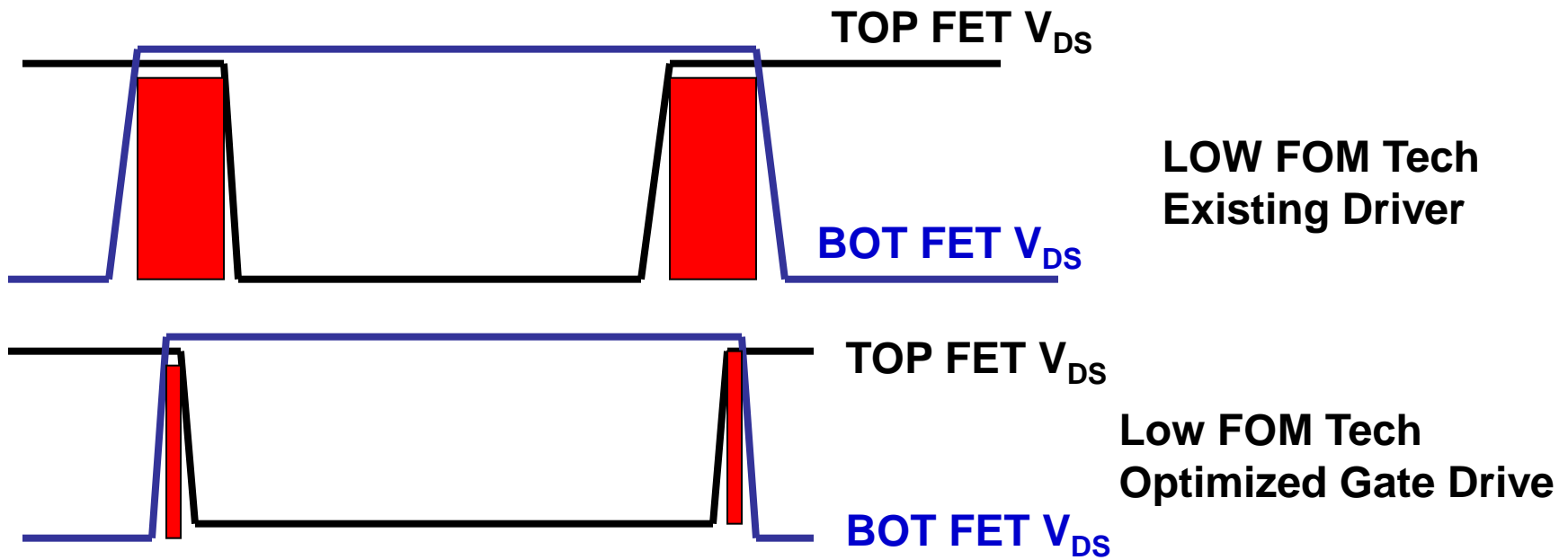
- MOSFET Low Capacitance Technology
 - Lower Switching Losses Increases Efficiency!



