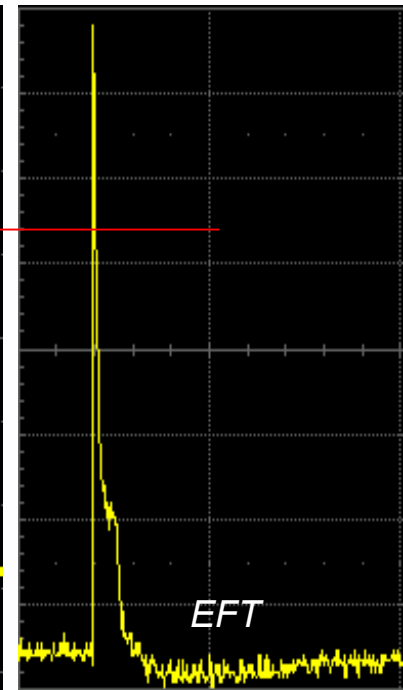
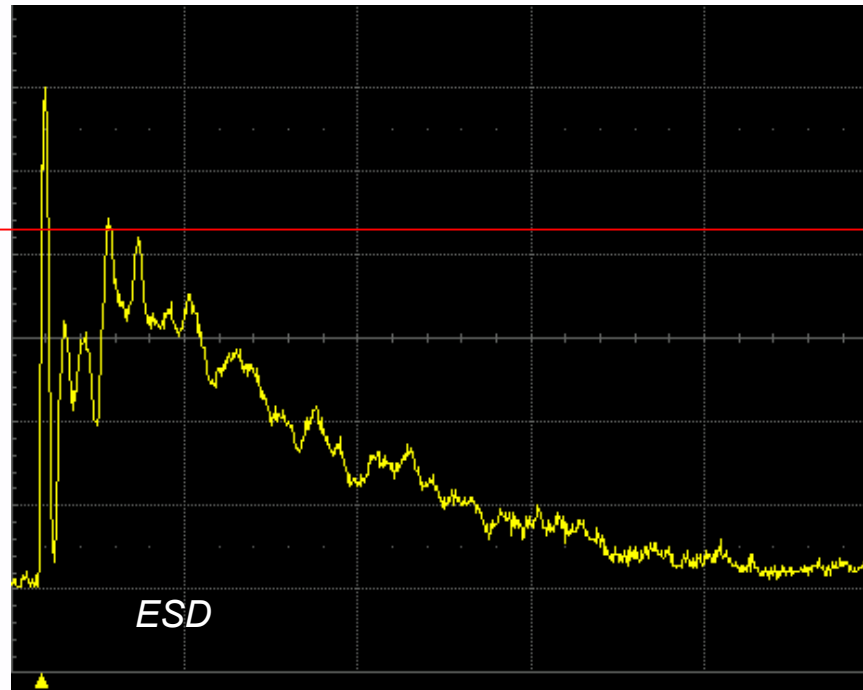
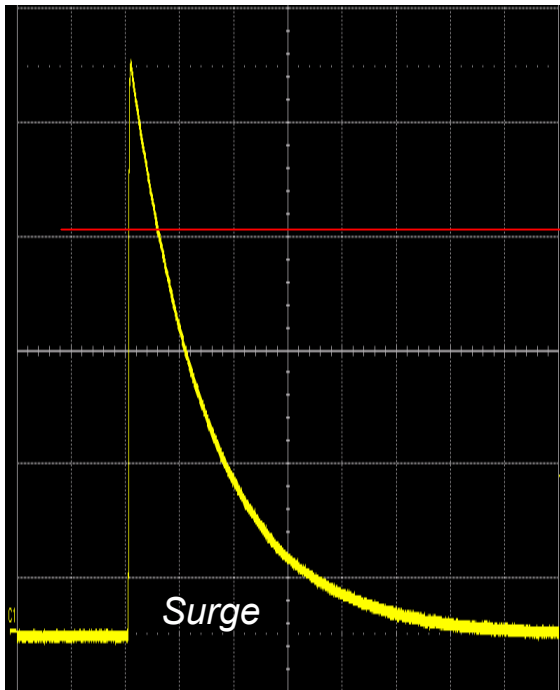


EMC Pulse Measurements

and Custom Thresholding

LeCroy

Presented to the Long Island/NY IEEE Electromagnetic Compatibility and Instrumentation & Measurement Societies - May 13, 2008



Contents

- EMC measurement requirements
- How thresholds affect pulse measurement definitions and why standard pulse parameters will not work for EMC pulses
- Measurement thresholds for ESD pulses
- Sequenced acquisition for EFT (Electrical Fast Transient) pulses
- Parameter limiters applied to filter EMC pulse statistics
- Custom measurements

EMC

**Measurement
Requirements**

4 Quadrants of EMC/ESD Testing

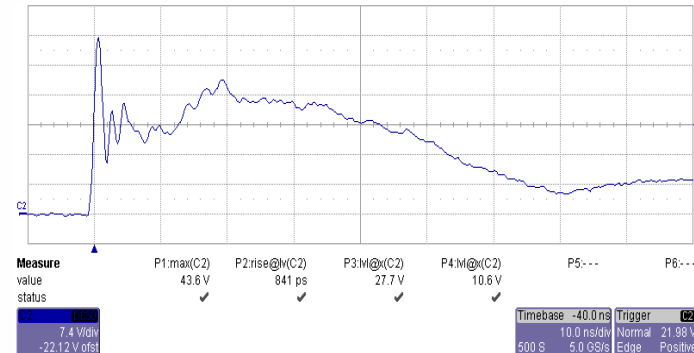
Radiated Emissions Will the EUT create emissions that interfere with the operation of other products?	Conducted Emissions How much noise voltage is injected back into the mains by the EUT?
Radiated Immunity Will the EUT be susceptible to emissions from other devices, either through the air or via cables?	Conducted Immunity Will the EUT be susceptible to transients generated by switching of capacitive or inductive components?

EUT = Equipment Under Test

- Oscilloscopes used for
 - Radiated Immunity
 - Conducted Immunity
- "Pulsed EMI tests:
 - ESD (Electrostatic Discharge)
 - EFT (Electrical Fast Transient)
 - Surge

Test Requirements

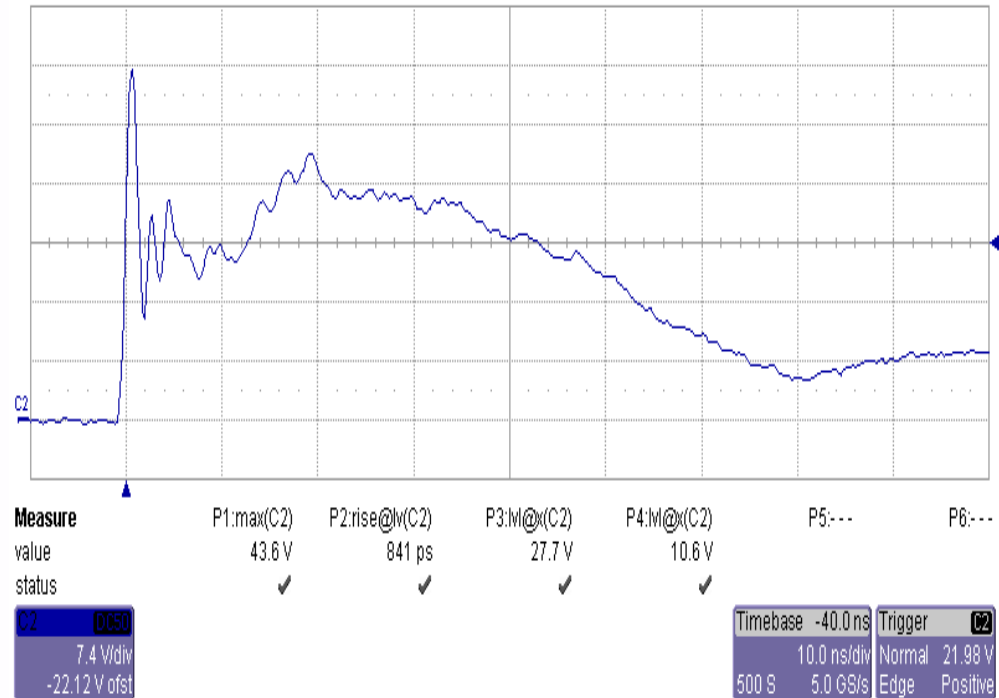
- Generate a Burst, Surge, or ESD pulse (for example, with an ESD gun)
- Verify the pulse shape(s) from the generator with an oscilloscope before each test
 - Rise Time
 - Fall Time
 - Width
- Ensure that the DUT still operates correctly during test, for example:
 - Automotive engine control unit still transmits proper messages
 - Telecom board serial data messages are uncorrupted
 - Consumer electronics item still functions
- ESD Standards:
 - IEC 61000-4, EN 61000-4, ITU, UL, FCC, Telcordia, ANSI, Bellcore, Proprietary (Military, Automotive), etc.
 - The majority of Immunity Testing follows the IEC 61000 (CE Mark)



ESD Testing – Electrostatic Discharge

Measurement Steps

- Pulse Characteristics
 - $T_{\text{rise}} = 0.7 \text{ to } 1.0 \text{ ns}$
 - $T_{\text{fall}} = 0.7 \text{ to } 1.0 \text{ ns}$
- Measurement Needs
 - Capture a Single Pulse
 - Measure one pulse, verify rise time for positive pulses, verify fall time for negative pulses
 - 1 GHz, 2 GHz, or 3 GHz+ scope depending on standard specification

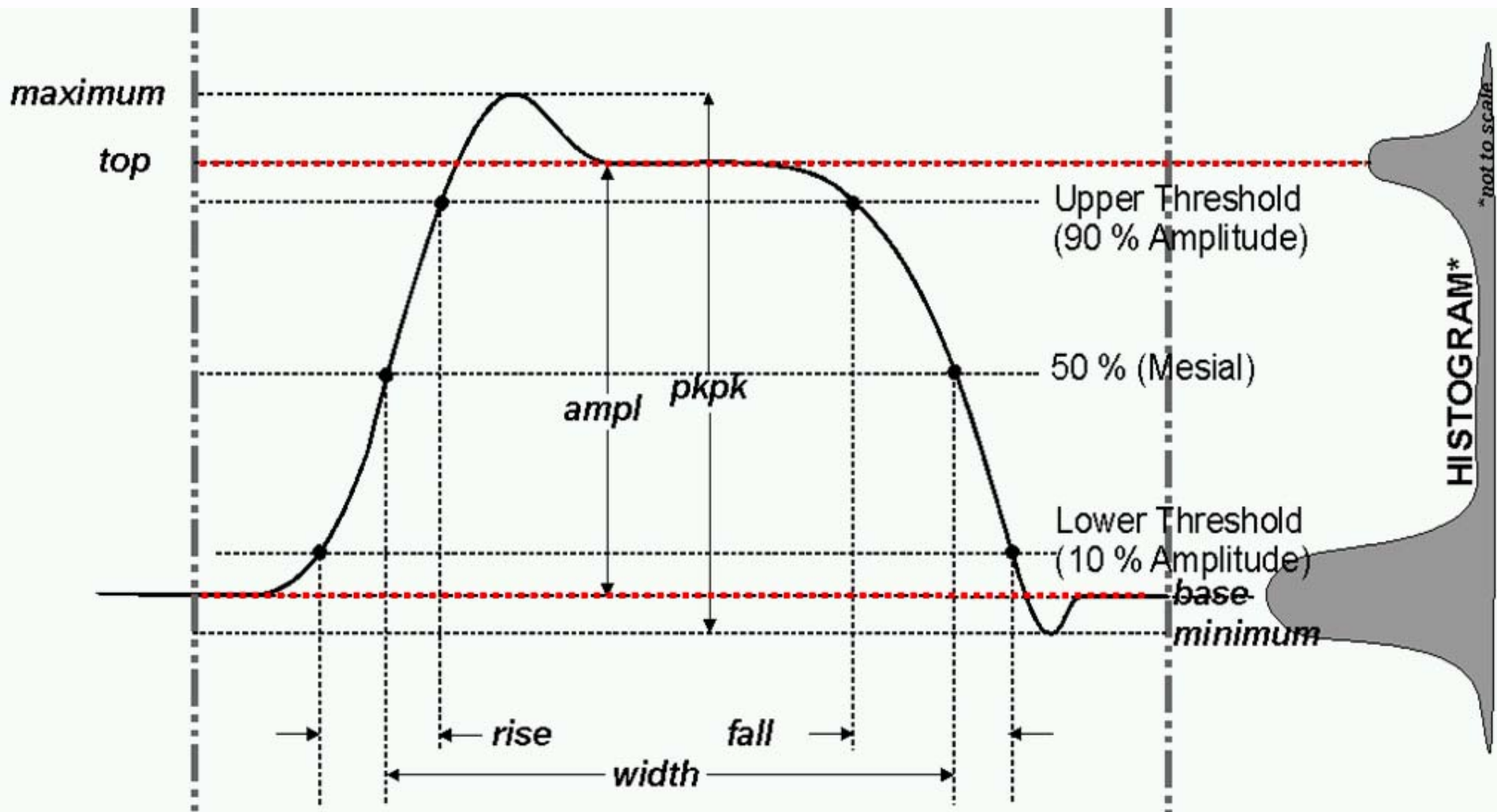


How is risetime defined on this ESD pulse?
10%-90% risetime is only meaningful if 0% and 100% levels exist and have been defined on the pulse.

Pulse Measurement Definitions

IEEE Standard Pulse Definitions

How Oscilloscopes Measure Pulse Parameters

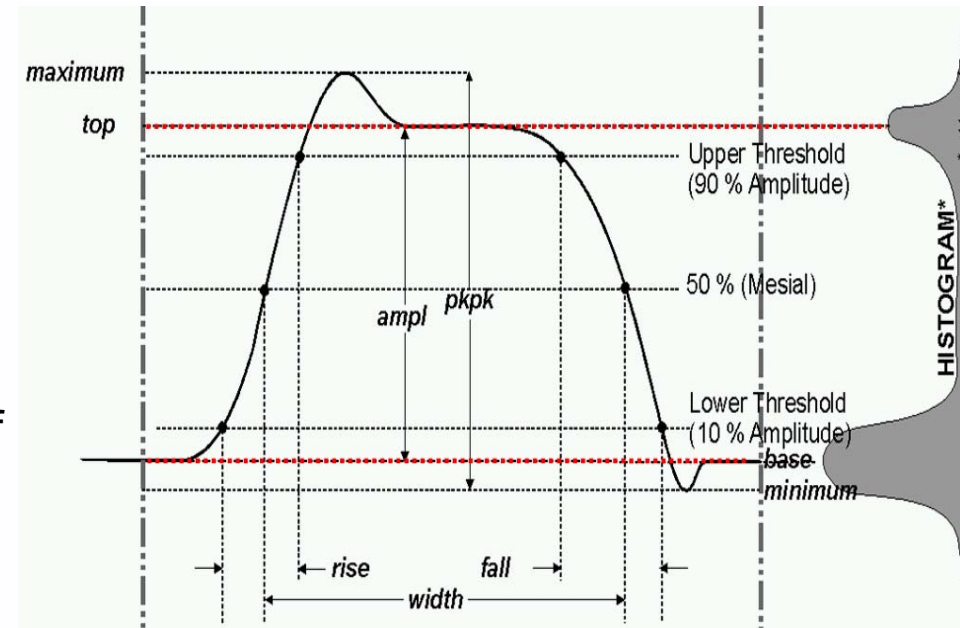


Oscilloscopes determine pulse parameters from Top and Base values

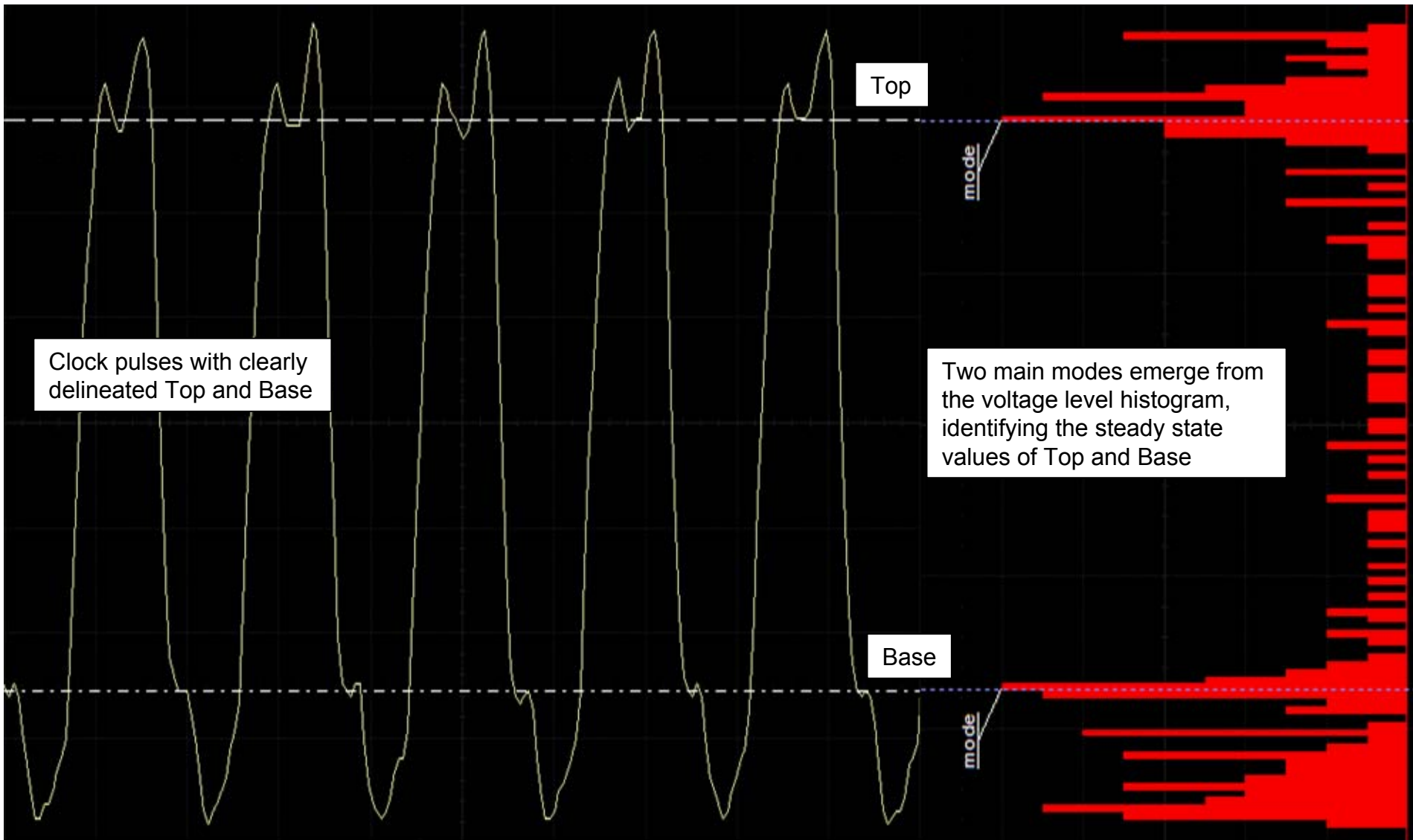
IEEE Pulse Definitions

How Pulse Measurements Are Determined

- Pulse measurement definitions are defined by the IEEE Std 181-2003 "IEEE standard on transitions, pulses, and related waveforms"
- Oscilloscopes conform to the IEEE pulse measurement definitions, and Top and Base are determined statistically based on the two modes of a voltage level histogram.
- Top and Base form the 100% and 0% reference levels which are used for measurements such as amplitude, risetime, falltime, period, frequency, width, duty cycle, overshoot, and virtually every timing measurement.
- Top and Base must first be calculated correctly in order for timing and amplitude measurements to produce the correct measurement result.



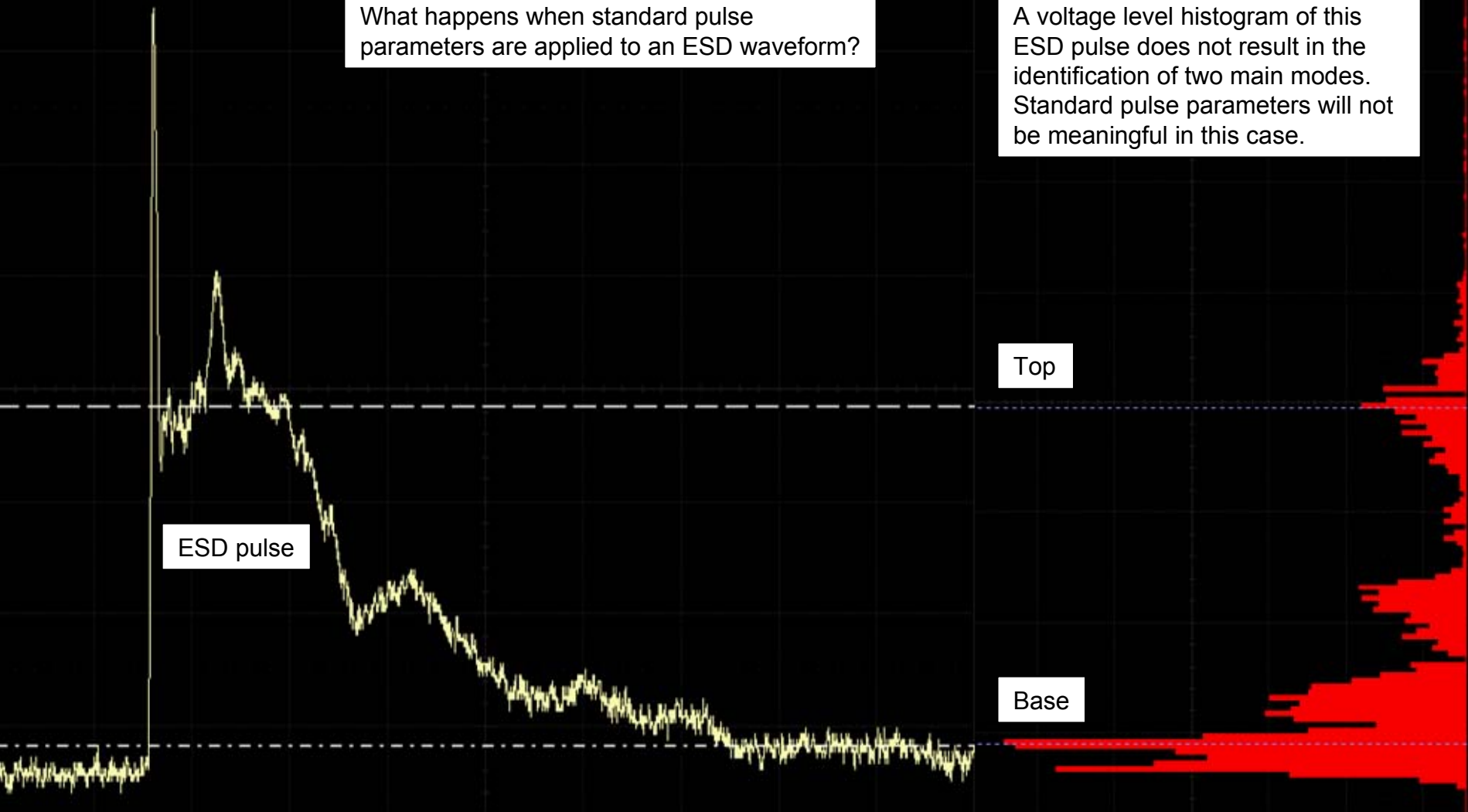
Clock Top and Base correctly determined from voltage histogram



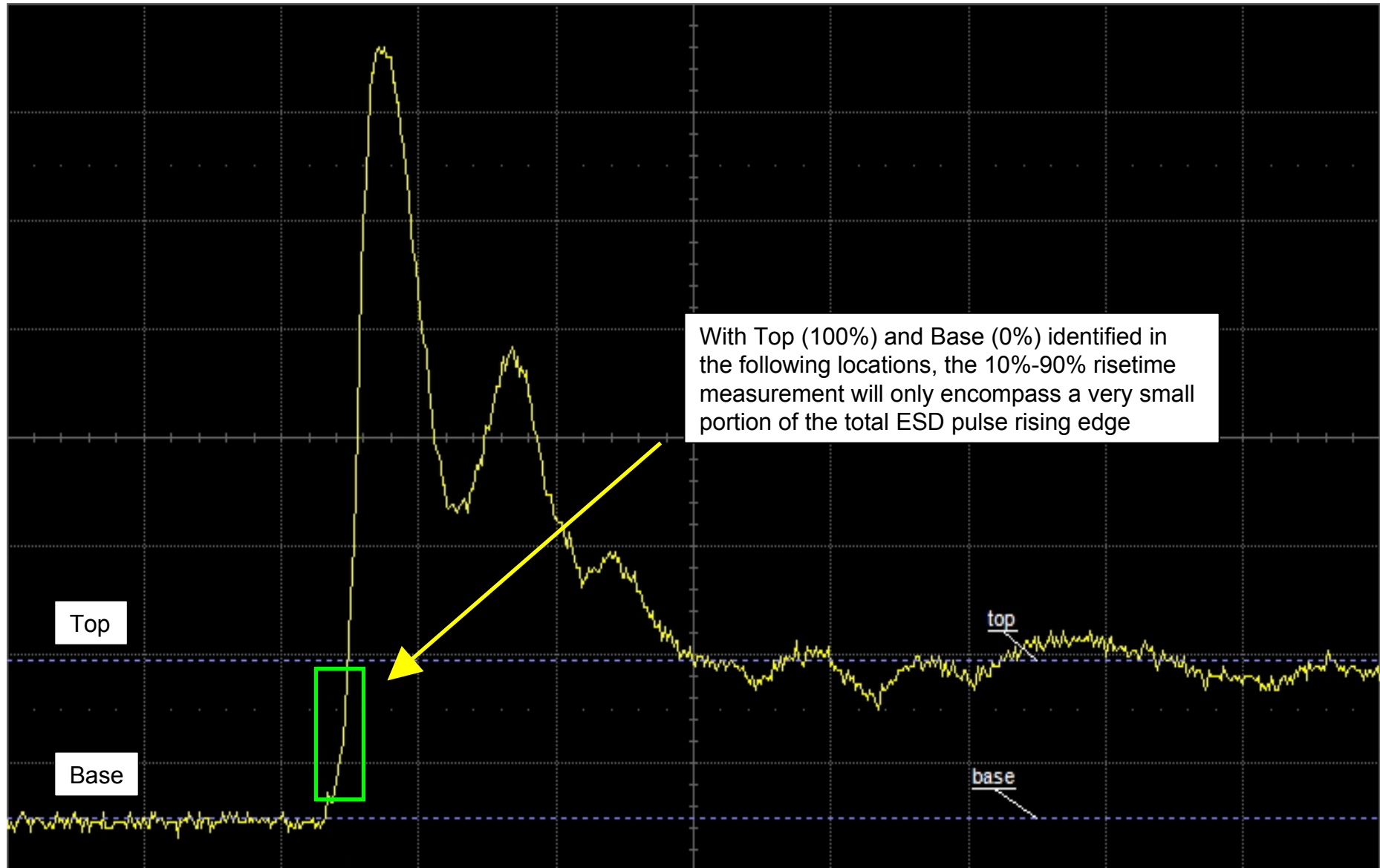
ESD Top and Base are not meaningful for pulse measurements

What happens when standard pulse parameters are applied to an ESD waveform?

A voltage level histogram of this ESD pulse does not result in the identification of two main modes. Standard pulse parameters will not be meaningful in this case.



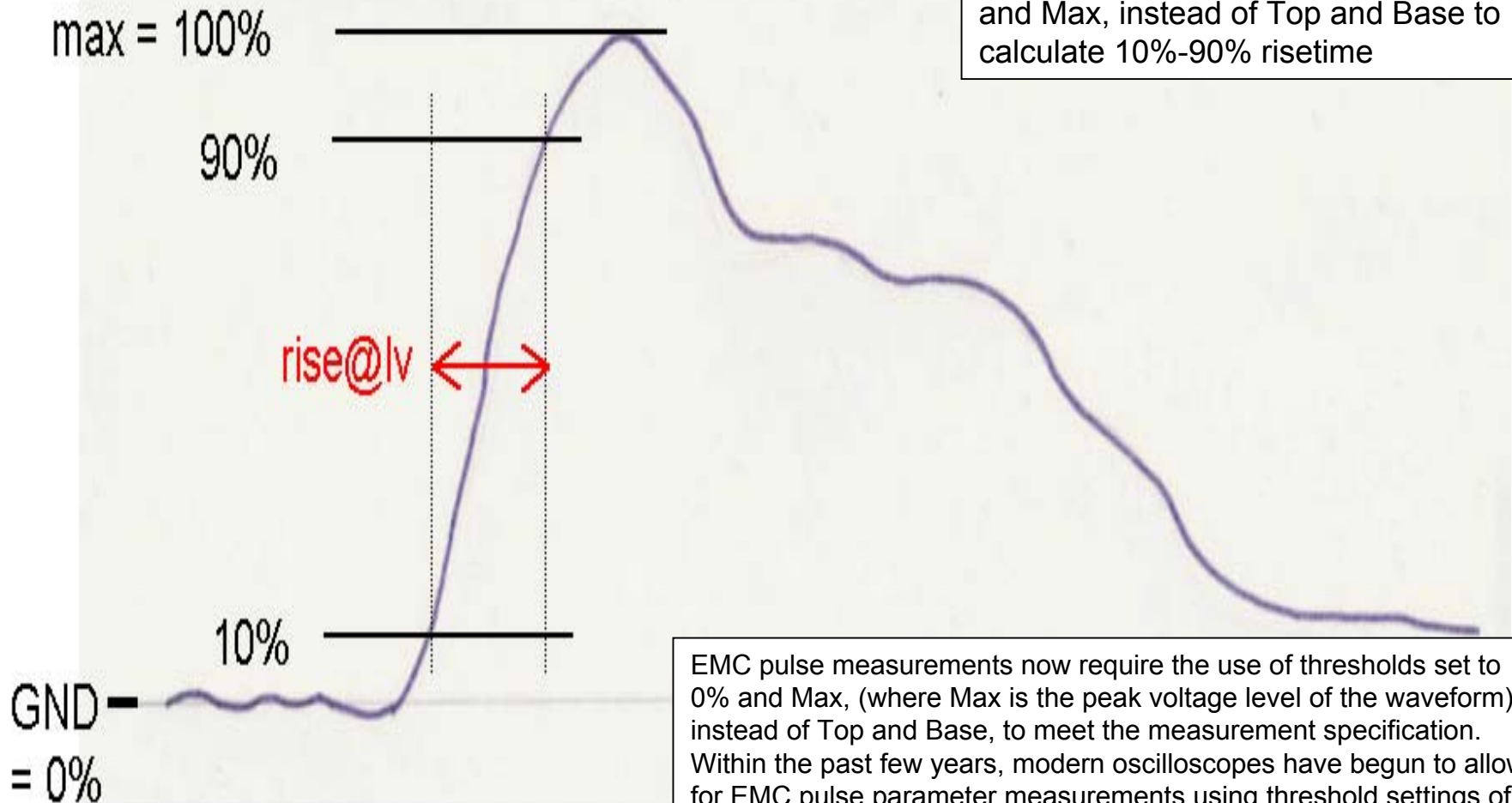
ESD Top and Base are not meaningful for pulse measurements



EMC Risetime Definitions use 0% and Max

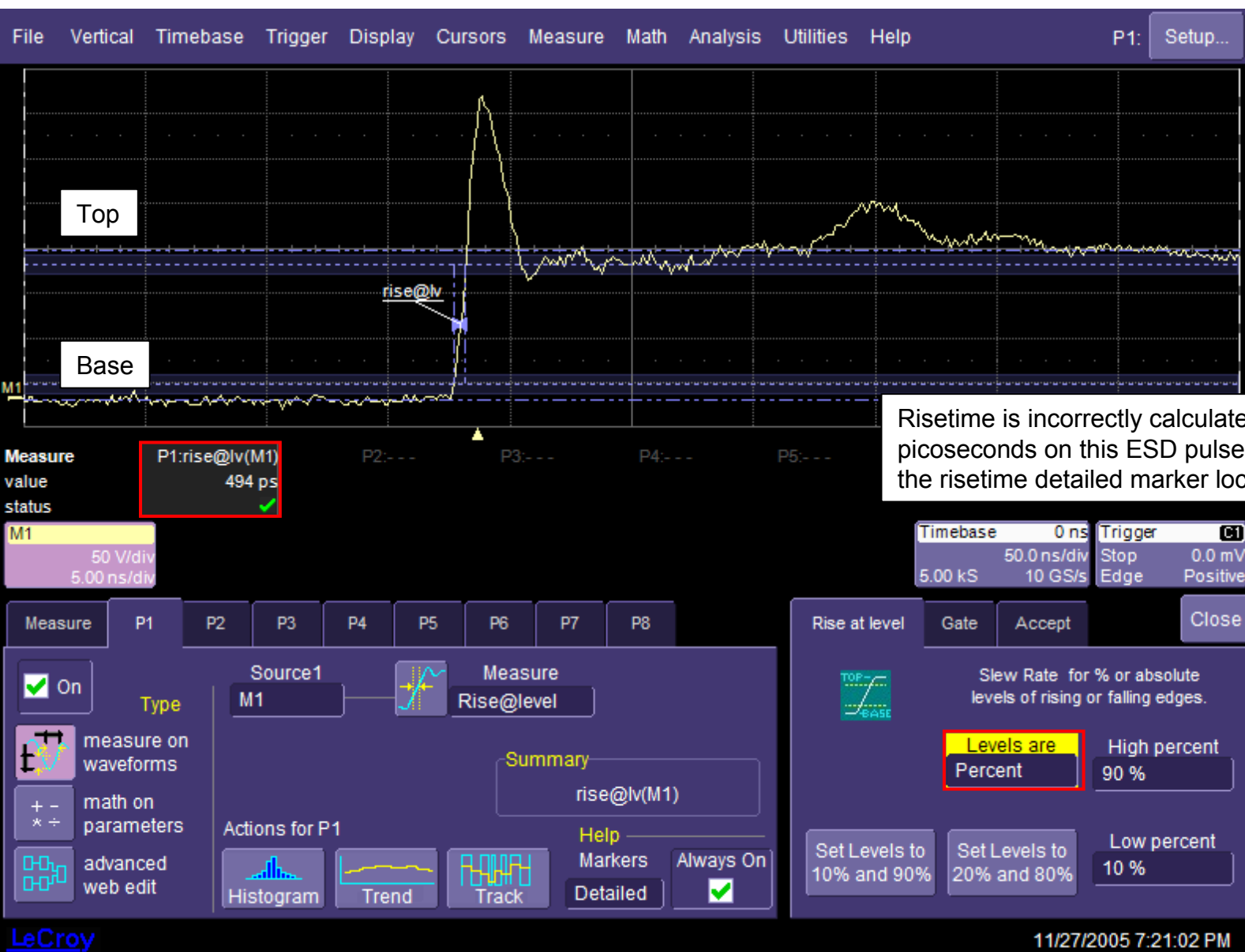
An oscilloscope must use 0% and Max thresholds in order to perform the EMC-specific measurement

Differing from IEEE pulse definitions, EMC pulse definitions (for example the IEC 61000-4-2 standard) use 0% and Max, instead of Top and Base to calculate 10%-90% risetime



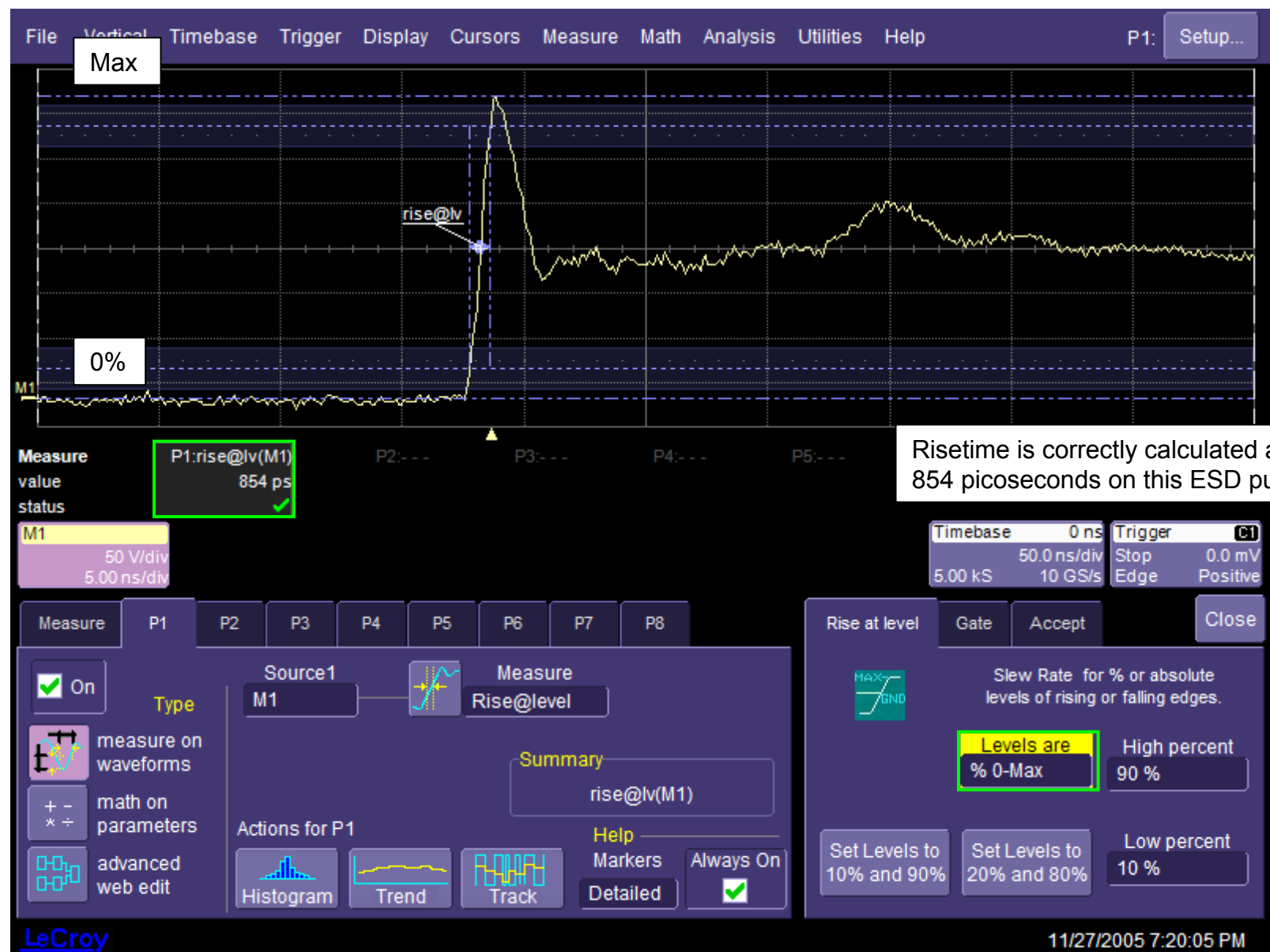
EMC pulse measurements now require the use of thresholds set to 0% and Max, (where Max is the peak voltage level of the waveform), instead of Top and Base, to meet the measurement specification. Within the past few years, modern oscilloscopes have begun to allow for EMC pulse parameter measurements using threshold settings of peak-to-peak, 0% to Max, and 0% to Min along with the standard absolute or percent levels.

Risetime calculated using standard IEEE pulse parameter definitions

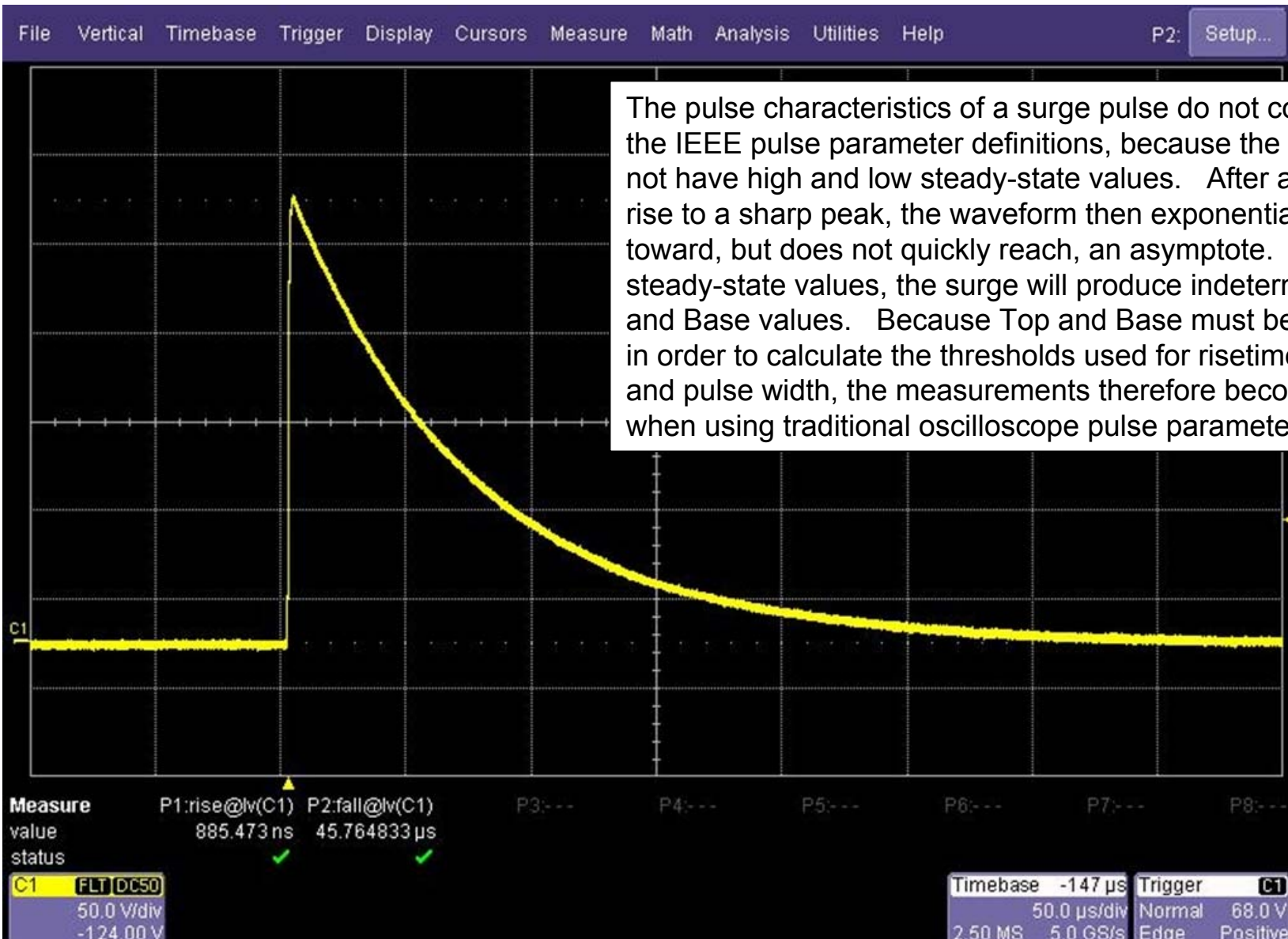


Risetime is incorrectly calculated as 494 picoseconds on this ESD pulse. Note the risetime detailed marker location.

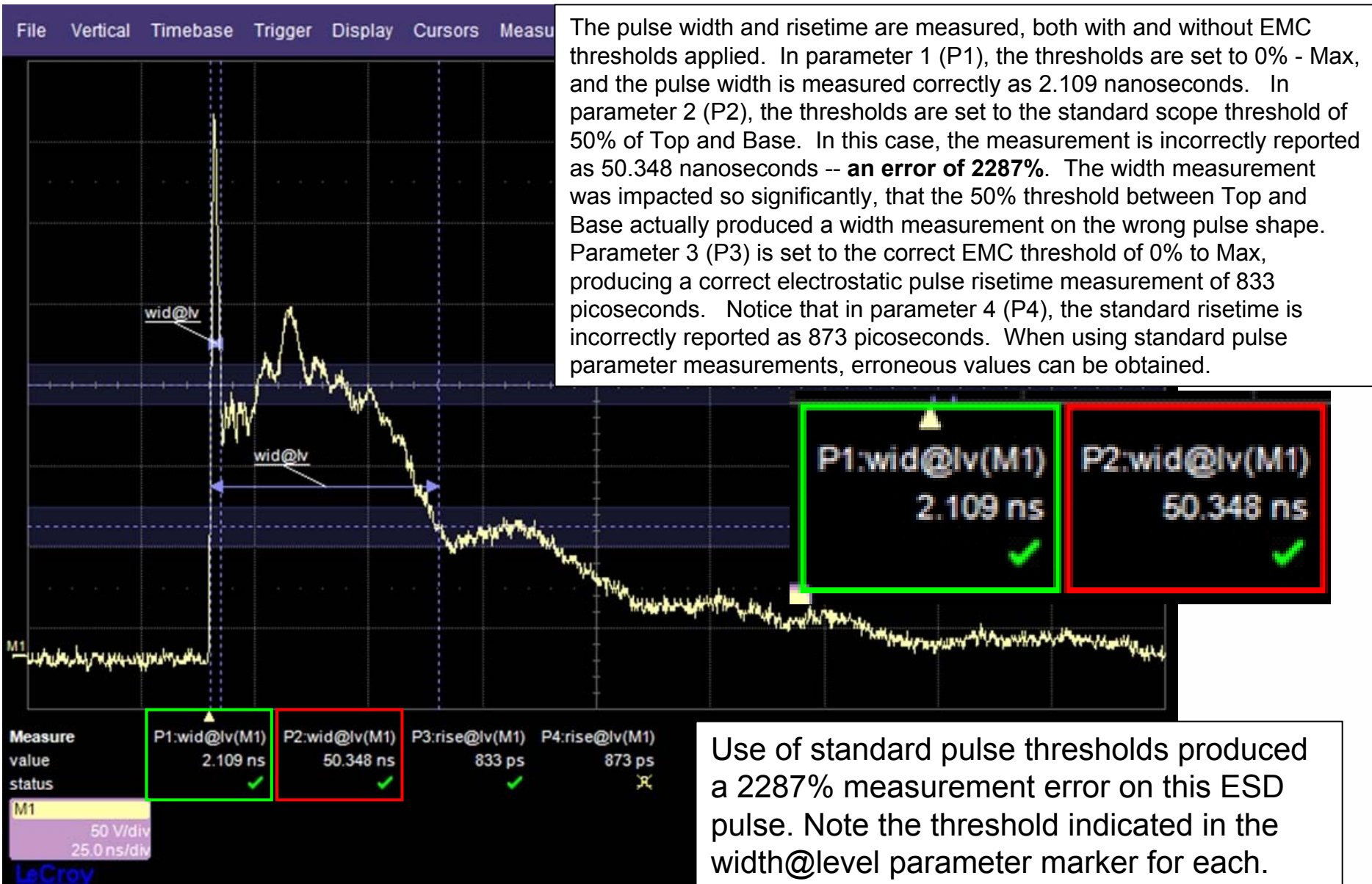
Risetime calculated using EMC thresholds