MOSFET Body Diode Loss

- **Optimized Dead Times**

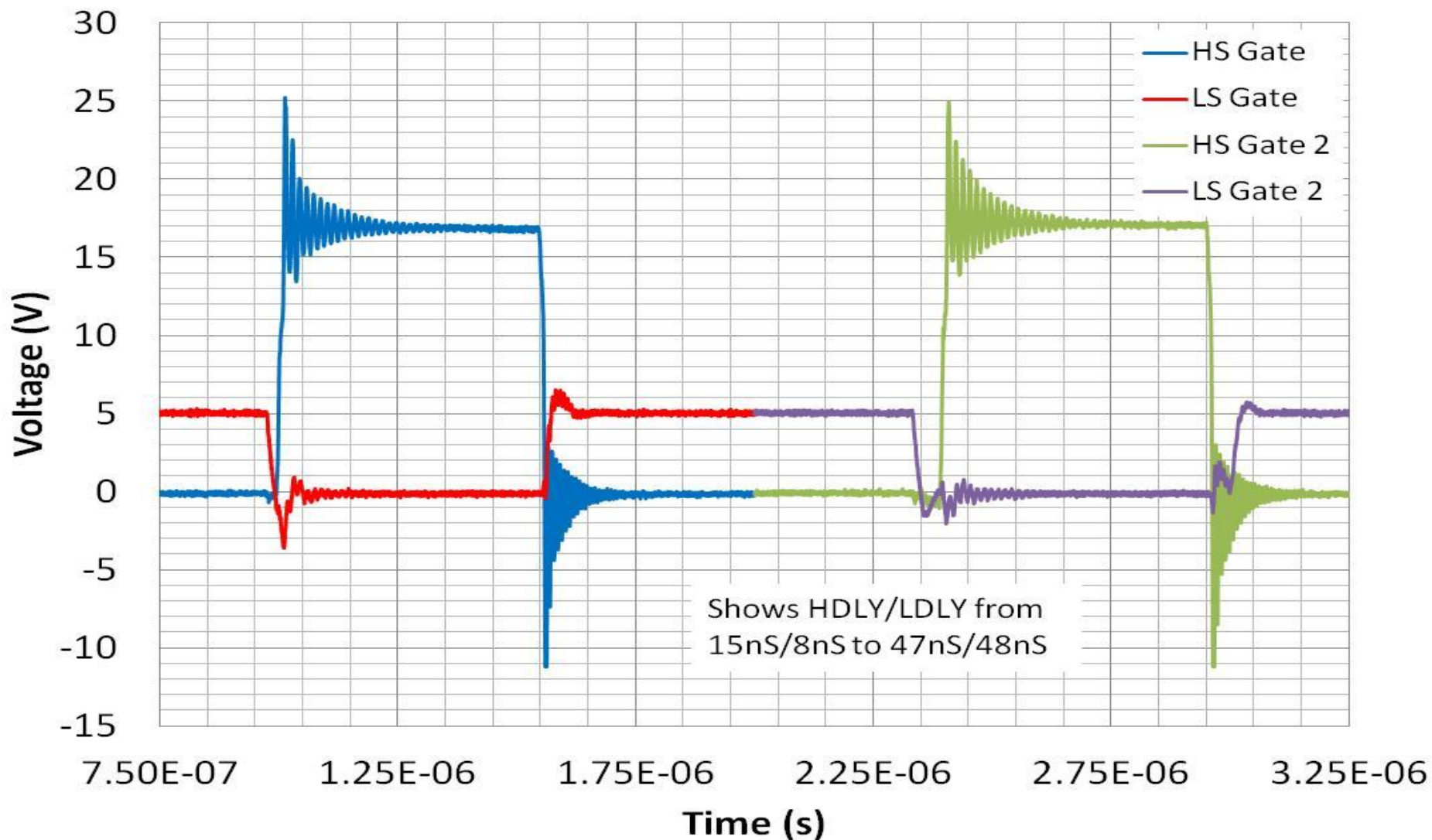
- **Keeping current out of the diode reduces reverse recovery losses and conduction losses**





MCP19111 Waveforms

Dead Time Control





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**Digitally Enhanced Power
Analog Applications
Continued**



MCP19111 Applications

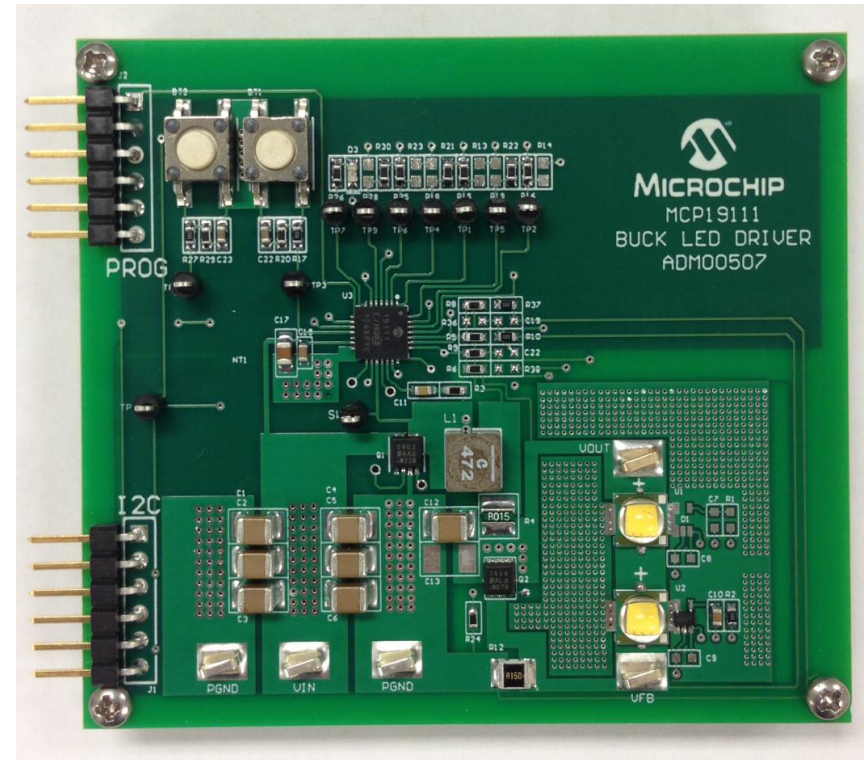
DC/DC LED Lighting

- **Buck Converter High Power LED Lighting**
- **Applications**
 - Automotive (Optics to Distribute Light)
 - Adaptive Lighting
 - Communicating with LED Lighting
 - Commercial LED Lighting