A Surge pulse does not have a clearly-defined Top and Base



Standard and EMC thresholds for ESD pulse width

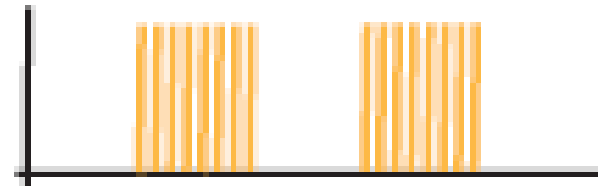
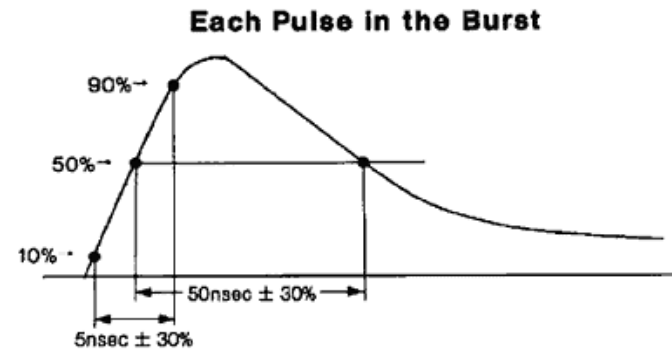


EFT Testing – Electrical Fast Transient

Measurement Steps

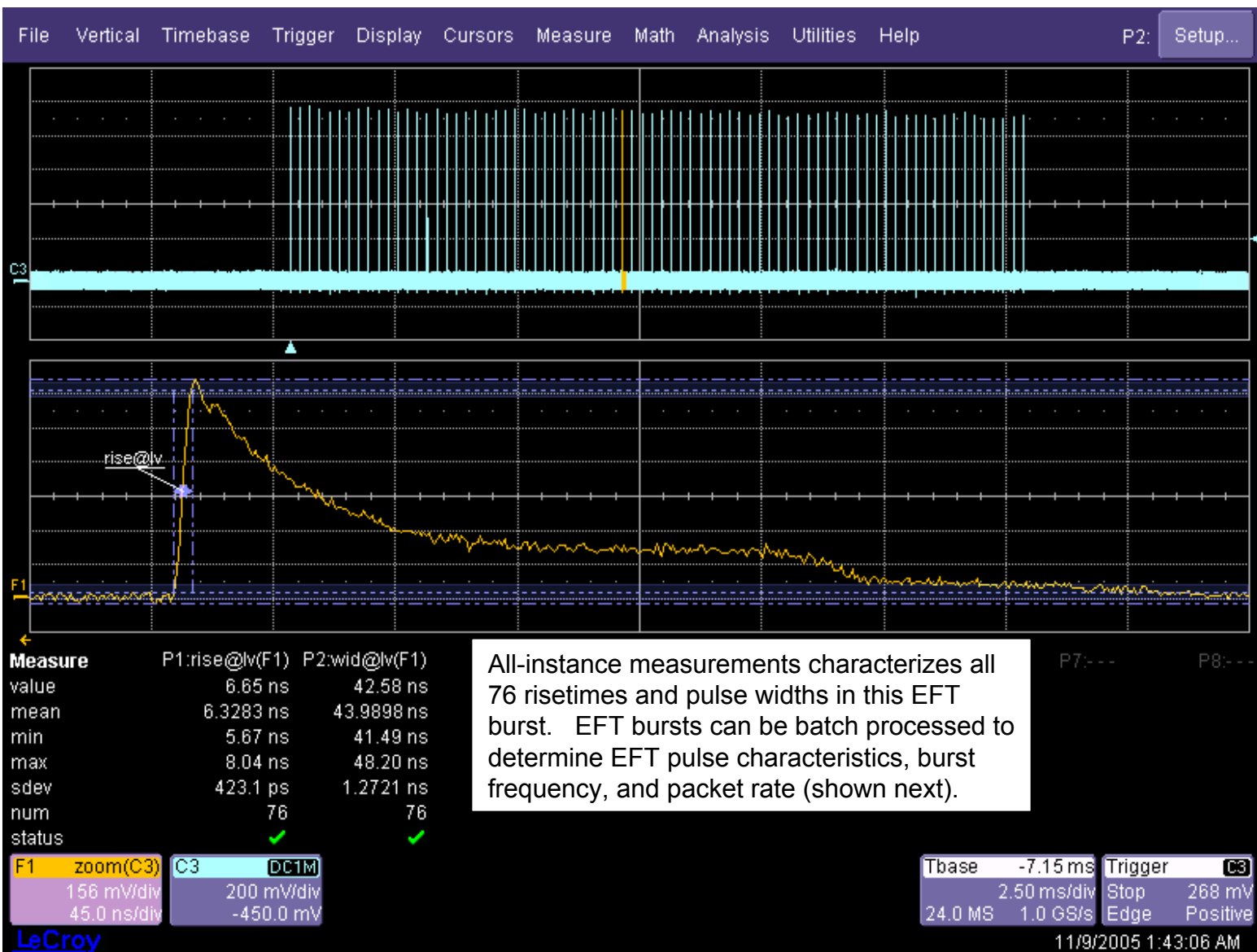
- Pulse Characteristics
 - $T_{\text{rise}} = 5\text{ns}$
 - $T_{\text{fall}} = 50\text{ns}$
 - Burst of many 5x50 pulses
- Measurement Needs
 - Capture 2ms of burst
 - Measure one pulse, verify shape (rise, fall, width)
 - Measure burst frequency (10-100 kHz)
 - Measure Capture time of burst packet (2ms)
 - Measure burst packet rate (300ms)

STANDARD EFT WAVEFORM

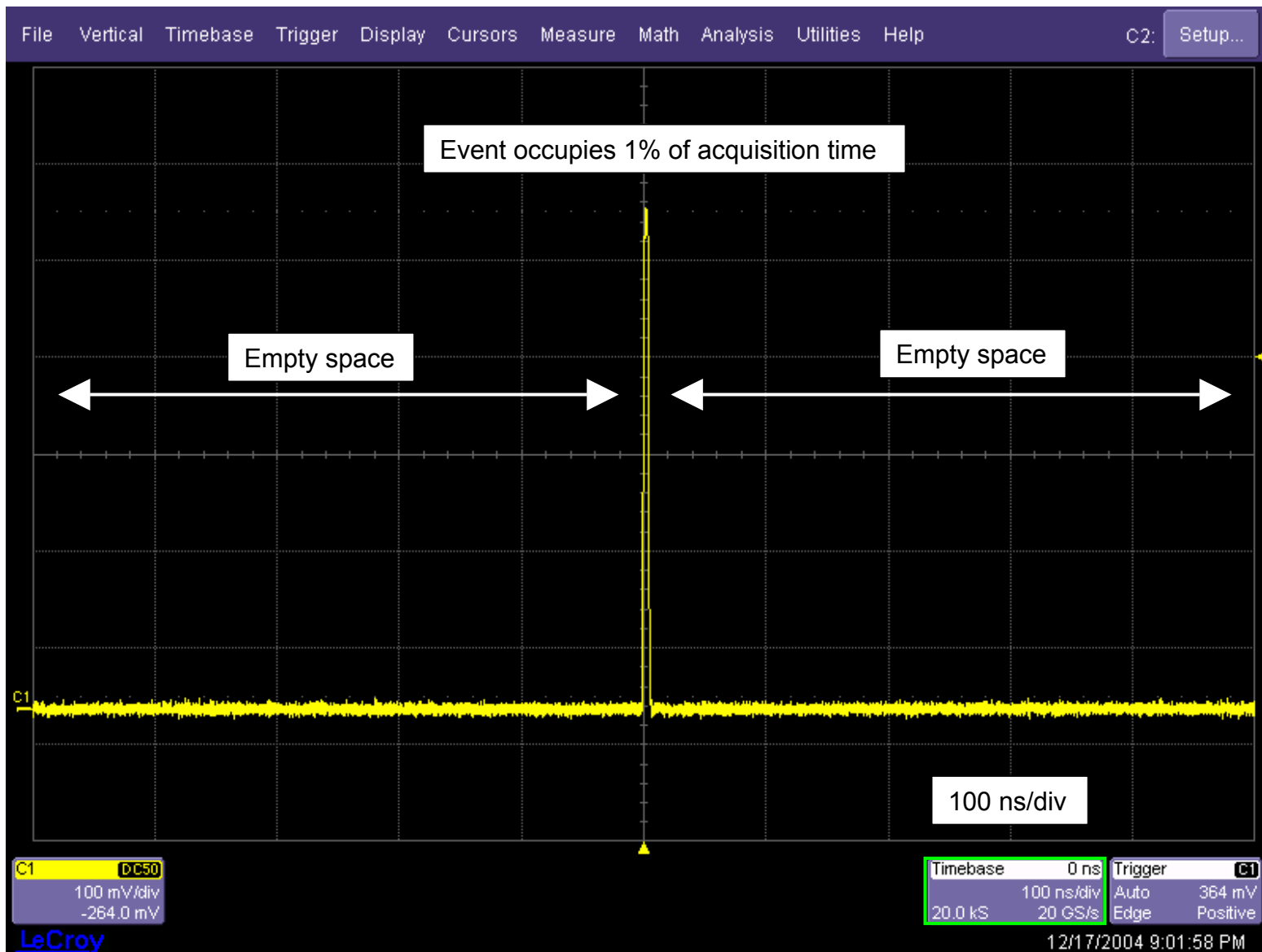


EFT Testing – Electrical Fast Transient

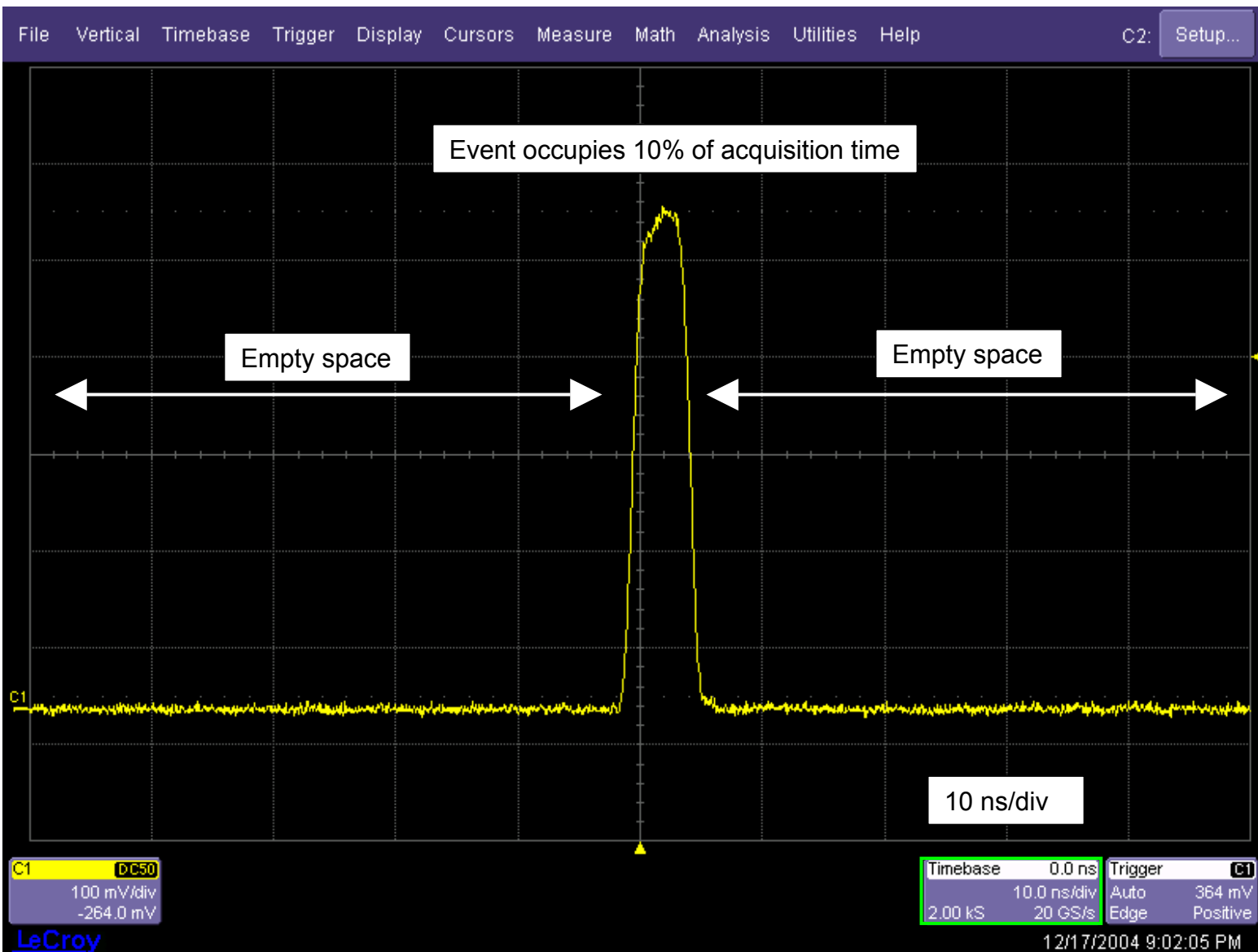
Measurement Statistics



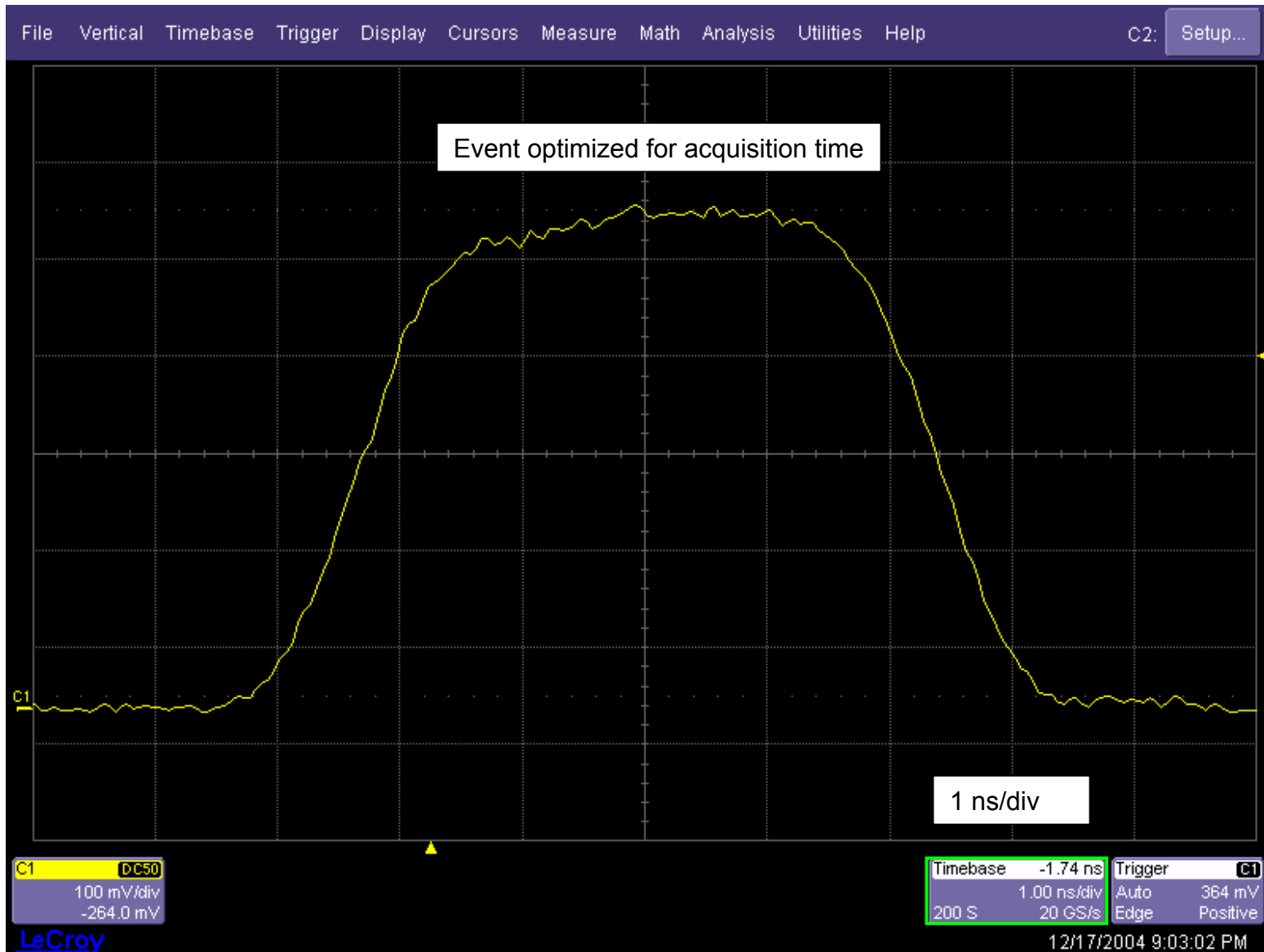
Maximizing Acquisition Memory for Events



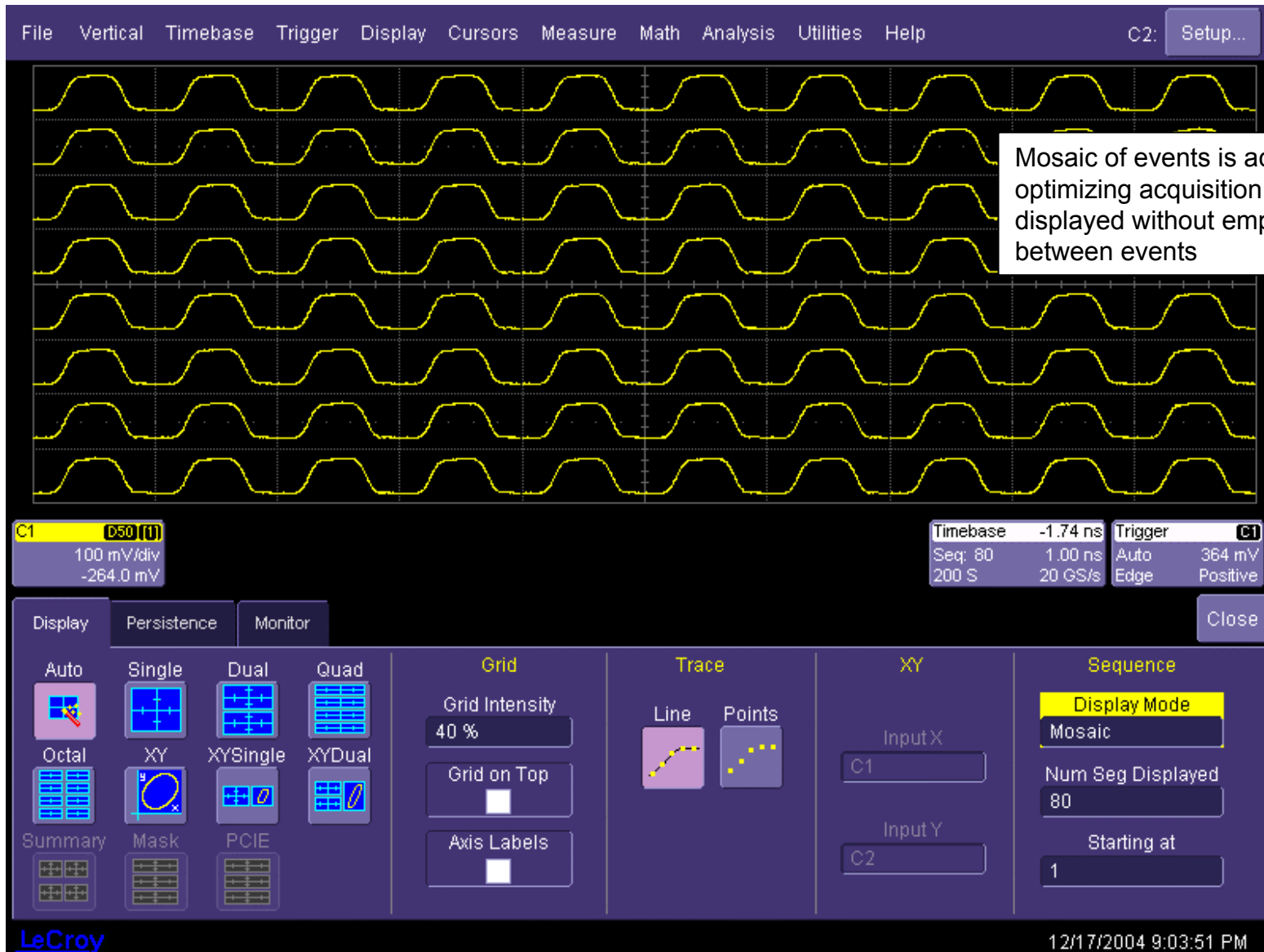
Maximizing Acquisition Memory for Events



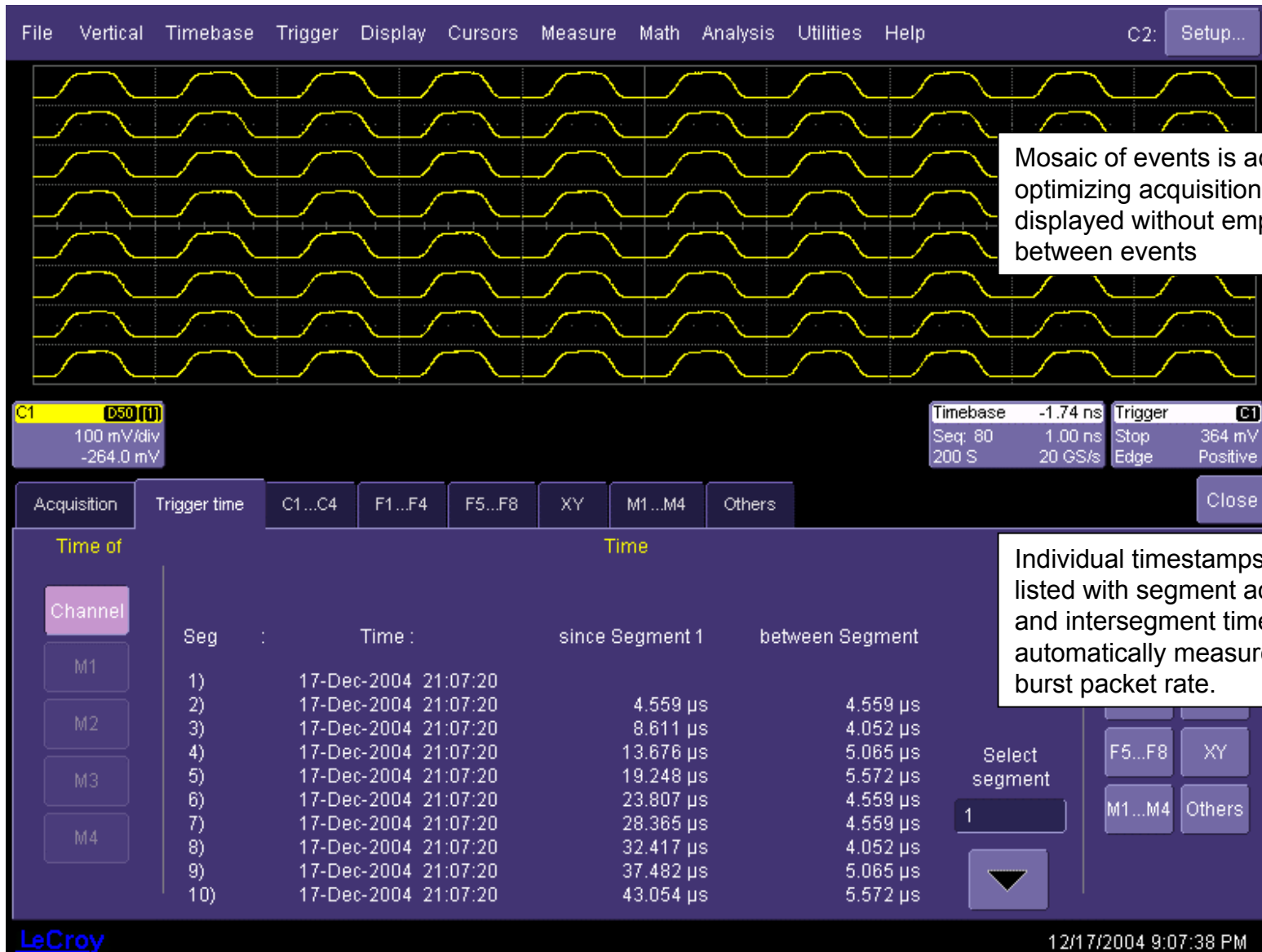
Maximizing Acquisition Memory for Events



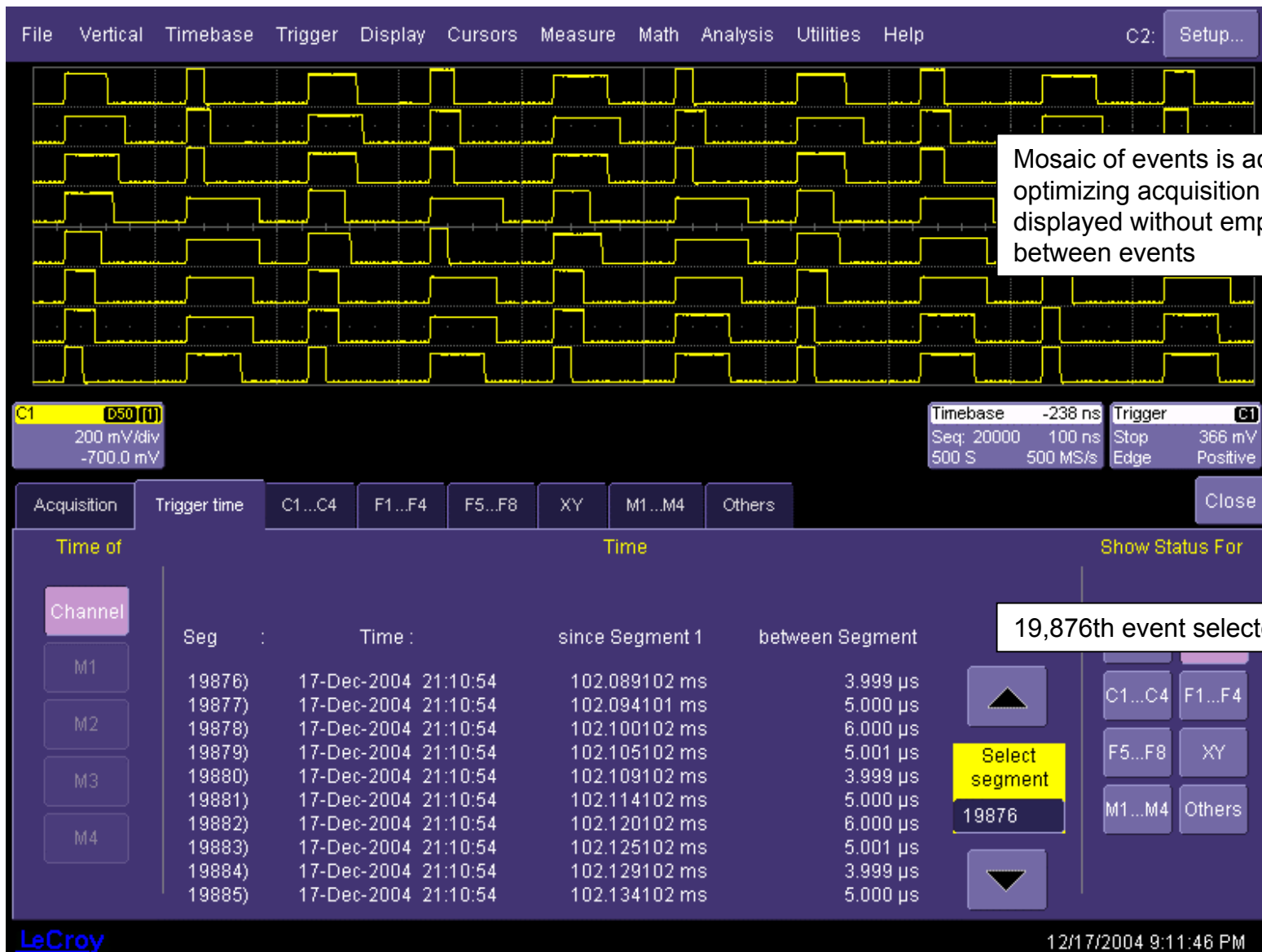
Maximizing Acquisition Memory for Events



Maximizing Acquisition Memory for Events



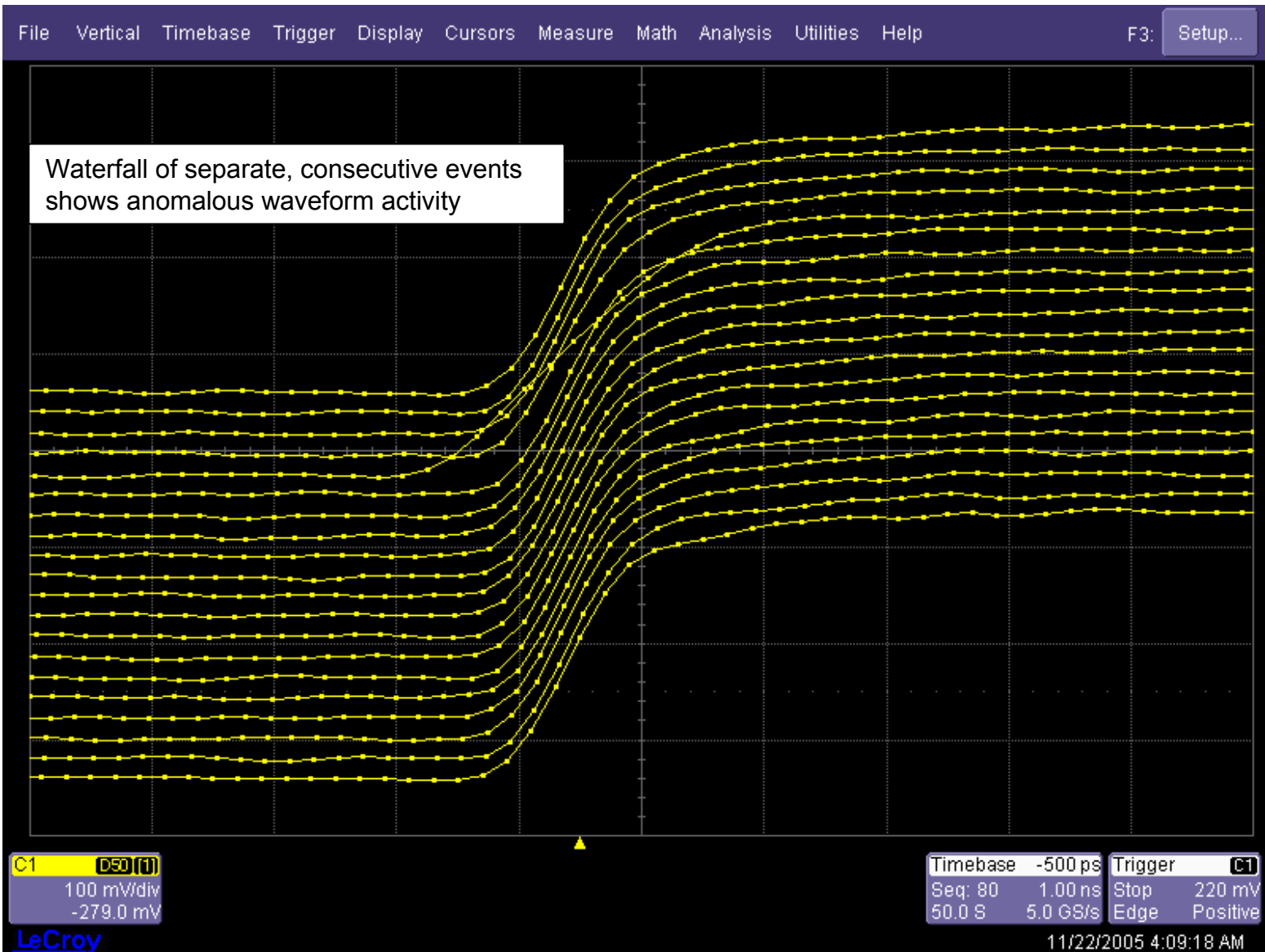
Maximizing Acquisition Memory for Events



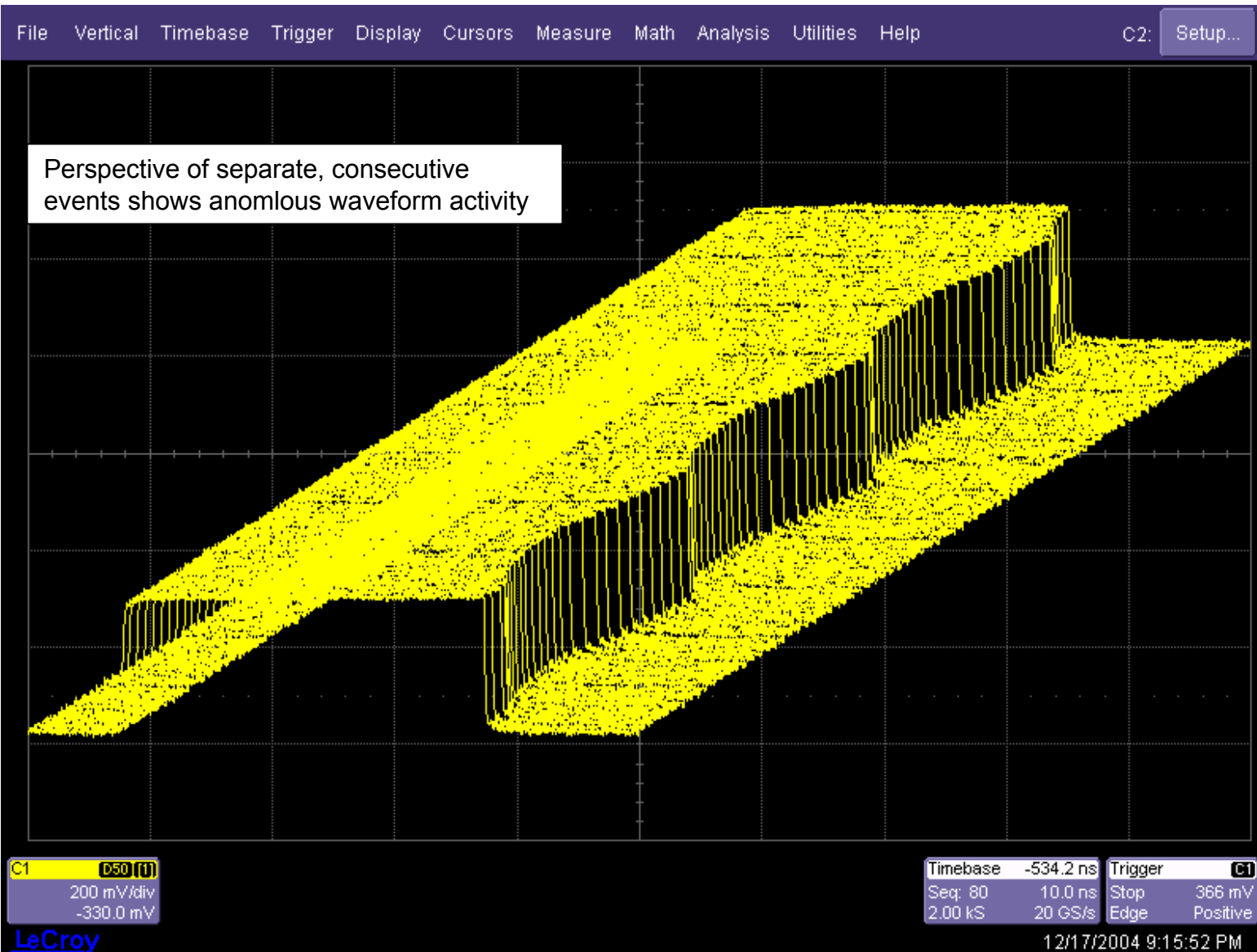
Mosaic of events is acquired while optimizing acquisition memory, and displayed without empty spaces between events

19,876th event selected

Sequence Waterfall shows anomaly



Sequence Perspective shows contour of acquired pulses

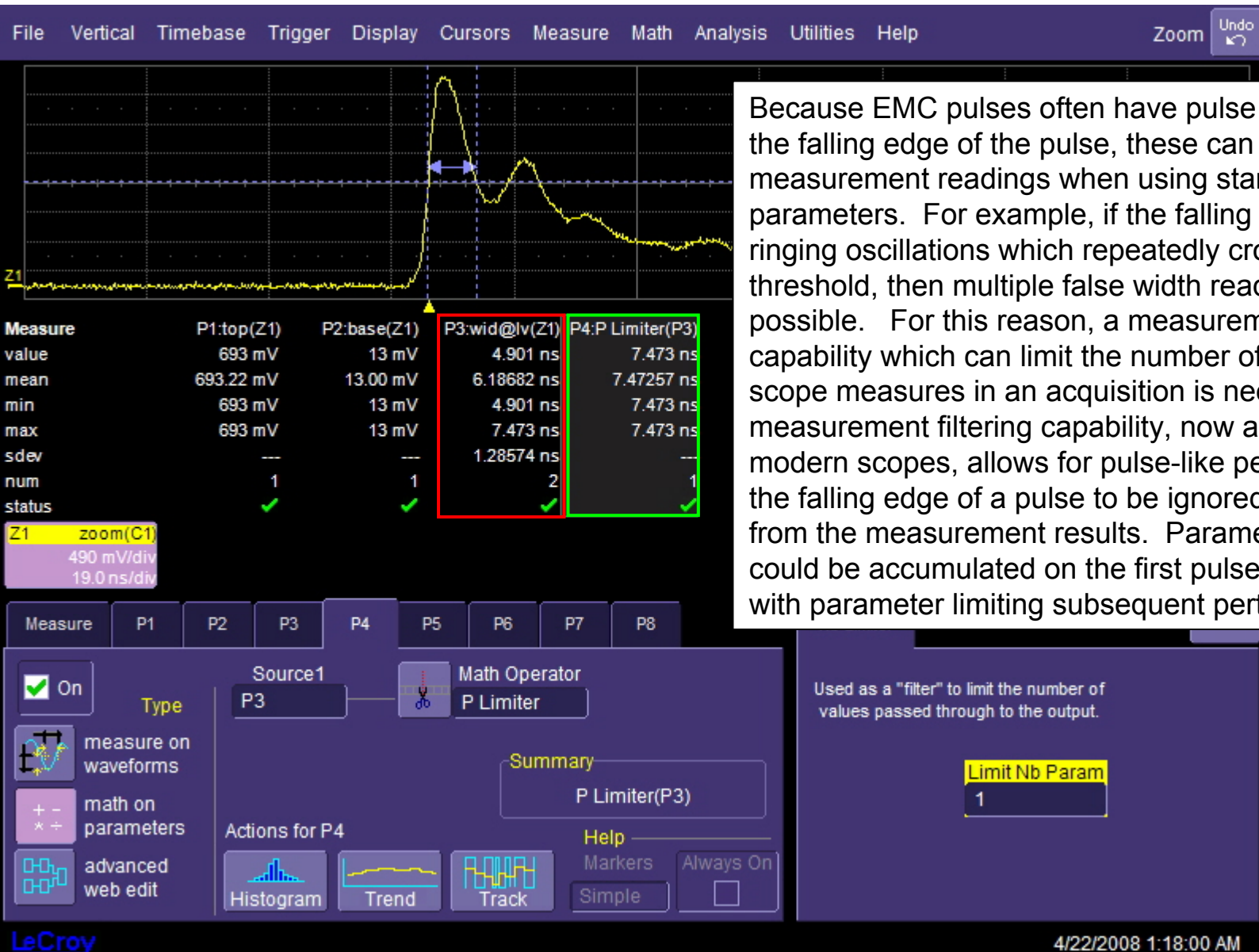


EFT Testing – Electrical Fast Transient

Sequence Mode and Octal Grid

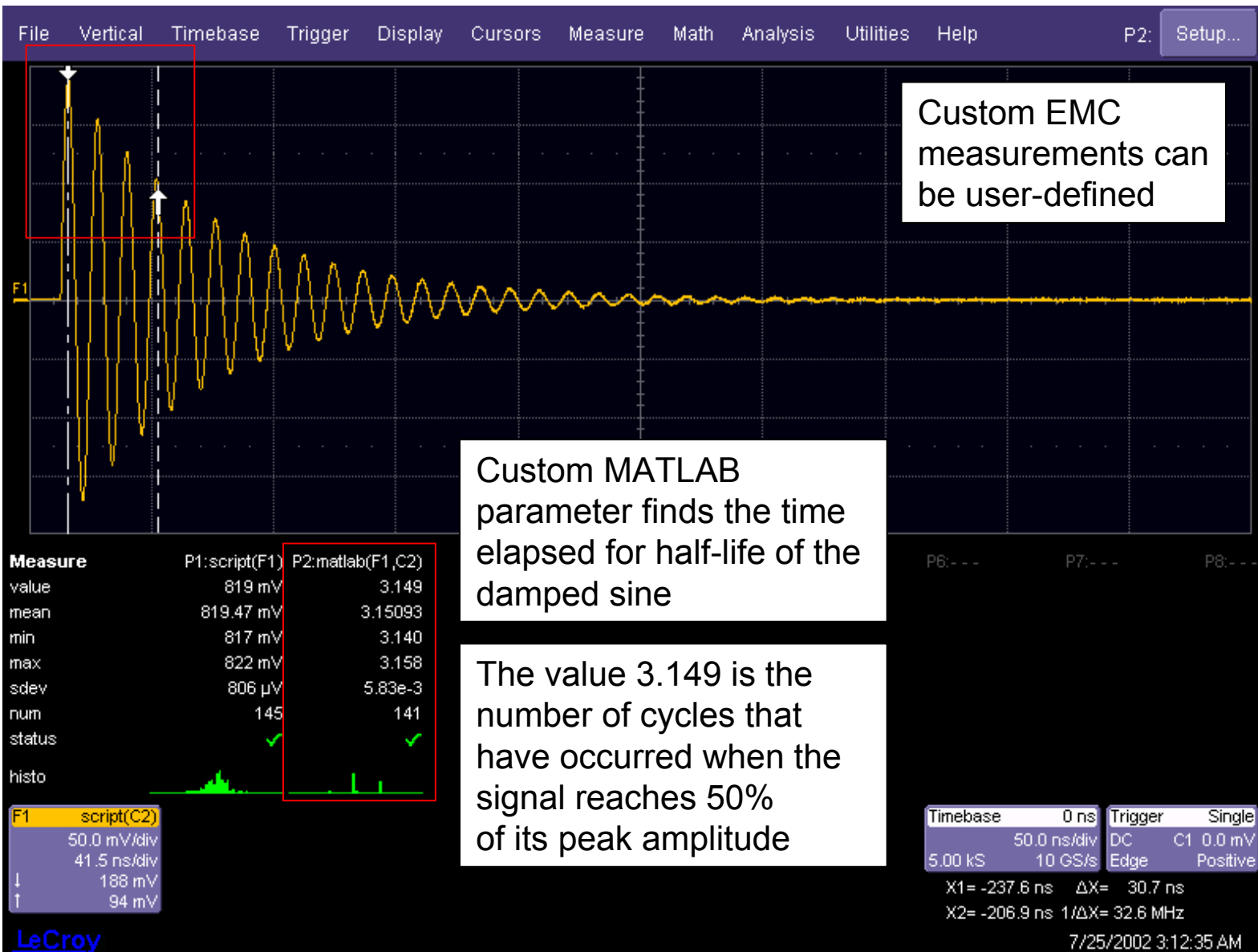


Parameter limiting technique for ESD width measurement



Because EMC pulses often have pulse perturbations on the falling edge of the pulse, these can result in false measurement readings when using standard parameters. For example, if the falling edge had ringing oscillations which repeatedly crossed the threshold, then multiple false width readings would be possible. For this reason, a measurement filtering capability which can limit the number of pulses the scope measures in an acquisition is needed. This measurement filtering capability, now available on modern scopes, allows for pulse-like perturbations on the falling edge of a pulse to be ignored and excluded from the measurement results. Parameter statistics could be accumulated on the first pulse in conjunction with parameter limiting subsequent perturbations.

Inline Custom Measurement



Real-Time Modification of Custom Measurement

The screenshot displays the LeCroy oscilloscope's measurement and MATLAB integration interface. At the top, a menu bar includes File, Vertical, Timebase, Trigger, Display, Cursors, Measure, Math, Analysis, Utilities, and Help. The main display area shows a waveform labeled F1 with a text overlay: "Real-time modification of custom algorithm".

Below the waveform, the "Measure" section provides statistical data for two sources:

	P1:script(F1)	P2:matlab(F1)
value	820 mV	3.149
mean	819.47 mV	3.15347
min	817 mV	3.149
max	822 mV	3.158
sdev	801 μ V	4.95e-3
num	150	2
status	✓	✓
histo		

On the left, a "script(C2)" panel shows measurement settings: 50.0 mV/div, 41.5 ns/div, 188 mV (down), and 94 mV (up).