MCP19111 Applications

DC/DC LED Lighting

- Synchronous Buck Converter LED Evaluation Board
- $V_{IN} = 8V$ to $32V$
- Programmable current
- Provides current regulation using a sense resistor
- Two LEDs in series
- Hardware dimming and software dimming



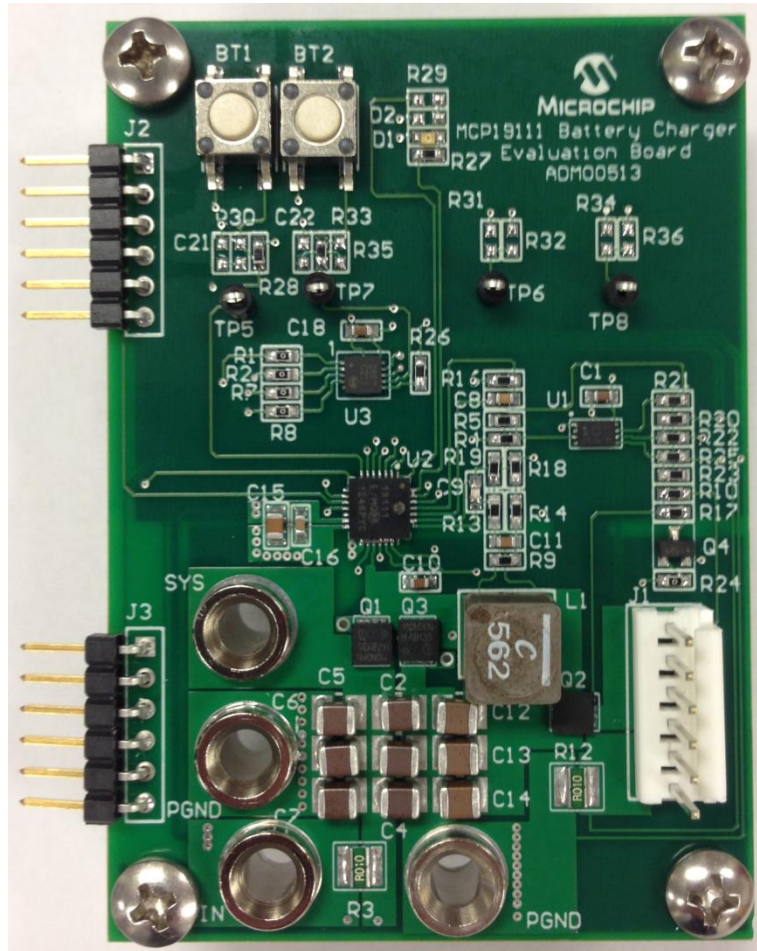


MCP19111 Applications

Charging Batteries

- **Multi-Chemistry (Programmable Current Source)**
- **Wide I_{OUT} Range**
 - Pre-Charge, Fast Charge, Termination
 - NiMH, Li-Ion, Pb-Acid Battery Profiles

Multi-Chemistry Battery Charger



- Sync Buck Multi-Chemistry Battery Charger Evaluation Board
- 1-4 Cell Li-Ion
- NiMH, NiCd, Pb Acid
- $V_{IN} = 4.5V$ to 32V
- Programmable Charging current up to 8A
- PIC core provides ability to design custom charging curves, protections, etc.