The "MATLAB Editor" window is open, showing the following code:

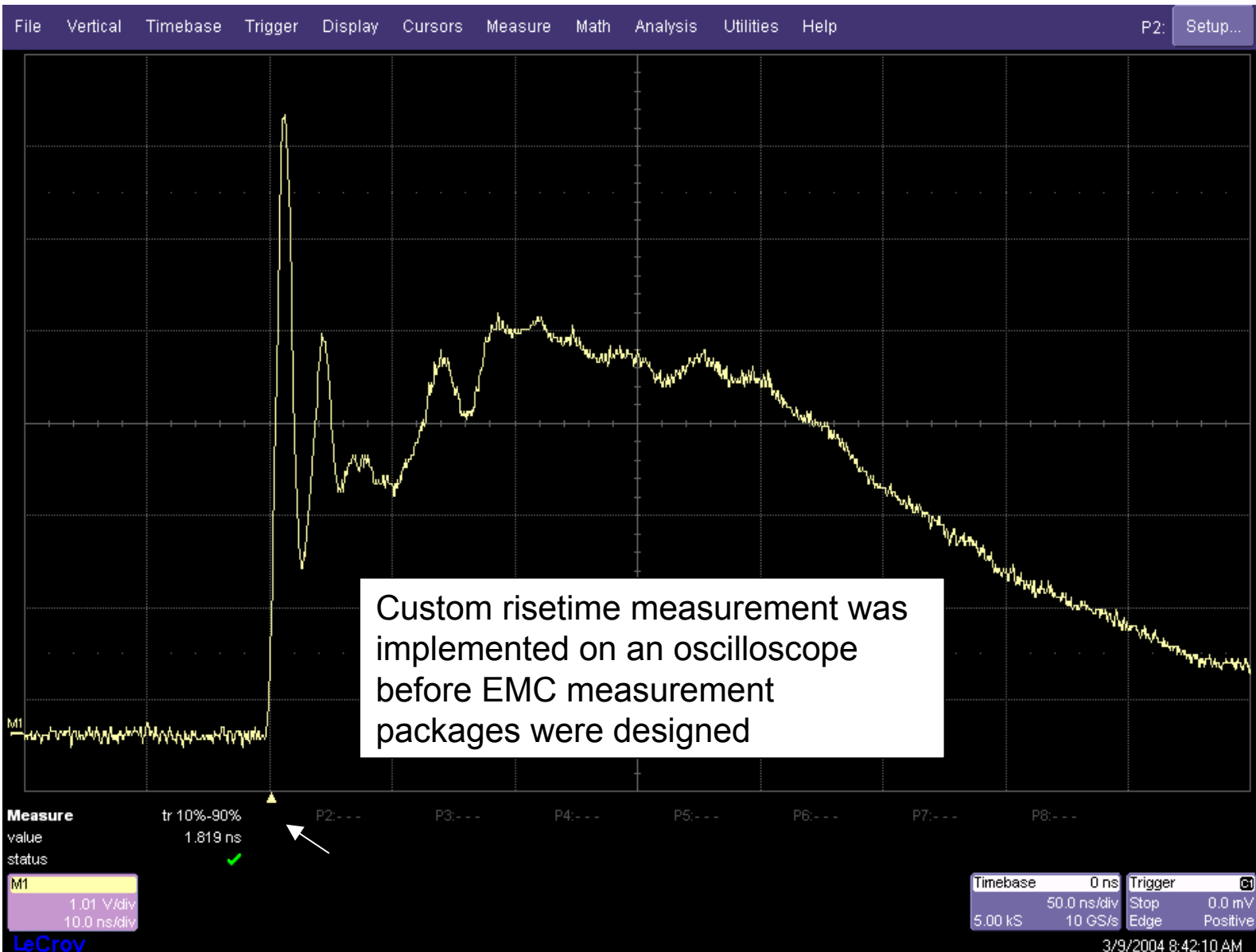
```
for k = edgepos(start):edgepos(start+1)
    if data(k) > 0.5 * maxdata
        halflife = start+(k-edgepos(start))/(edgepos(start+1)-edgepos(start))
        break
    end
end
ParamOut = halflife;
```

The "MATLAB Response" window displays an error message:

```
??? Undefined function or variable 'x'.
Error in ==> C:\MATLAB6pl\work\TimeDecayHalfLife.m
On line 7 ==> x = x + 5
```

At the bottom, there are buttons for "Load Code", "Save Code", and "Close". The LeCroy logo is in the bottom left corner, and the timestamp "7/25/2002 3:14:28 AM" is in the bottom right corner.

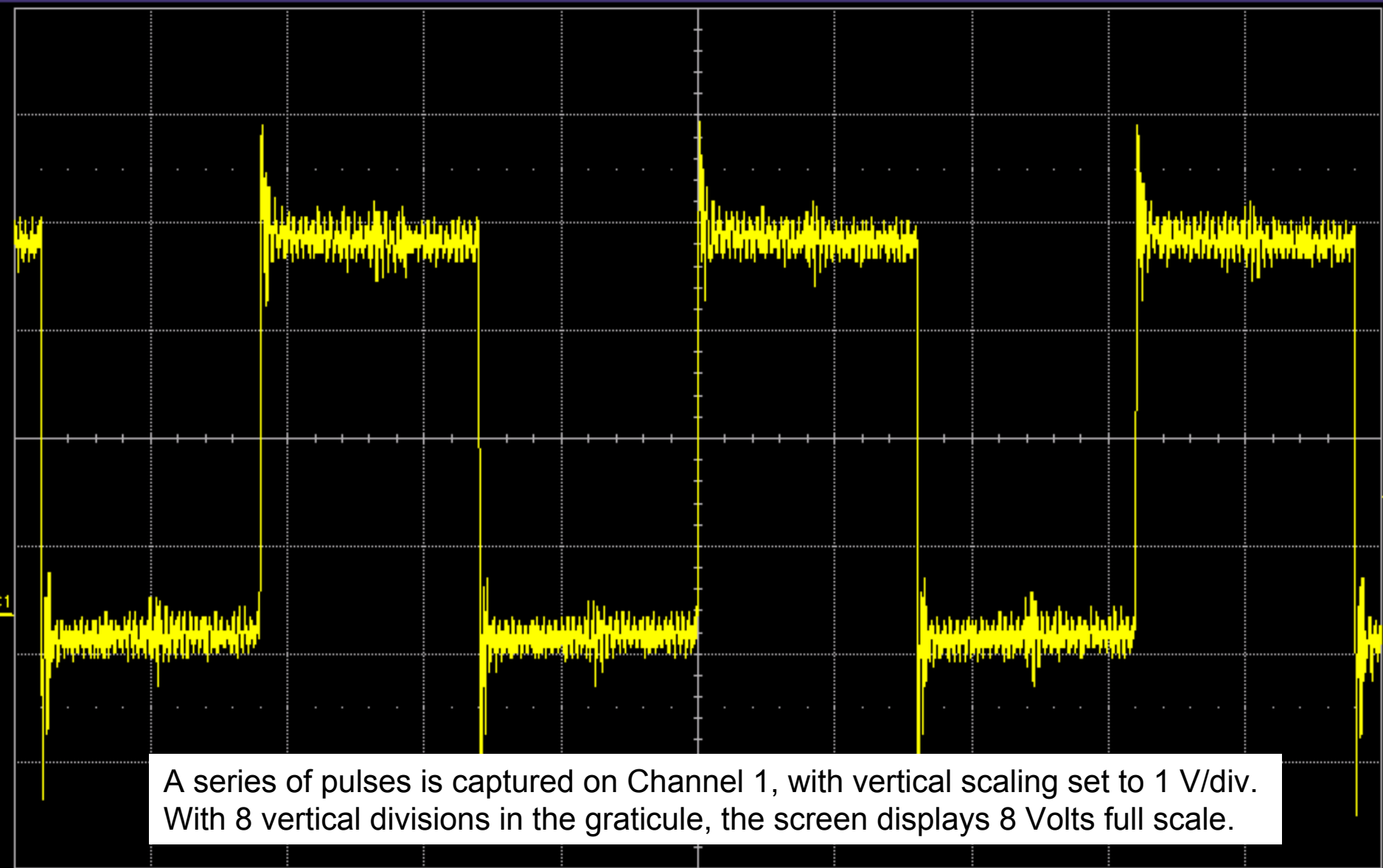
EMC Risetime Custom Definition



Summary

- EMC/ESD test specifications require verification of rise times, fall times, pulse widths and pulse shapes
- Standard oscilloscope pulse parameter measurements are based on IEEE pulse definitions
- EMC engineers use different pulse definitions which oscilloscopes are not designed to use
- Non-standard measurement setups are required to perform accurate pulse parameter measurements of electrostatic discharge, electrical fast transients, and surges.
- Selecting the correct measurement threshold can make a significant difference in the measurement accuracy of these signals.
- During acquisition of EMC pulses, vertical channel scaling affects signal integrity (shown next)

Vertical Scaling of EMC pulses affects Signal Integrity



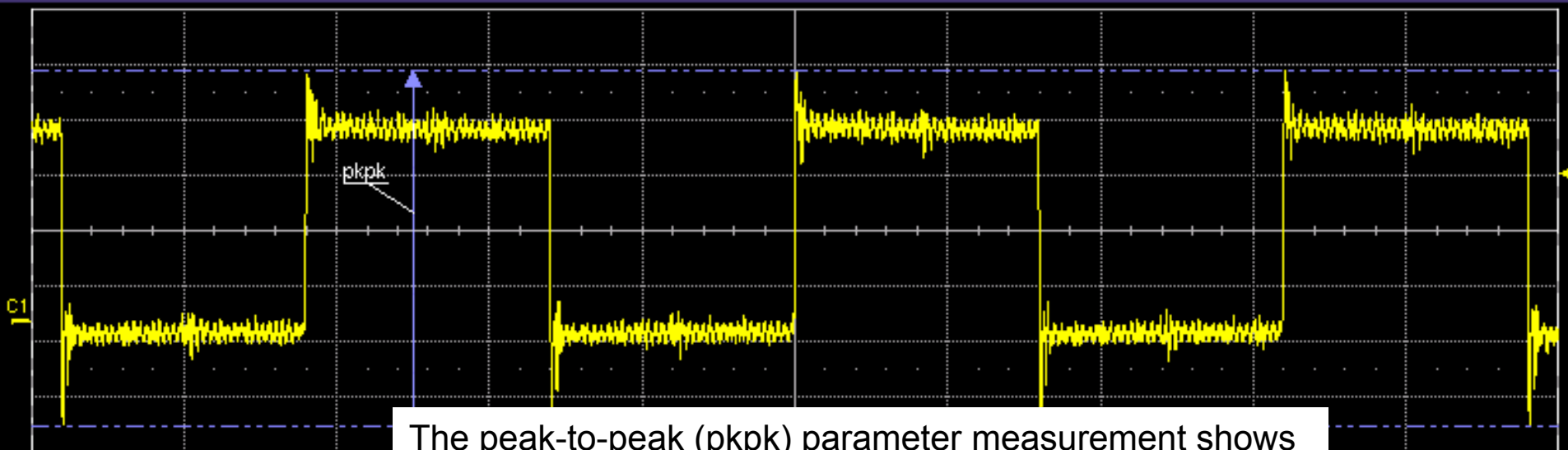
C1

DC1M

1.00 V/div

-1.650 V offset

Timebase	0 ns	Trigger	C1
	250 ns/div	Auto	1.10 V
12.5 kS	5.0 GS/s	Edge	Positive



The peak-to-peak (pkpk) parameter measurement shows a value of 6.41 V for this waveform. The waveform is occupying $(6.41\text{V})/(8\text{V}) = 80.1\%$ of full scale.

Measure
value
status

P1:pkpk(C1)
6.41 V

C1

1.00 V/div
-1.650 V offset

Timebase 0 ns
250 ns/div
12.5 kS 5.0 GS/s

Trigger C1
Stop 2.64 V
Edge Positive

Measure P1 P2 P3 P4 P5 P6 P7 P8

☒ On

Type

measure on waveforms

math on parameters

advanced web edit

Source1
C1

Measure
Peak to peak

Summary
pkpk(C1)

Actions for P1

Histogram

Trend

Track

Help

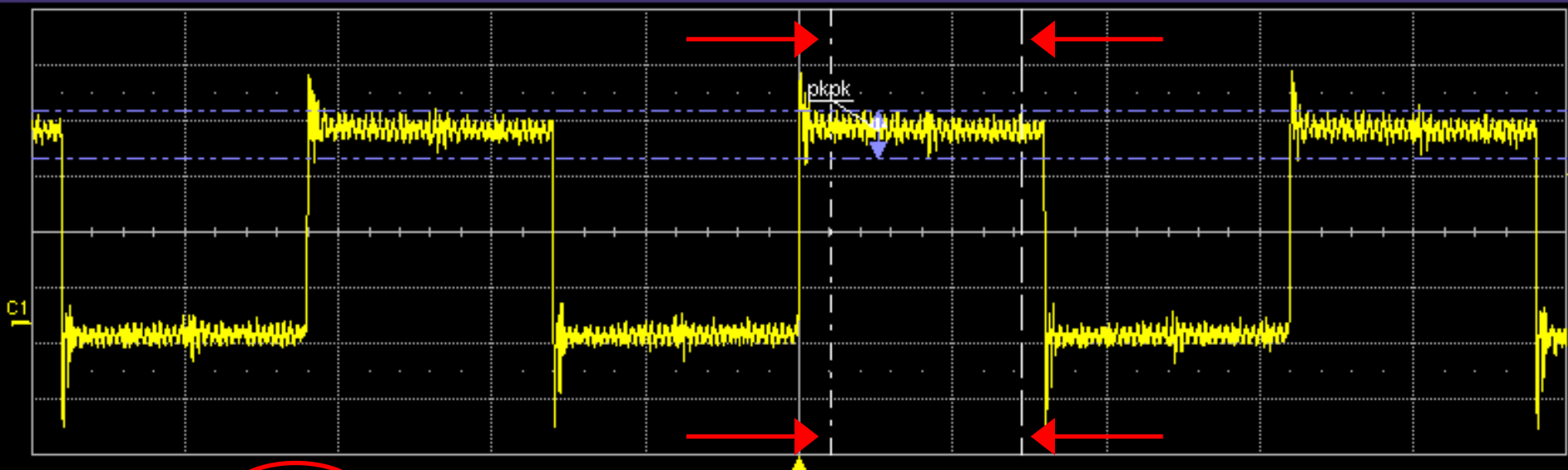
Markers

Always On

Detailed

Peak to Peak Gate Accept Close

Difference between maximum and minimum data values.



Measure
value
status
C1 DC1M
1.00 V/div
-1.650 V ofst

P1: pkpk(C1)
840 mV

The noise riding on the top of the pulse can be isolated and monitored, by adjusting the measurement gates to measure pkpk on the top of the pulse only.

Measure P1 P2 P3 P4 P5 P6 P7 P8

☒ On Type

Source1 C1 Measure Peak to peak

Summary pkpk(C1)

Actions for P1 Histogram Trend Track

Help Markers Always On Detailed

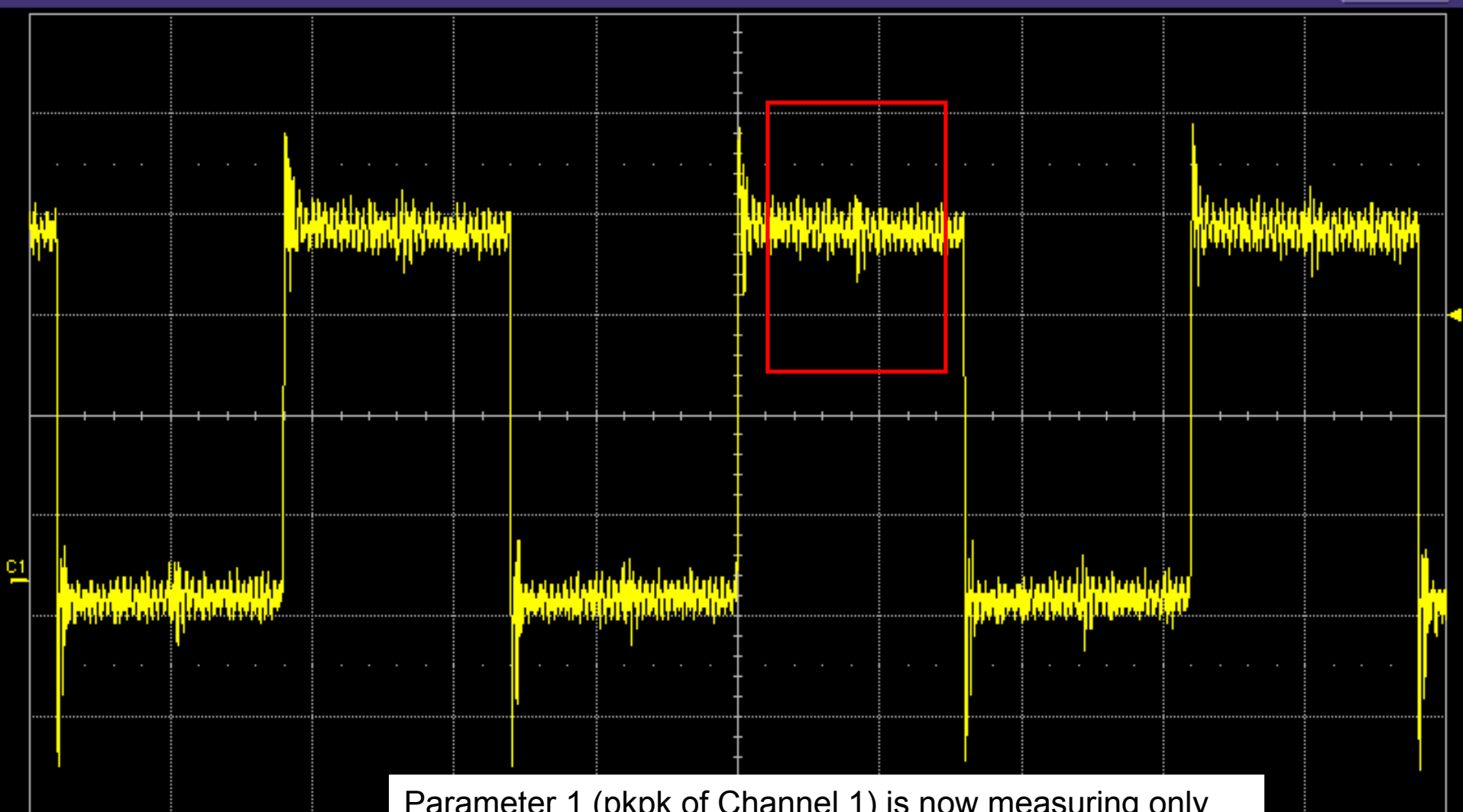
Peak to Peak Gate Accept Close

Measure gate on Source(s)

Default

Start 5.21 div

Stop 6.45 div

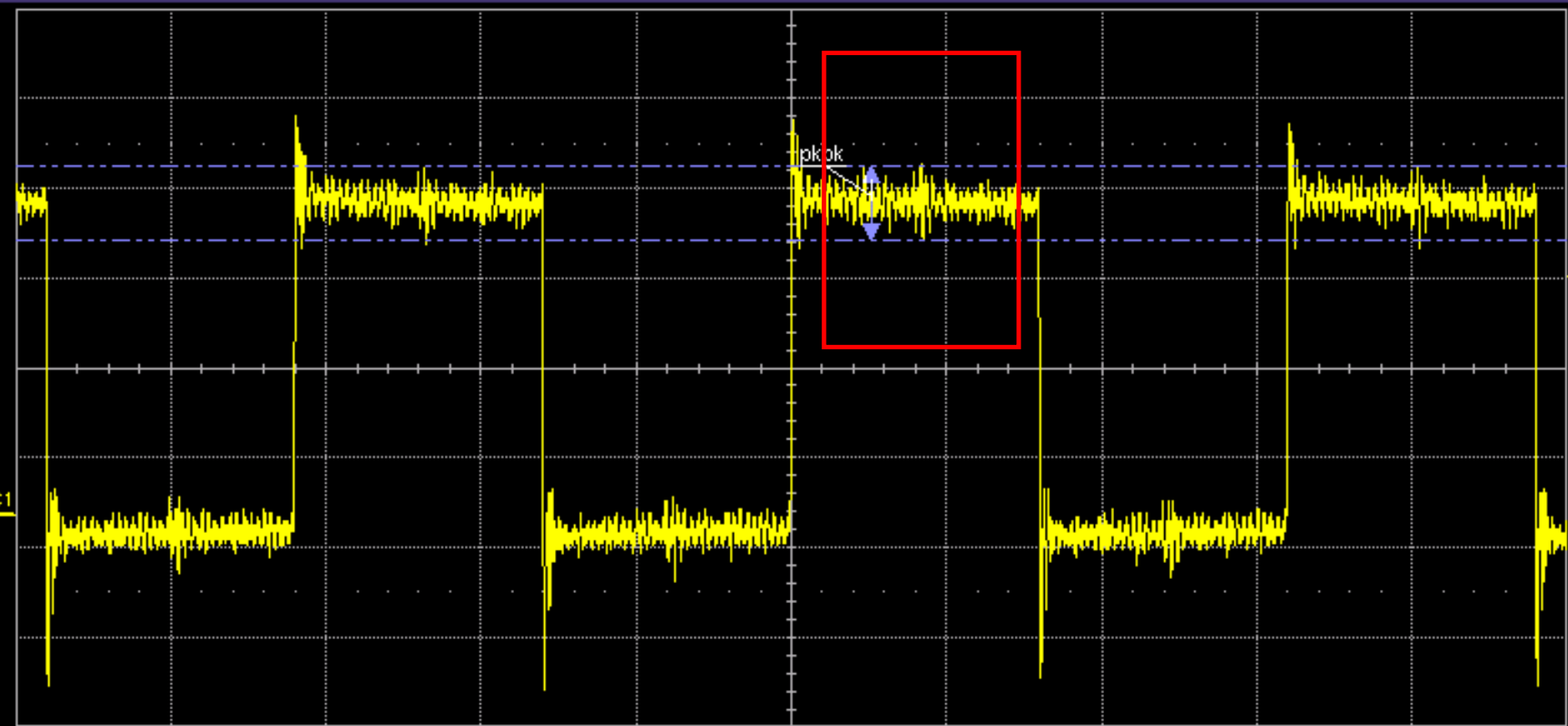


Parameter 1 (pkpk of Channel 1) is now measuring only the noise riding on the top of the pulse shown above.

Measure
value
status
F1:pkpk(C1)
840 mV

C1 DC1M
1.00 V/div
-1.650 V ofst

Timebase 0 ns
250 ns/div
12.5 kS 5.0 GS/s
Trigger C1
Stop 2.64 V
Edge Positive



Measure	P1:pkpk(C1)	P2:---	P3:---	P4:---	P5:---	P6:---	P7:---	P8:---
value	840 mV							
mean	886.7 mV							
min	663 mV							
max	1.10 V							
sdev	60.6 mV							
num	1.000e+3							
status								

C1

DC1M

1.00 V/div

-1.650 V ofst

To ensure statistical accuracy, 1000 acquisitions are taken, and the pkpk of the top of the pulse is measured each time. With vertical scaling of 1 V/div, the mean value of noise on the pulse is 886.7 mV.

Timebase0 ns

250 ns/div

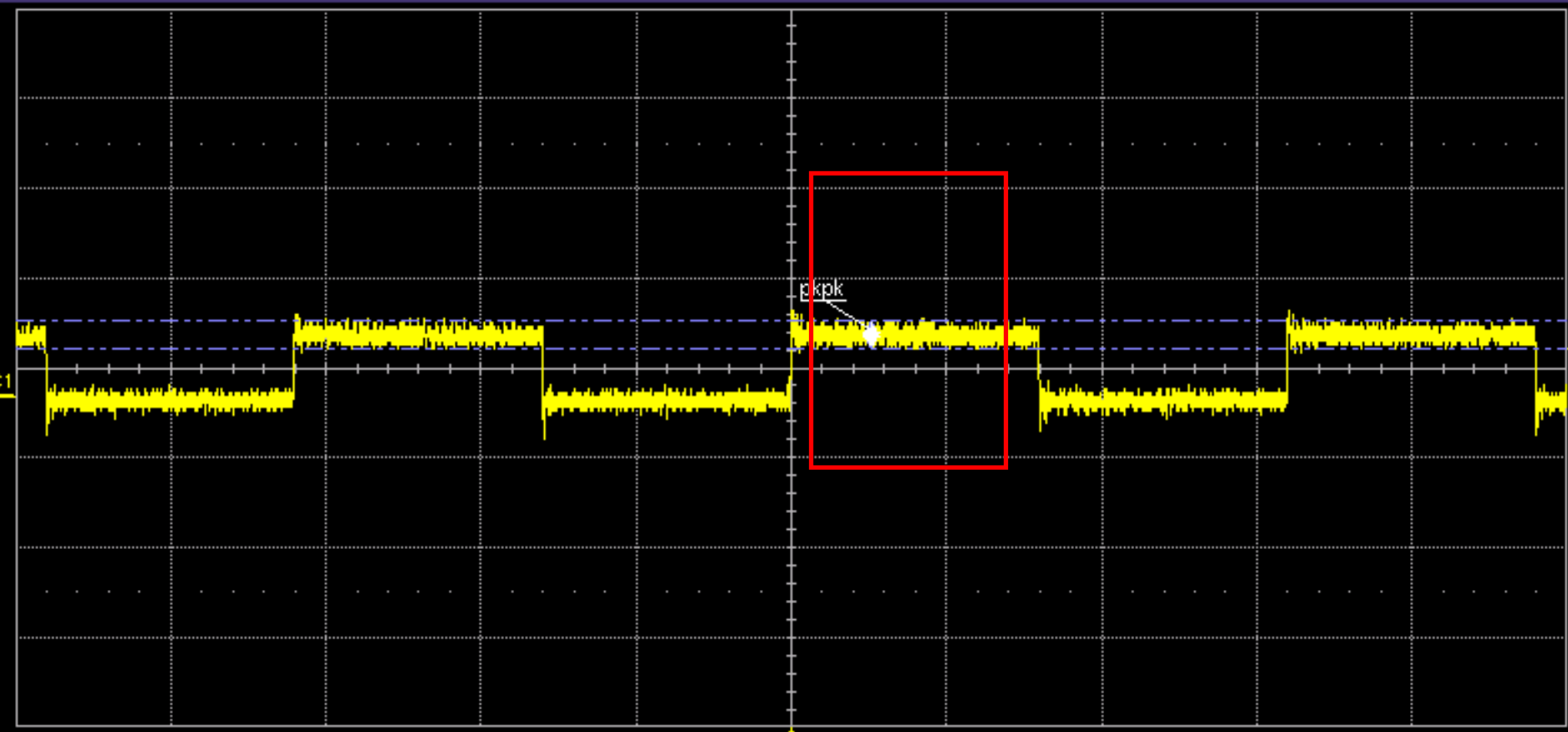
12.5 kS

5.0 GS/s

TriggerC1

Stop2.64 V

EdgePositive



Measure	P1:pkpk(C1)	P2:---	P3:---	P4:---	P5:---	P6:---	P7:---	P8:---
value	1.5 V							
mean	1.783 V							
min	1.3 V							
max	2.4 V							
sdev	153 mV							
num	1.000e+3							
status	✓							

Changing vertical scaling to 5 V/div, the mean value of pkpk noise has now changed to 1.783 V.

C1

DC1M

5.00 V/div

-1.60 V ofst

Timebase0 ns

250 ns/div

12.5 kS

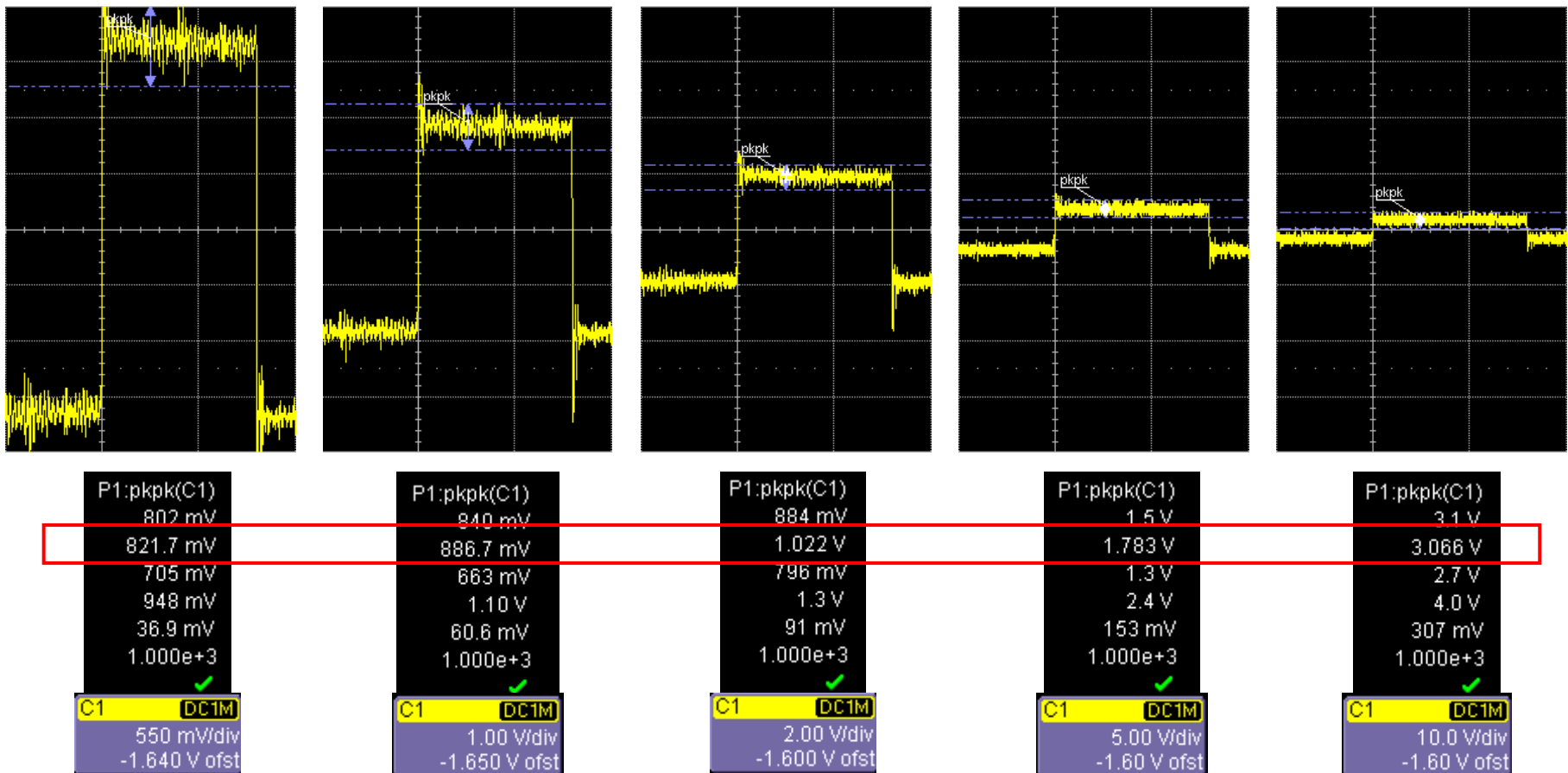
5.0 GS/s

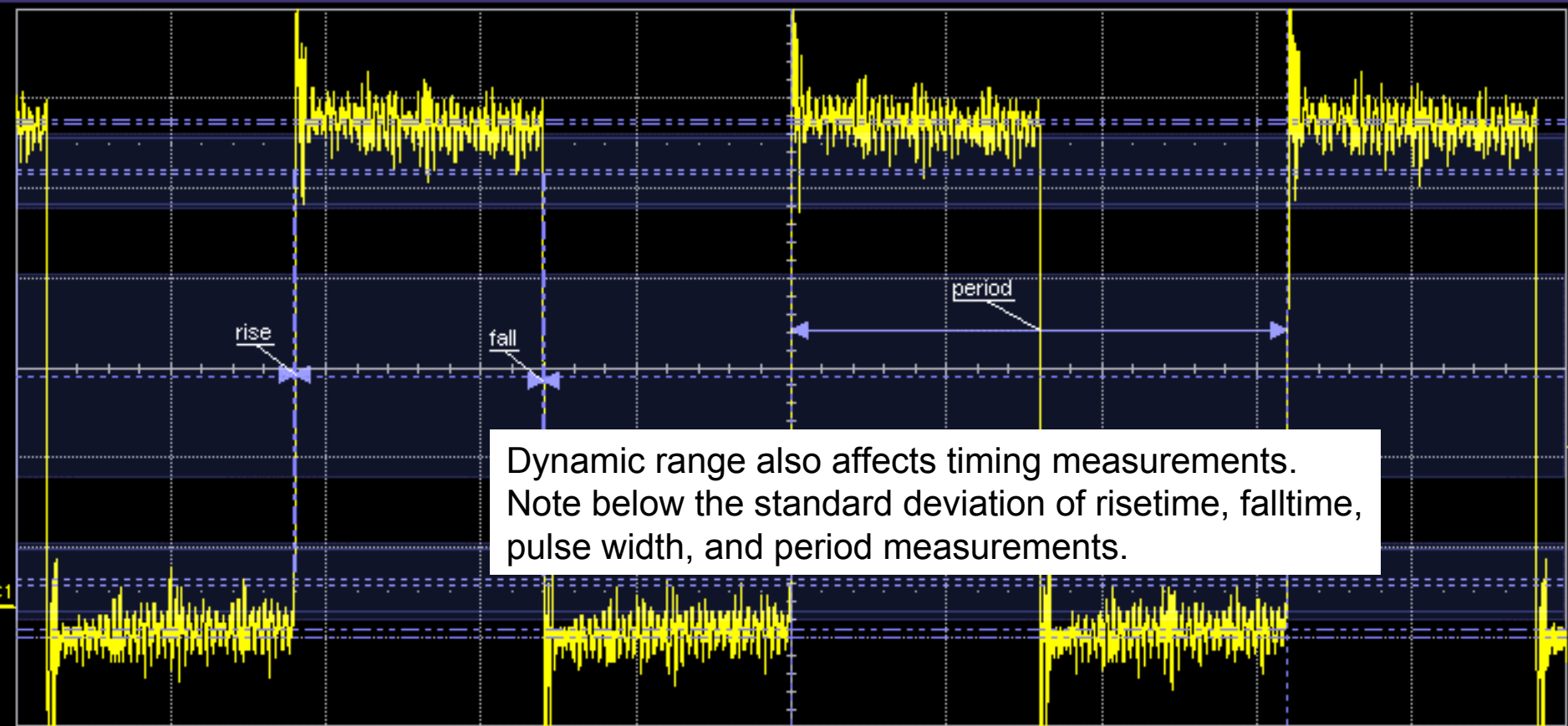
TriggerC1

Stop2.65 V

EdgePositive

Further adjusting vertical scaling shows that channel vertical scaling significantly affects the measured noise level. At 550 mV/div, the mean noise level is **821 mV**; at 2 V/div, the noise level is **1.02 V**, and at 10 V/div, the noise level is **3.06V**. Between 2 V/div and 10 V/div, the measured noise level tripled (factor of 3x) when changing the V/div by a factor of 5x.





Dynamic range also affects timing measurements.
Note below the standard deviation of risetime, falltime, pulse width, and period measurements.

Measure	P1:rise(C1)	P2:fall(C1)	P3:width(C1)	P4:period(C1)	P5:---	P6:---	P7:---	P8:---
value	1.648 ns	1.335 ns	400.316 ns	800.007 ns				
mean	1.63438 ns	1.33528 ns	400.27507 ns	799.99620 ns				
min	1.515 ns	1.232 ns	400.211 ns	799.922 ns				
max	1.829 ns	1.432 ns	400.340 ns	800.055 ns				
sdev	41.08 ps	30.41 ps	21.45 ps	21.12 ps				
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3				
status	✓	✓	✓	✓				

C1

DC1M

650 mV/div

-1.730 V ofst

Timebase0 ns

250 ns/div

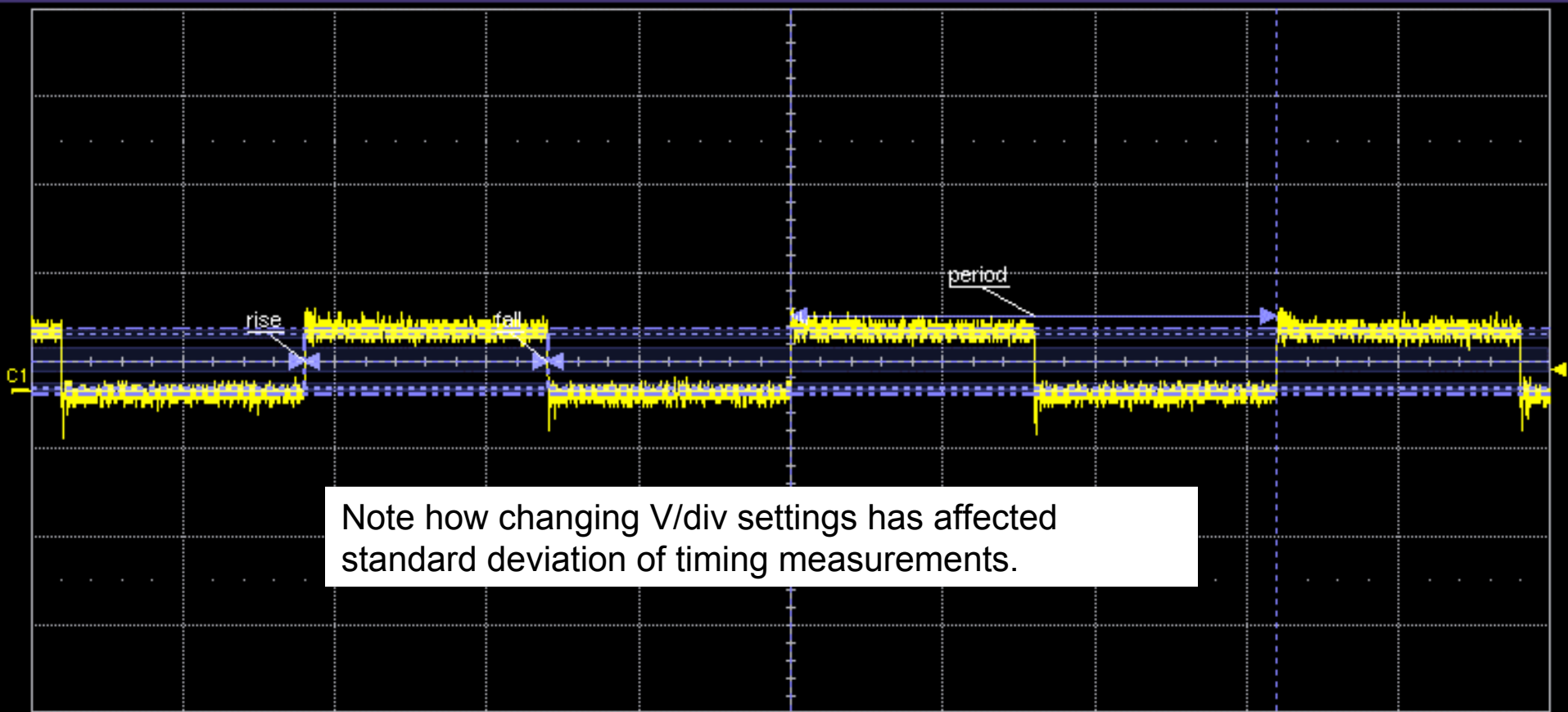
12.5 kS

5.0 GS/s

TriggerC1

Stop1.157 V

EdgePositive



Measure	P1:rise(C1)	P2:fall(C1)	P3:width(C1)	P4:period(C1)	P5:---	P6:---	P7:---	P8:---
value	1.713 ns	1.496 ns	400.192 ns	800.121 ns				
mean	1.62728 ns	1.42165 ns	400.20818 ns	799.99405 ns				
min	978 ps	872 ps	399.781 ns	799.552 ns				
max	2.442 ns	2.181 ns	400.688 ns	800.417 ns				
sdev	214.79 ps	205.31 ps	145.57 ps	134.51 ps				
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3				
status	✓	✓	✓	✓				

C1
DC1M

5.00 V/div
-1.70 V ofst

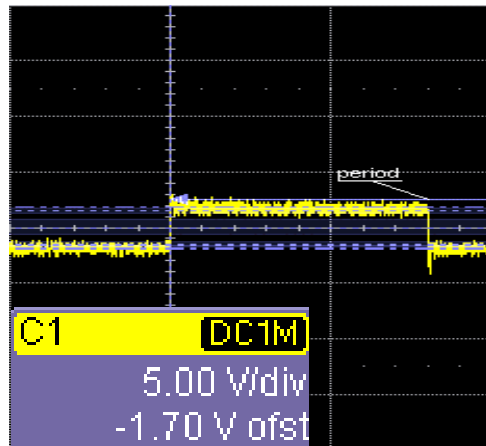
Timebase
0 ns

250 ns/div
12.5 kS
5.0 GS/s

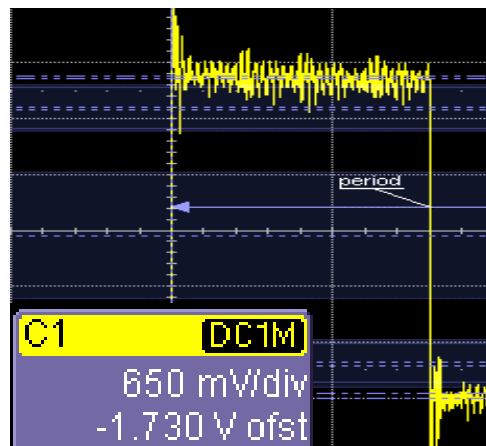
Trigger
C1

Stop
Edge
1.15 V
Positive

Summary: Adjusting the vertical scaling of waveforms also affects the accuracy of timing measurements.

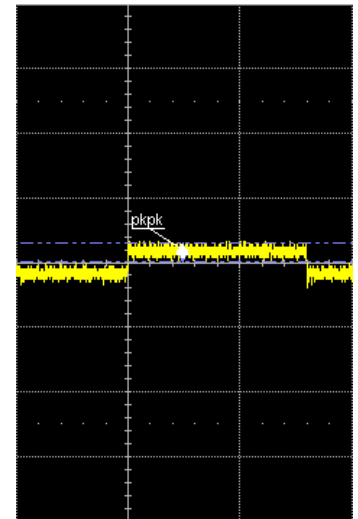
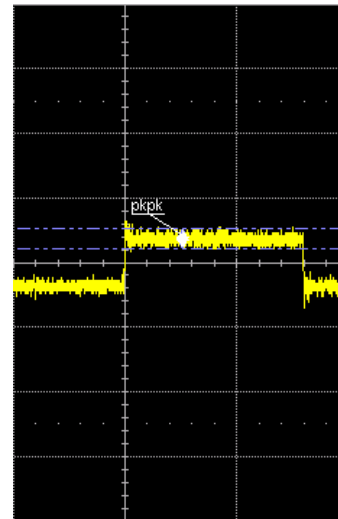
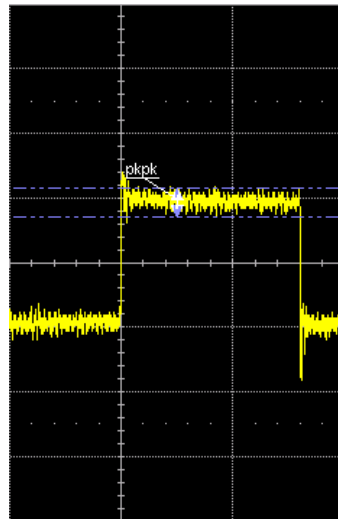
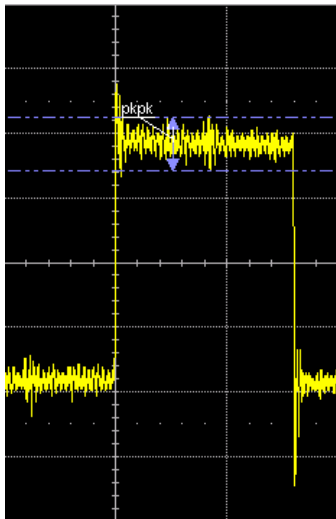
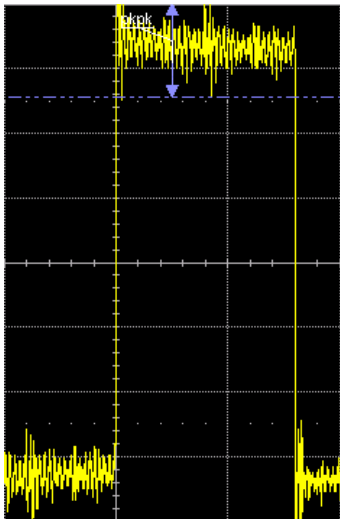


Measure	P1:rise(C1)	P2:fall(C1)	P3:width(C1)	P4:period(C1)
value	1.713 ns	1.496 ns	400.192 ns	800.121 ns
mean	1.62728 ns	1.42165 ns	400.20818 ns	799.99405 ns
min	978 ps	872 ps	399.781 ns	799.552 ns
max	2.442 ns	2.181 ns	400.688 ns	800.417 ns
sdev	214.79 ps	205.31 ps	145.57 ps	134.51 ps
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3



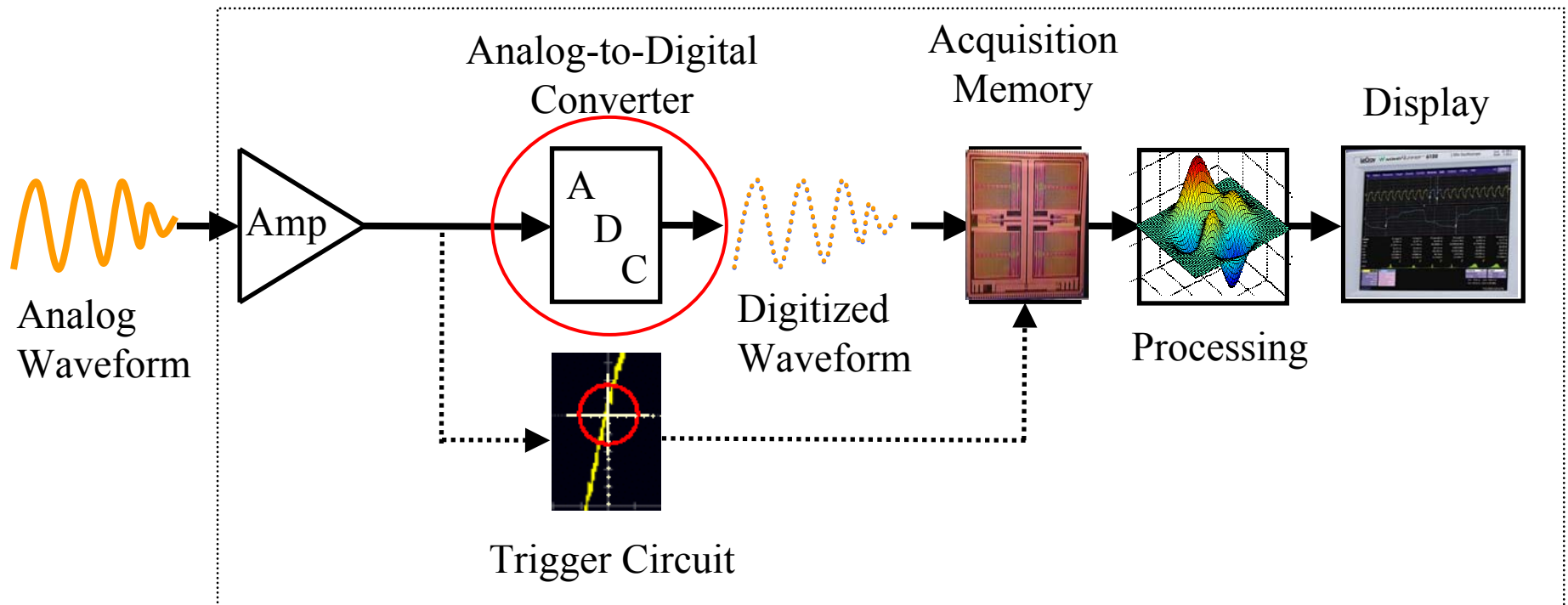
Measure	P1:rise(C1)	P2:fall(C1)	P3:width(C1)	P4:period(C1)
value	1.648 ns	1.335 ns	400.316 ns	800.007 ns
mean	1.63438 ns	1.33528 ns	400.27507 ns	799.99620 ns
min	1.515 ns	1.232 ns	400.211 ns	799.922 ns
max	1.829 ns	1.432 ns	400.340 ns	800.055 ns
sdev	41.08 ps	30.41 ps	21.45 ps	21.12 ps
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3

Why does measurement accuracy vary with changes in V/div setting?



Dynamic Range

When high-performance oscilloscopes acquire an input signal, the output of the amplifier is digitized by an **8-bit** analog-to-digital converter (ADC). The dynamic range of the oscilloscope is the range of signal amplitudes that the ADC can process effectively. The minimum of the range occurs where signal power equals noise power. The maximum of the range occurs at or near full scale where maximum counts of the ADC are used while digitizing the waveform, while distortion is minimized.