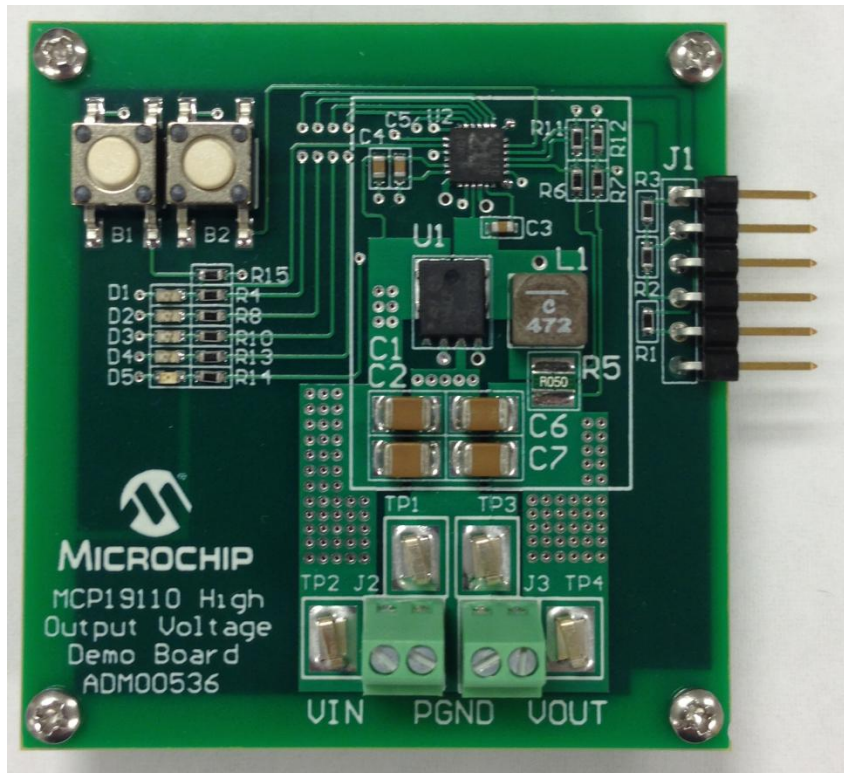
MCP19111 Applications

High Output Voltage

- Output of higher than 3.6V are possible with the MCP19111 by connecting the $+V_{SEN}$ pin to a voltage divider
- Care must be taken to ensure voltage rating compliance on all pins

MCP19111 Applications

High Output Voltage



- $V_{IN} = 6V$ to $32V$
- I_{OUT} up to $5A$
- Switchable between 4 voltage options using buttons
 - 3.5V, 5V, 10V, 12V
 - LED Indication
- Current sensing using resistor
- Utilizes MCP19110
 - Same as MCP19111 in 4x4QFN package, minus 4 pins and debug capability



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Output Voltage Control

- Controlled by writing to OVCCON and OVFCON registers

REGISTER 6-10: OVCCON: OUTPUT VOLTAGE SET POINT COARSE CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OVC7	OVC6	OVC5	OVC4	OVC3	OVC2	OVC1	OVC0
bit 7							bit 0

bit 7-0 **OVC<7:0>**: Output Voltage Set Point Coarse Configuration bits
 $OVC<7:0> = (V_{OUT}/15.8 \text{ mV}) + 15.8 \text{ mV}$

REGISTER 6-11: OVFCON: OUTPUT VOLTAGE SET POINT FINE CONTROL REGISTER

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
VOUTEN	—	—	OVF4	OVF3	OVF2	OVF1	OVF0
bit 7							bit 0

bit 7 **VOUTEN**: Output Voltage DAC Enable bit
 1 = Output Voltage DAC is enabled
 0 = Output Voltage DAC is disabled

bit 6-5 **Unimplemented**: Read as '0'

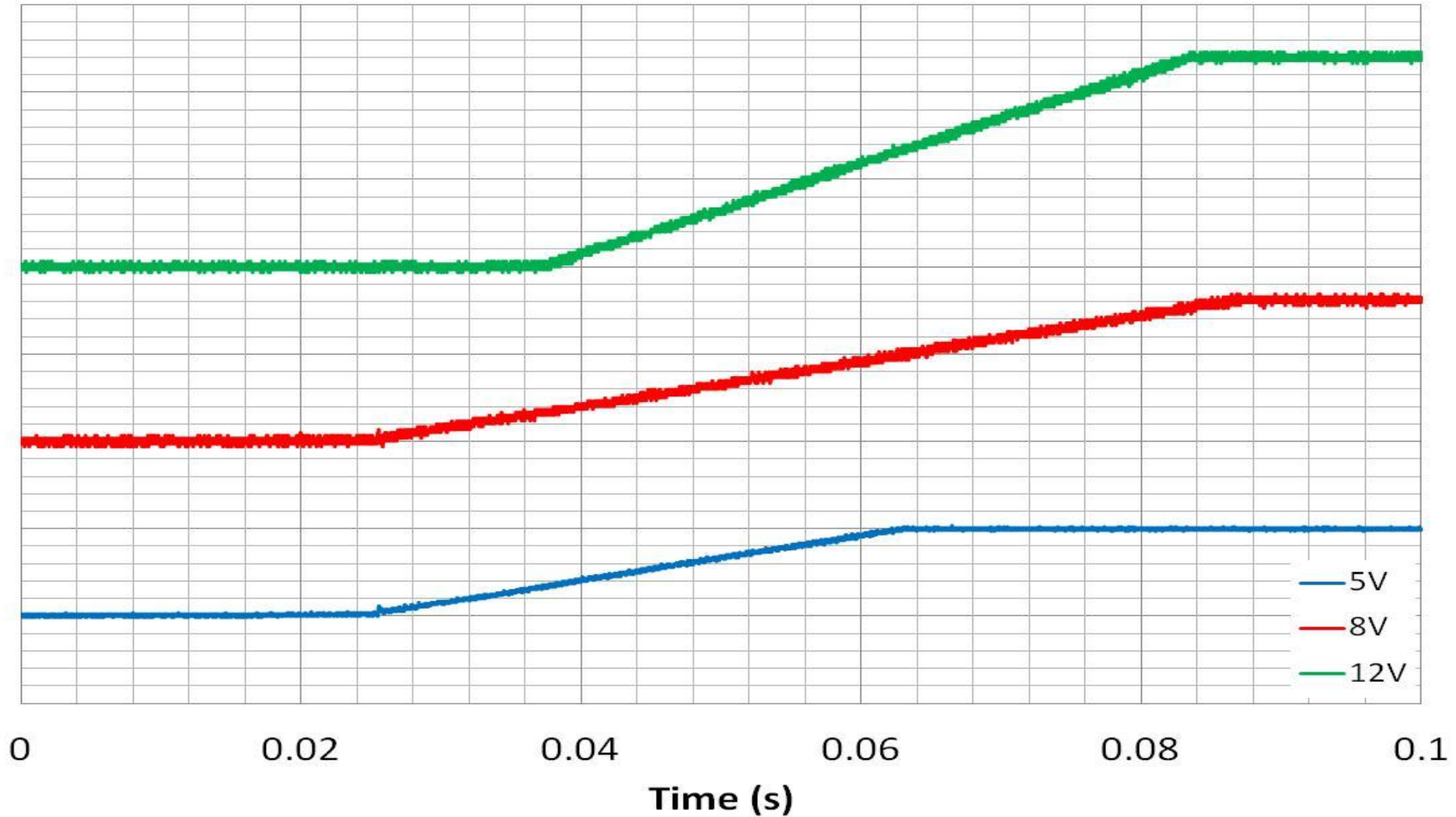
bit 4-0 **OVF<4:0>**: Output Voltage Set Point Coarse Configuration bits
 $OVF<4:0> = (V_{OUT} - V_{OUT_COARSE})/0.8 \text{ mV}$

Output Voltage can be programmed to < 0.1% accuracy



MCP19111 Waveforms

High Output Voltage





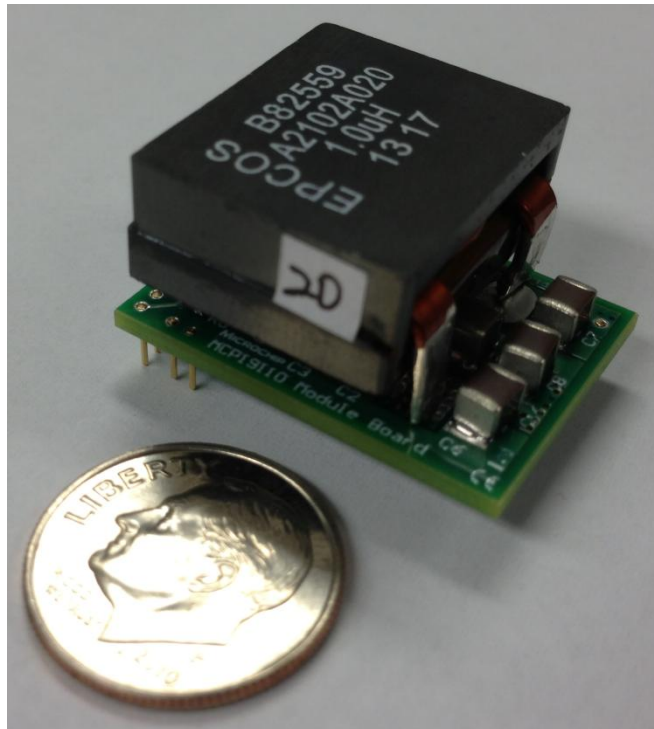
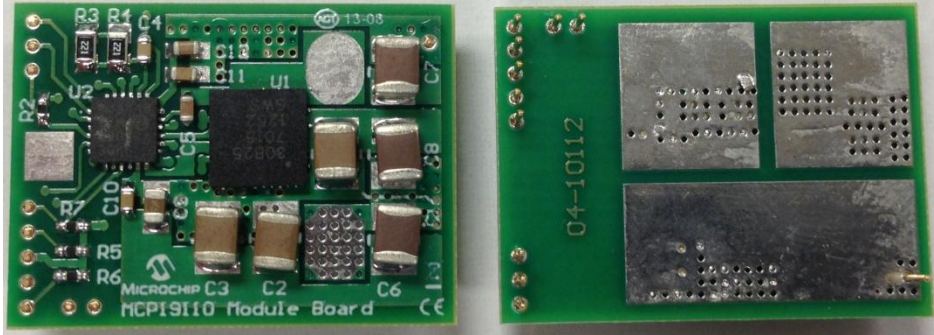
MCP19111 Applications