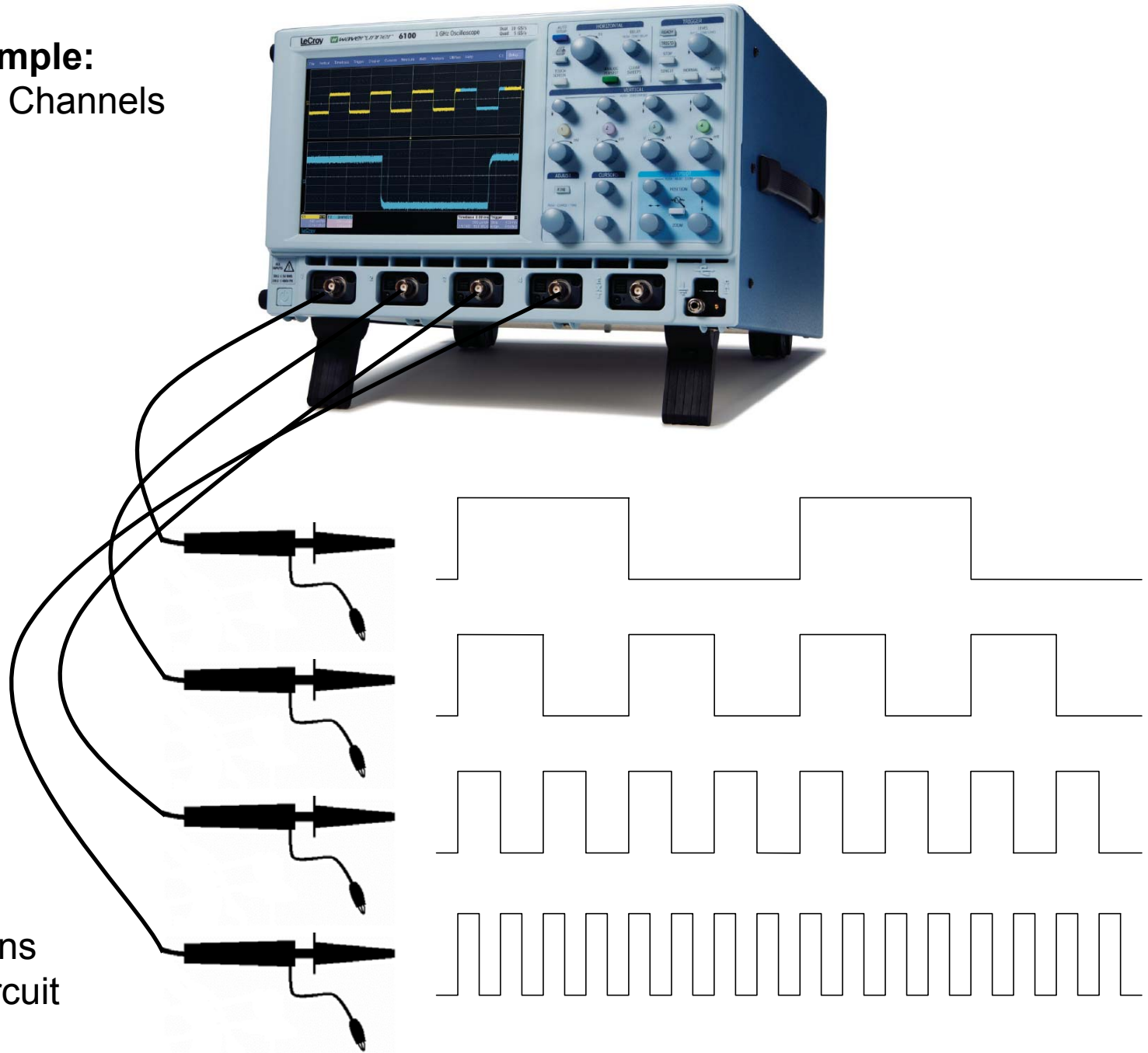


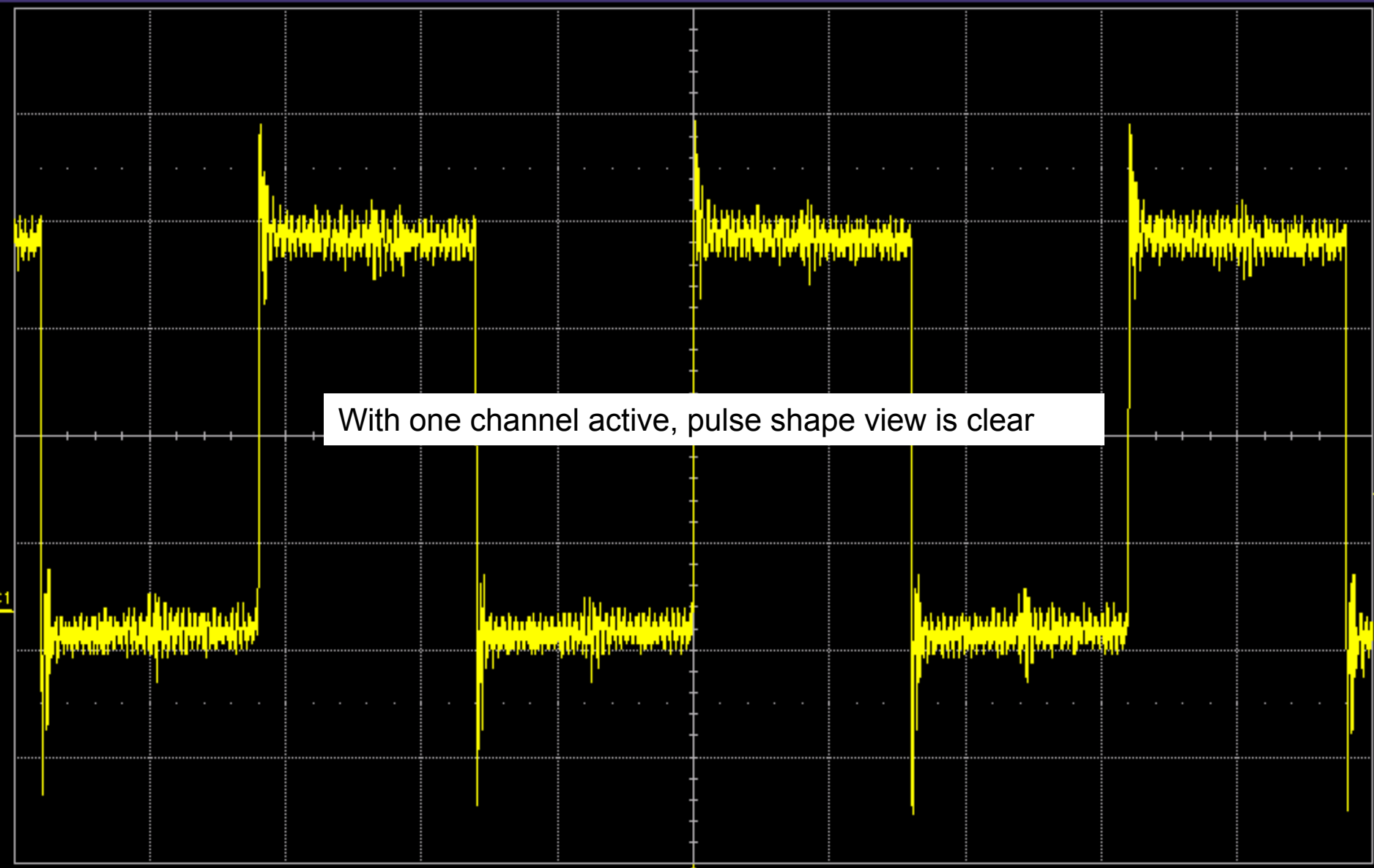
Oscilloscope Block Diagram

Practical Application:

Using Multiple Channels
While Maximizing Dynamic Range

Practical Example: Using Multiple Channels





With one channel active, pulse shape view is clear

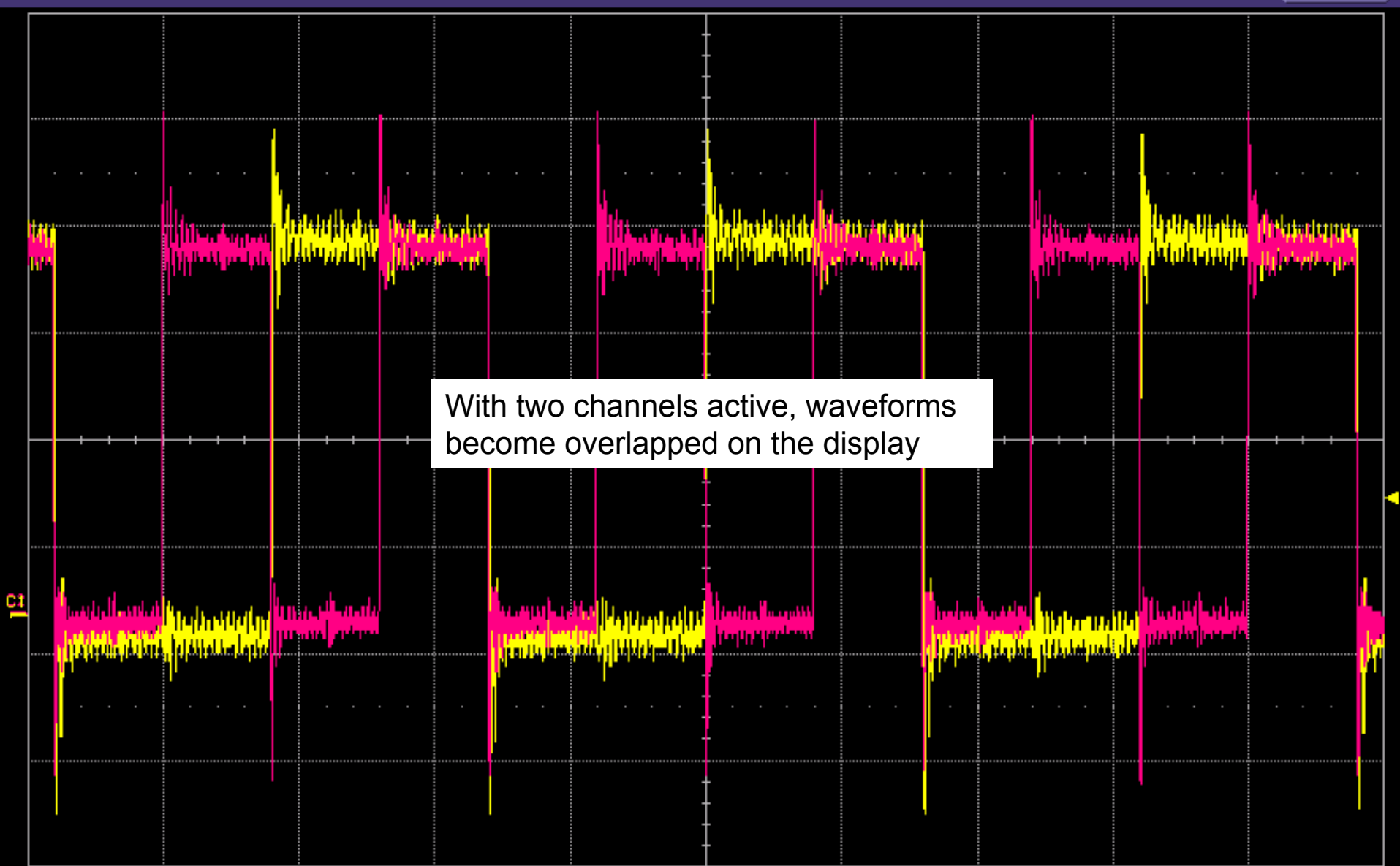
C1

DC1M

1.00 V/div

-1.650 V ofst

Timebase	0 ns	Trigger	C1
	250 ns/div	Auto	1.10 V
12.5 kS	5.0 GS/s	Edge	Positive



C1

DC1M

1.00 V/div

-1.650 V ofst

C2

DC1M

1.00 V/div

-1.620 V ofst

Timebase

0 ns

250 ns/div

12.5 kS

5.0 GS/s

Trigger

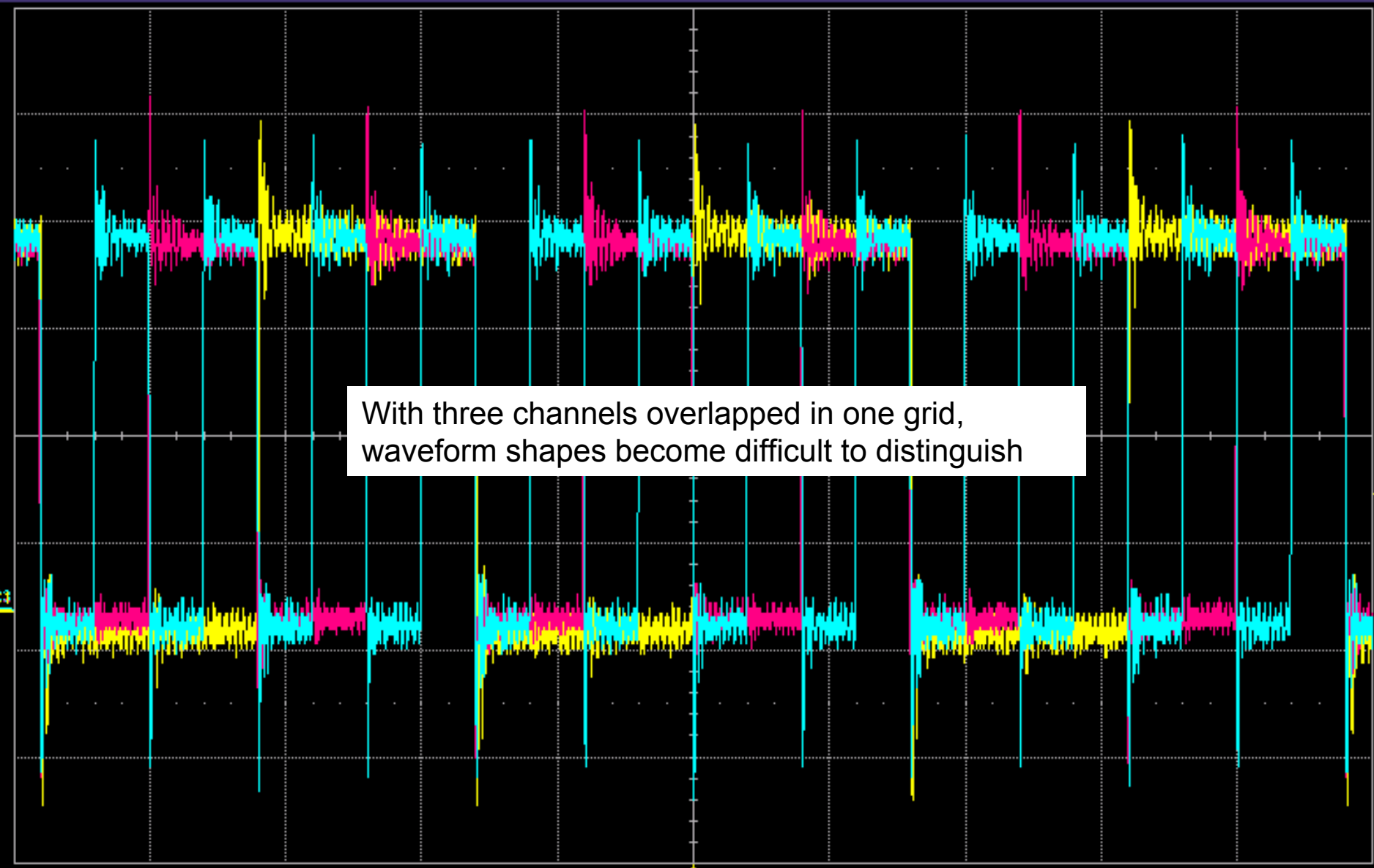
C1

Auto

1.10 V

Edge

Positive



C1

DC1M

1.00 V/div

-1.650 V ofst

C2

DC1M

1.00 V/div

-1.620 V ofst

C3

DC1M

1.00 V/div

-1.620 V ofst

Timebase

0 ns

250 ns/div

12.5 kS

5.0 GS/s

Trigger

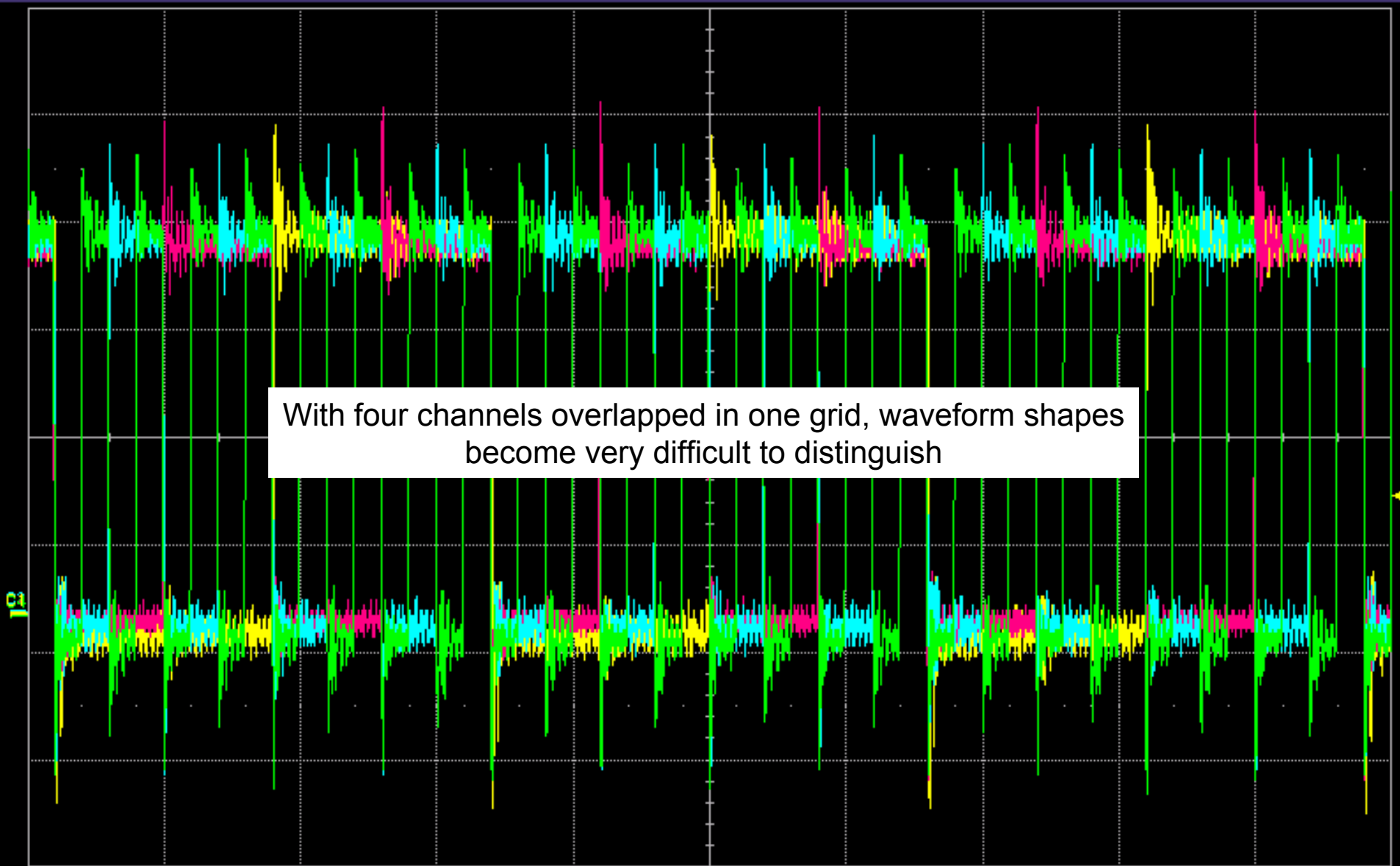
C1

Auto

1.10 V

Edge

Positive



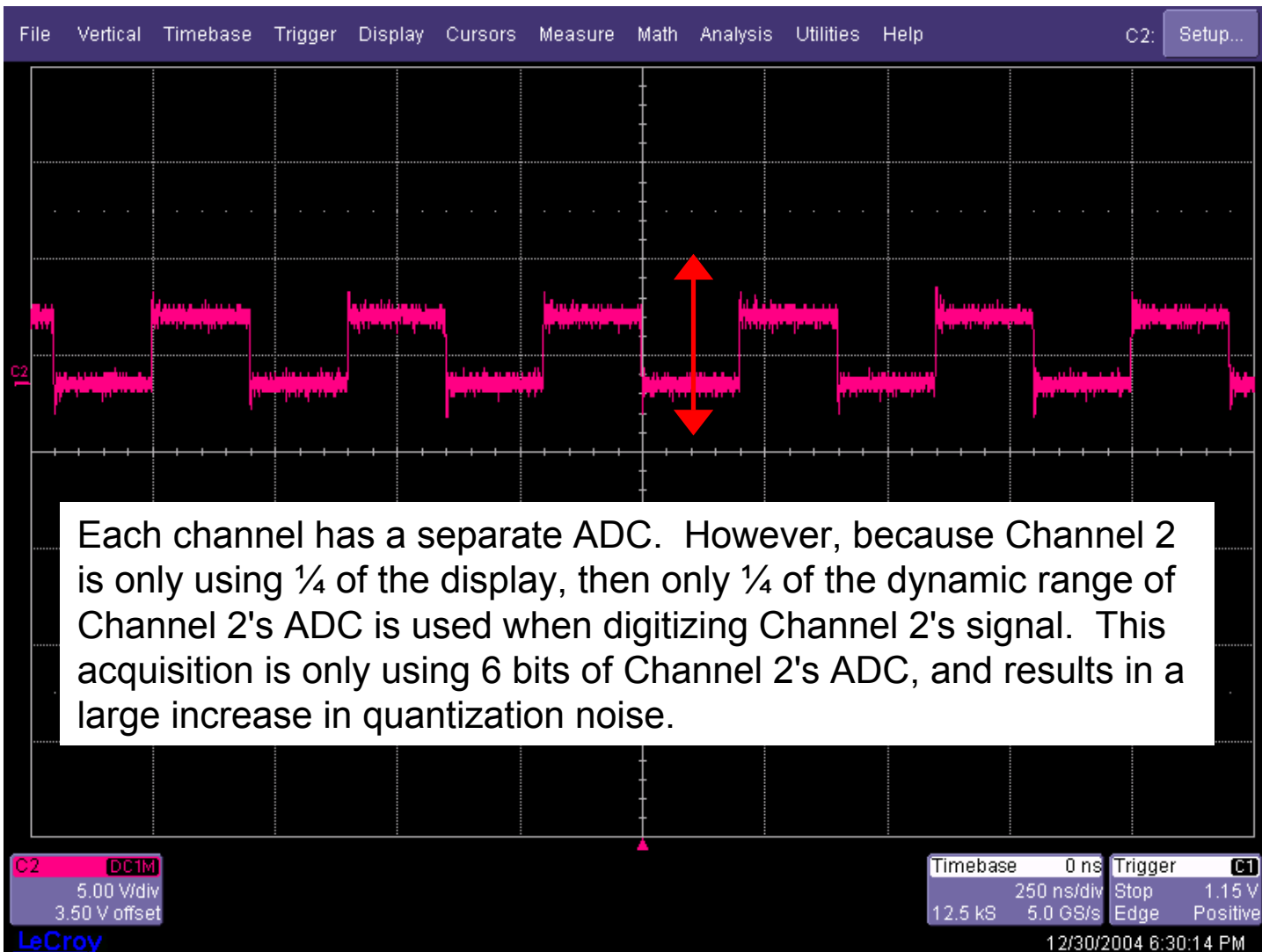
C1	C2	C3	C4	Timebase	Trigger
DC1M	DC1M	DC1M	DC1M	0 ns	C1
1.00 V/div	1.00 V/div	1.00 V/div	1.00 V/div	250 ns/div	Auto 1.10 V
-1.650 V ofst	-1.620 V ofst	-1.620 V ofst	-1.660 V ofst	12.5 kS 5.0 GS/s	Edge Positive