Power Supply Modules

- **Small footprint lends itself to very high power density applications**
 - MCP19111 – 5x5mm DFN, 28 Leads
 - MCP19110 – 4x4mm DFN, 24 Leads
- **Programmability allows module designer to use the same part number for many different modules**
- **GPIO for communication, P_{GOOD}, Enable, etc**

MCP19111 Applications

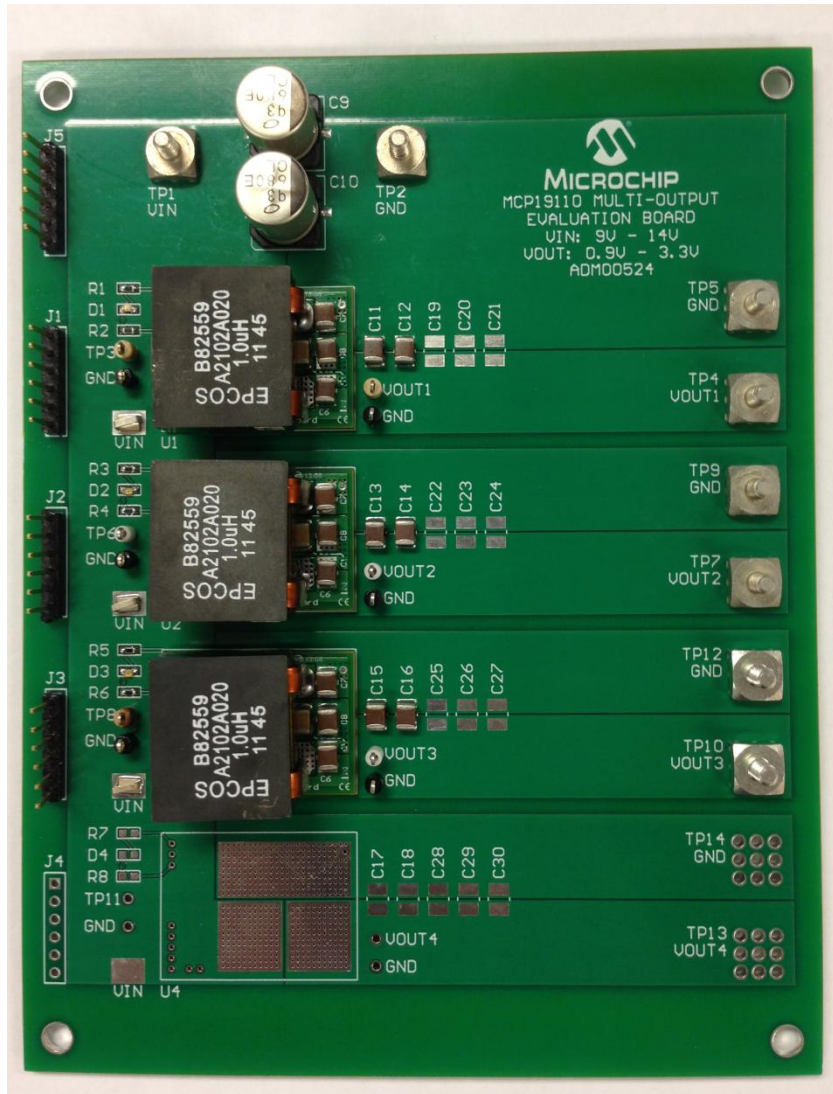
Power Supply Modules



- $V_{IN} = 6V$ to $16V$
- $V_{OUT} = 0.9$ to $3.3V$
- $I_{OUT} = 30A+$
- Utilizes the MCP19110, the GWS30B25 Dual MOSFET, EPCOS inductor
- Inductor “floats” over the PCB
- 66uF input ceramic cap, 300uF output ceramic cap
- 1” x 0.75” PCB
- **POWER DENSITY!**

MCP19111 Applications

Synchronized Multi-Output

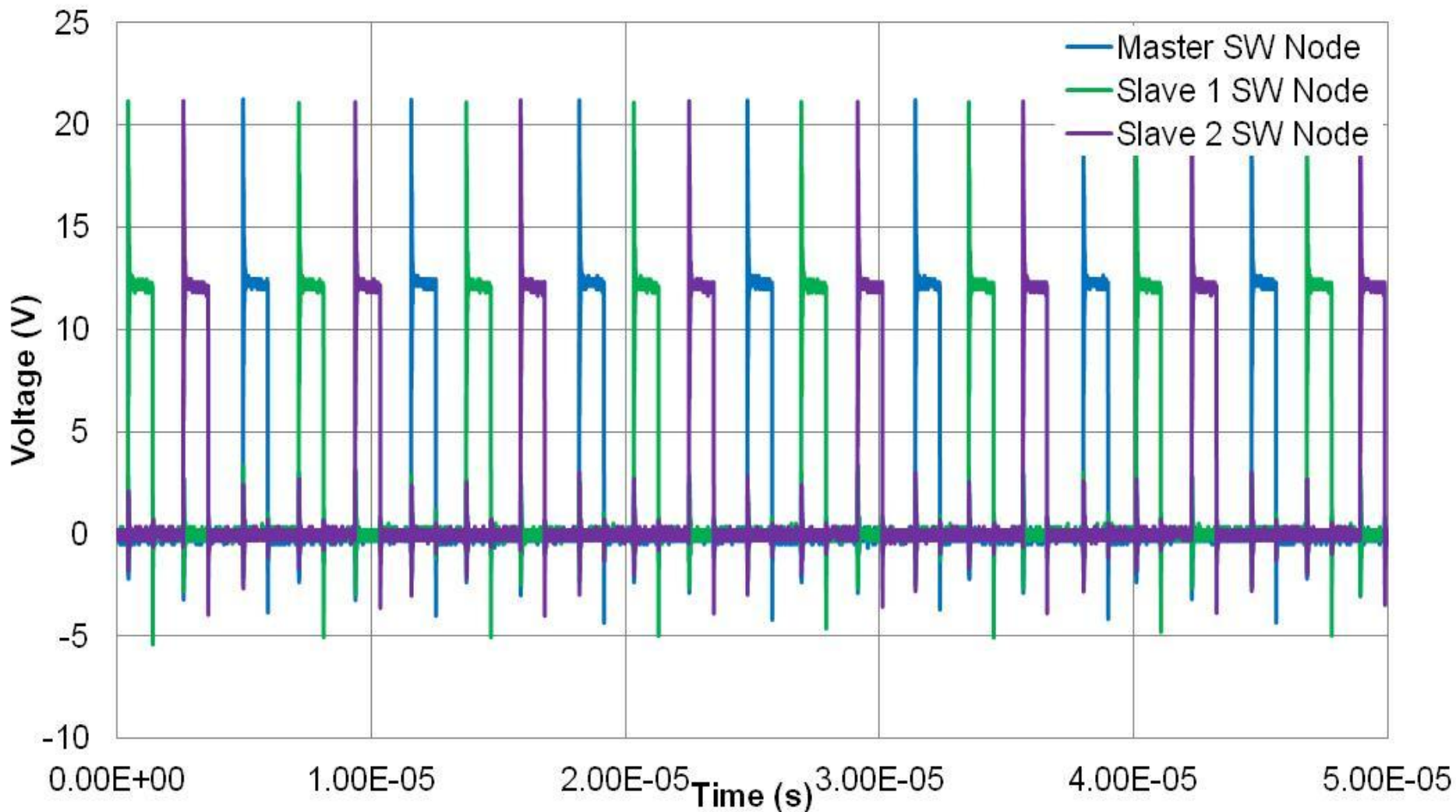


- $V_{IN} = 6V$ to $16V$
- $I_{OUT} = 30A+$ per output
- Utilizes 4x MCP19110 power supply modules
- Switching waveforms synchronized 90° out of phase
 - Simplifies input filtering
- PIC core allows easy control of start-up sequence



MCP19111 Waveforms

Synchronized Multi-Output





MCP19111 RECAP

- **Extremely versatile part**

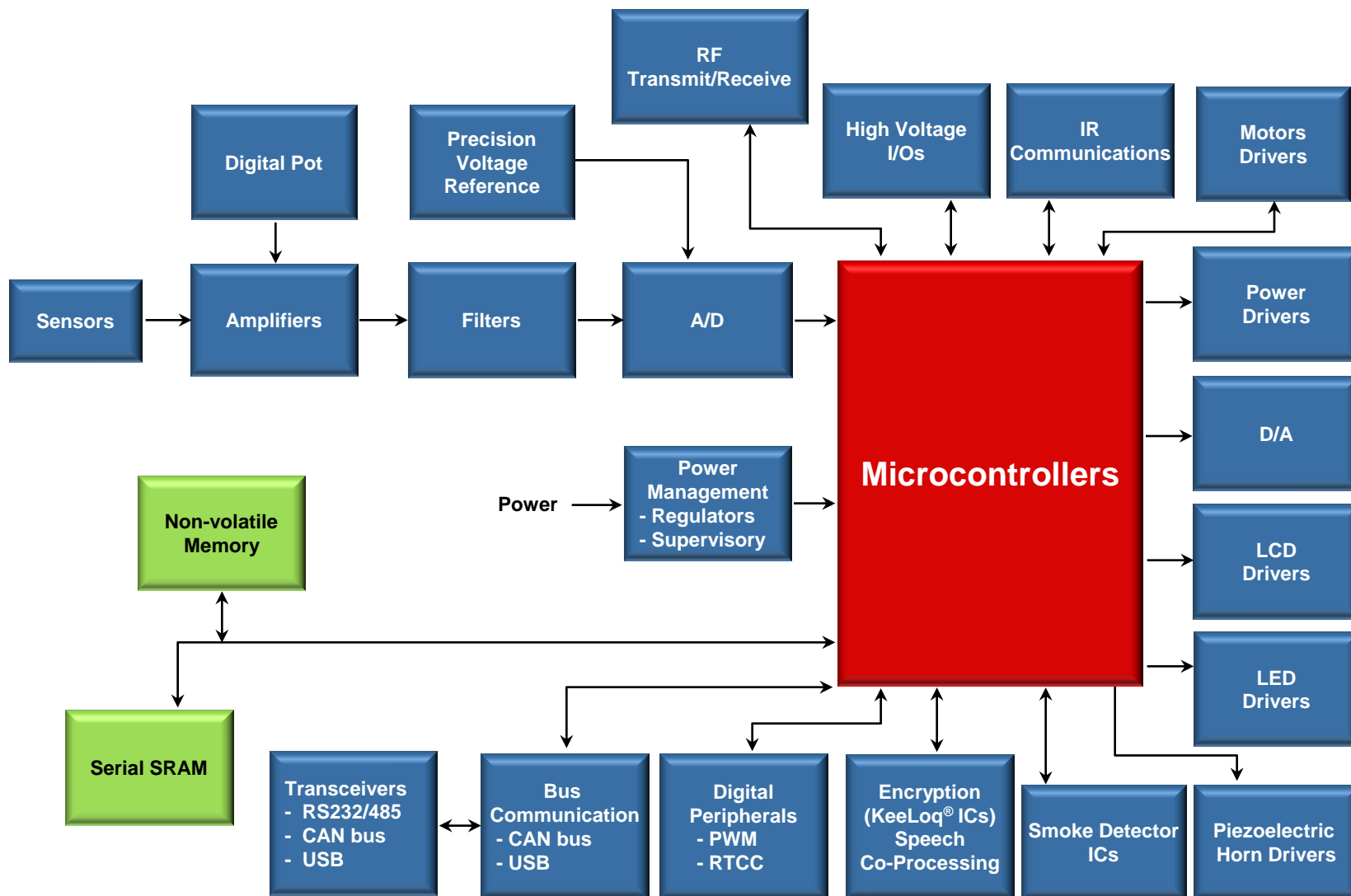
- POL, DC-DC LED Lighting, Battery Chargers, Modules, HV Output, Multi-rail, etc
- PIC core allows the flexibility, fault handling, and communication of a digital solution while offering the speed, resolution, and low quiescent current of an analog solution
- Flexibility = **higher efficiency!**
- Small footprint = **high power density!**

- **MCP87XXX MOSFETs**

- **FAST, ROBUST**



Our Analog & Memory Enables Providing Complete Solutions





Additional Resources

- **Product Landing Page**

- <http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en560308>

The screenshot shows the Microchip website interface. At the top left is the Microchip logo. To the right is a language dropdown menu set to "English". Further right are two search boxes: "Search Microchip" and "Search Data Sheets". Below these is a navigation menu with links for "PRODUCTS", "APPLICATIONS", "DESIGN SUPPORT", "TRAINING", "SAMPLE & BUY", and "ABOUT US", along with "Contact Us" and "myMicrochip Login". The main content area features the product name "MCP19111" with a status "In Production" and a tagline "The Low Power Analog Solution" with an image of a circuit board. Below the product name are five buttons: "Documentation & Software", "Pricing & Samples", "Development Tools", "Related Videos", and "Quick Links". A video thumbnail is visible with the title "MCP19111 Enhanced Power Analog Controller w/ Integrated Synchronous Driver (01/27/2013)". The main text describes the MCP19111 as a mid-voltage (4.5-32V) analog-based PWM controller family with an integrated 8-bit PIC(R) Microcontroller, highlighting its high-efficiency and fast transient response.