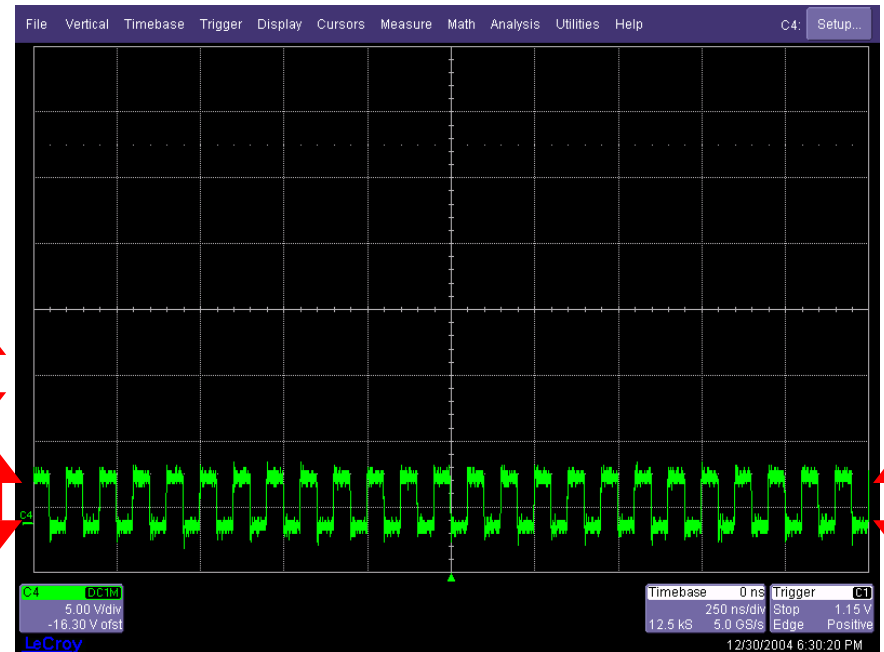
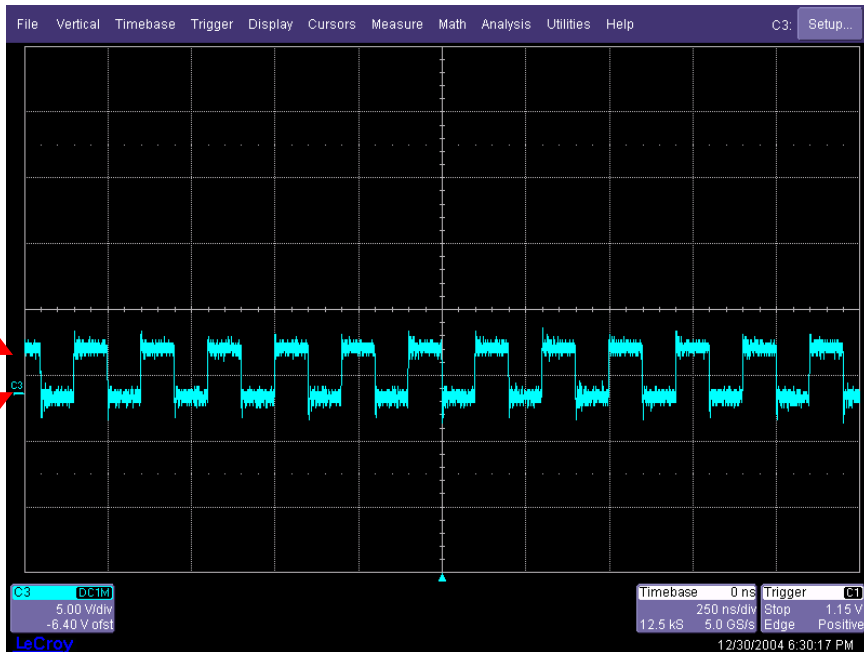
Because Channel 1 is only using $\frac{1}{4}$ of the display, only $\frac{1}{4}$ of the dynamic range of Channel 1's ADC is used when digitizing Channel 1's signal.

An 8-bit ADC has $2^8 = 256$ quantization levels. When using $\frac{1}{4}$ of the dynamic range, only a maximum of 64 of the 256 quantization levels are used for acquiring Channel 1. Using $\frac{1}{4}$ of quantization levels results in a maximum of 6-bit resolution on the acquired channel ($2^6 = 64$). This loss of resolution causes an increase in quantization noise.

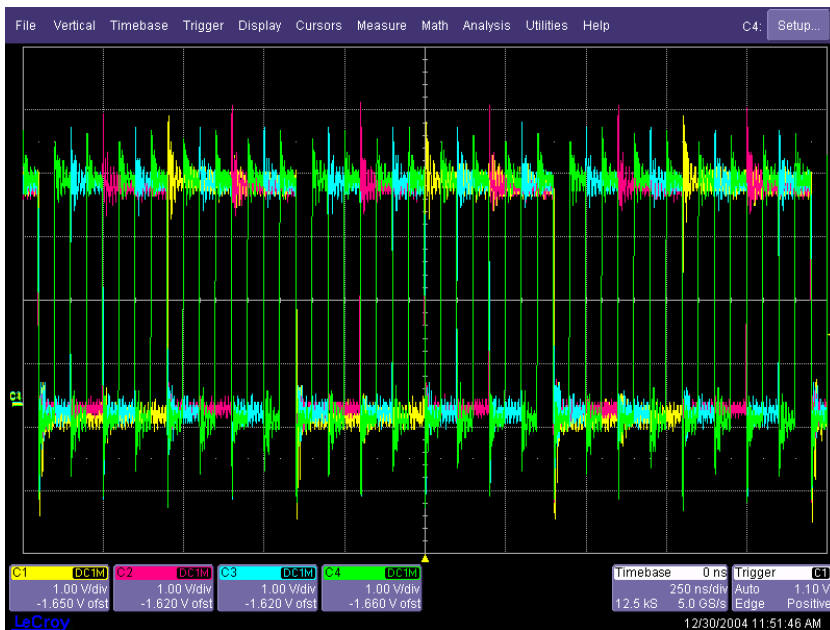


Dynamic Range

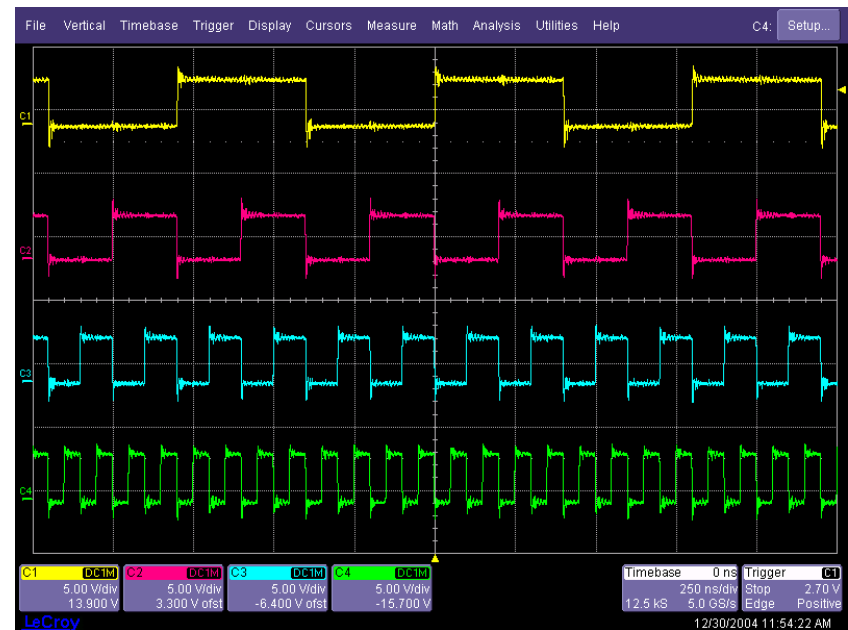
The same applies to Channels 3 and 4. When vertical scaling is reduced to fit four signals into the same grid, then each channel is only using $\frac{1}{4}$ of its dynamic range, which results in loss of vertical resolution and the addition of significant quantization noise.



How can the compromise between maximizing dynamic range, and clearly viewing multiple signals, be resolved?

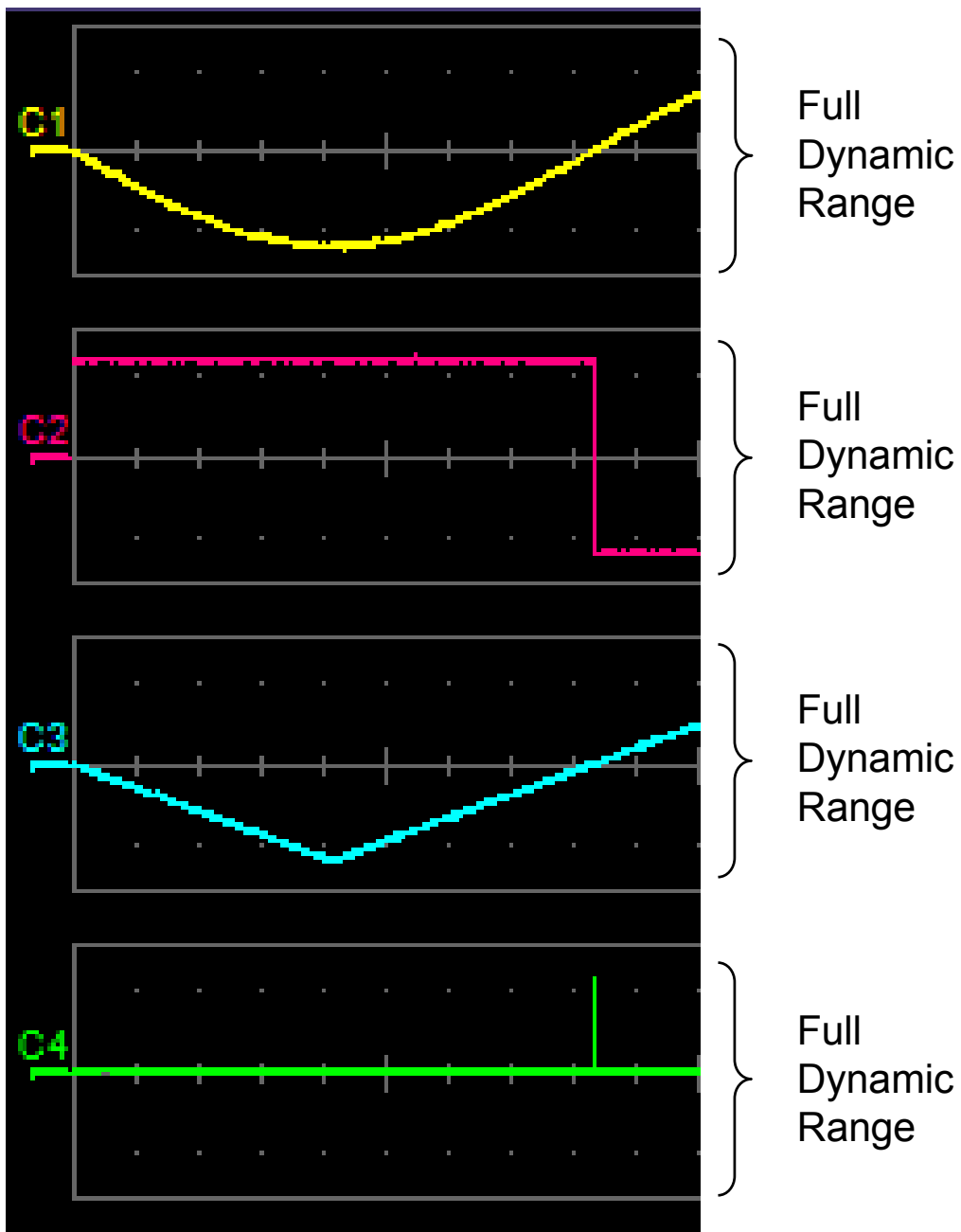


Maximize dynamic range



Clearly view all signals

Solution:
Multigrid Displays



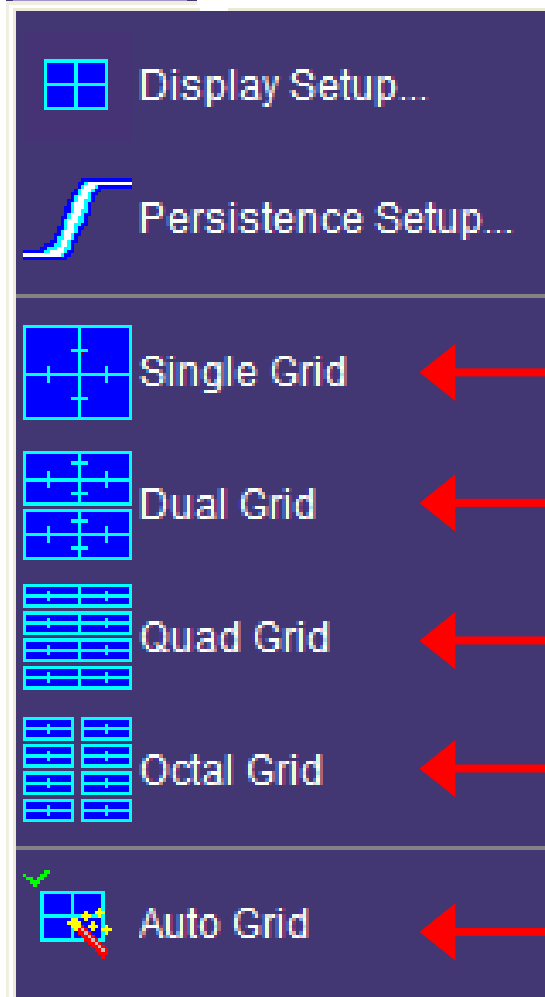
Multigrid Displays

Using Multigrid displays, each channel is contained within a separate grid.

Note that Channel 1 is fully contained within an independent grid that contains the full dynamic range of Channel 1's ADC.

The same is true for Channels 2, 3, and 4. Using Multigrid, dynamic range can be optimized while all signals are clearly viewed.

Display



Selecting Multigrid Displays

Signals are displayed in a single grid

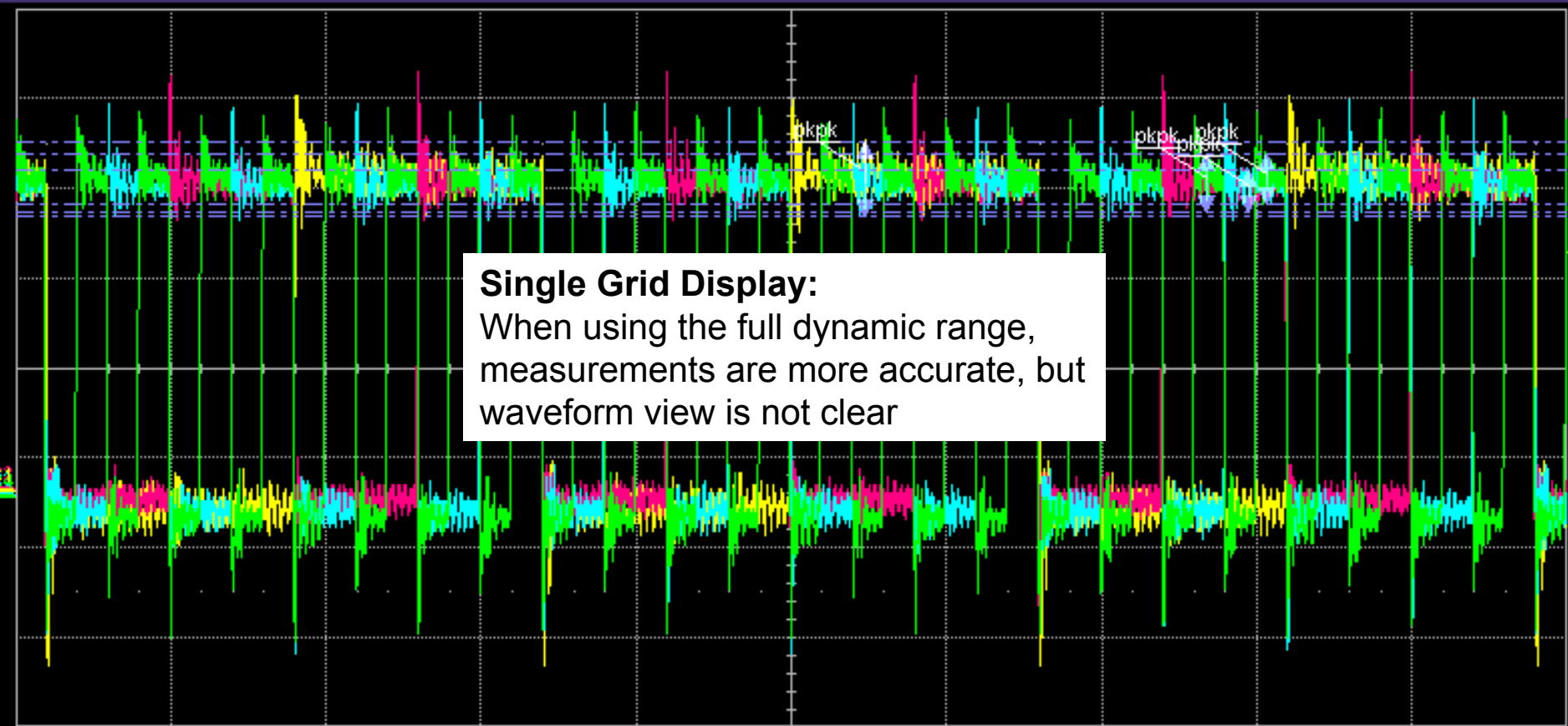
Signals are displayed in two grids, each with full dynamic range

Signals are displayed in four grids, each with full dynamic range

Signals are displayed in eight grids, each with full dynamic range

Autogrid will select the optimal number of grids for the signals displayed

Multigrid displays eliminate the compromise between clearly viewing multiple channels and maximizing dynamic range.



Measure	P1:pkpk(C1)	P2:pkpk(C2)	P3:pkpk(C3)	P4:pkpk(C4)	P5:---	P6:---	P7:---	P8:---
value	840 mV	663 mV	486 mV	575 mV				
mean	857.2 mV	551.7 mV	540.3 mV	510.3 mV				
min	751 mV	442 mV	398 mV	398 mV				
max	1.06 V	663 mV	751 mV	751 mV				
sdev	49.6 mV	41.8 mV	49.5 mV	50.2 mV				
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3				
status	✓	✓	✓	✓				

C1DC1M1.00 V/div-1.370 V ofst

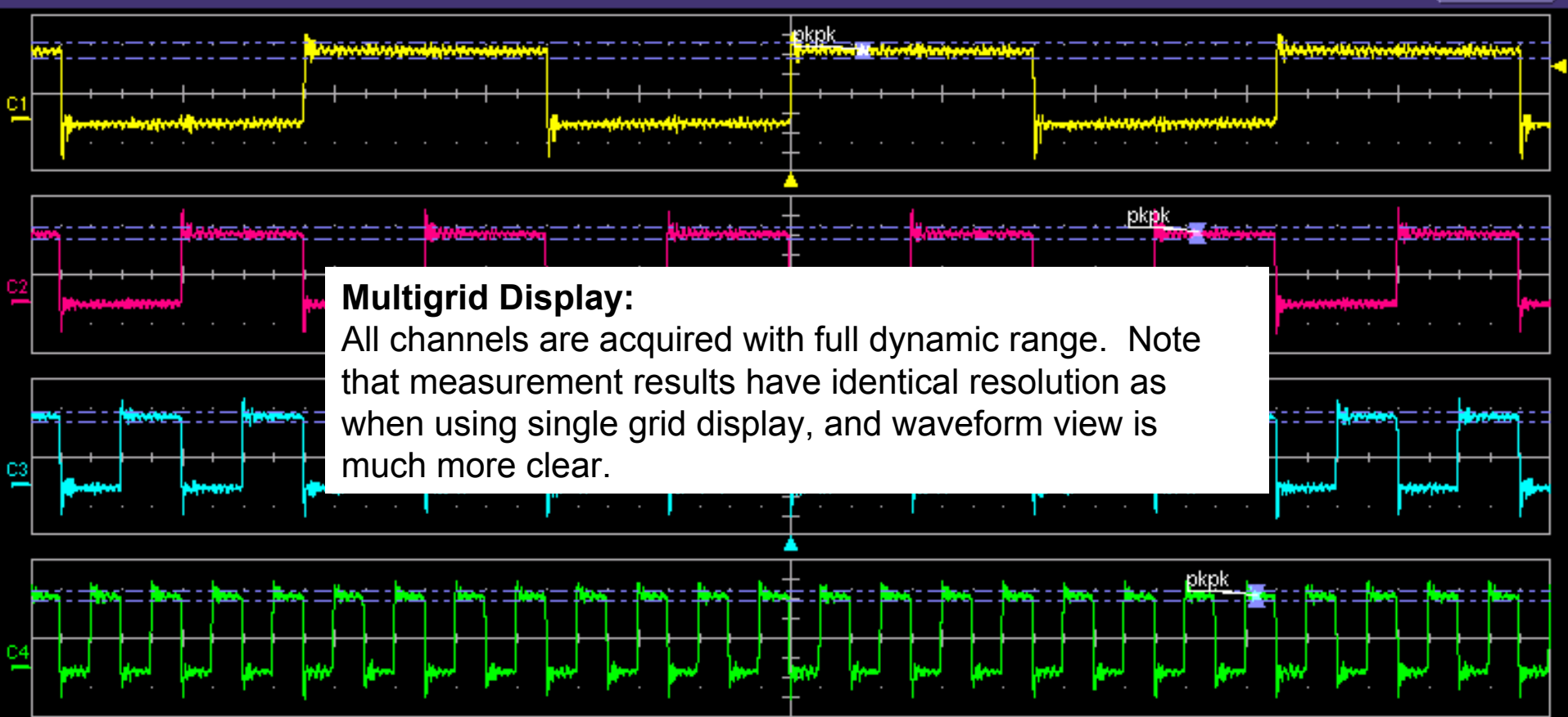
C2DC1M1.00 V/div-1.350 V ofst

C3DC1M1.00 V/div-1.430 V ofst

C4DC1M1.00 V/div-1.440 V ofst

Timebase0 ns250 ns/div12.5 kS

TriggerC1Stop2.64 VEdgePositive



Measure	P1:pkpk(C1)	P2:pkpk(C2)	P3:pkpk(C3)	P4:pkpk(C4)	P5:---	P6:---	P7:---	P8:---
value	796 mV	619 mV	486 mV	486 mV				
mean	887.1 mV	545.4 mV	548.1 mV	505.8 mV				
min	751 mV	442 mV	398 mV	398 mV				
max	1.10 V	707 mV	707 mV	707 mV				
sdev	51.2 mV	39.8 mV	50.6 mV	50.1 mV				
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3				
status	✓	✓	✓	✓				

C1	DC1M	C2	DC1M	C3	DC1M	C4	DC1M
1.00 V/div	1.00 V/div	1.00 V/div	1.00 V/div	1.00 V/div	1.00 V/div	1.00 V/div	1.00 V/div
-1.370 V ofst	-1.350 V ofst	-1.430 V ofst	-1.440 V ofst				

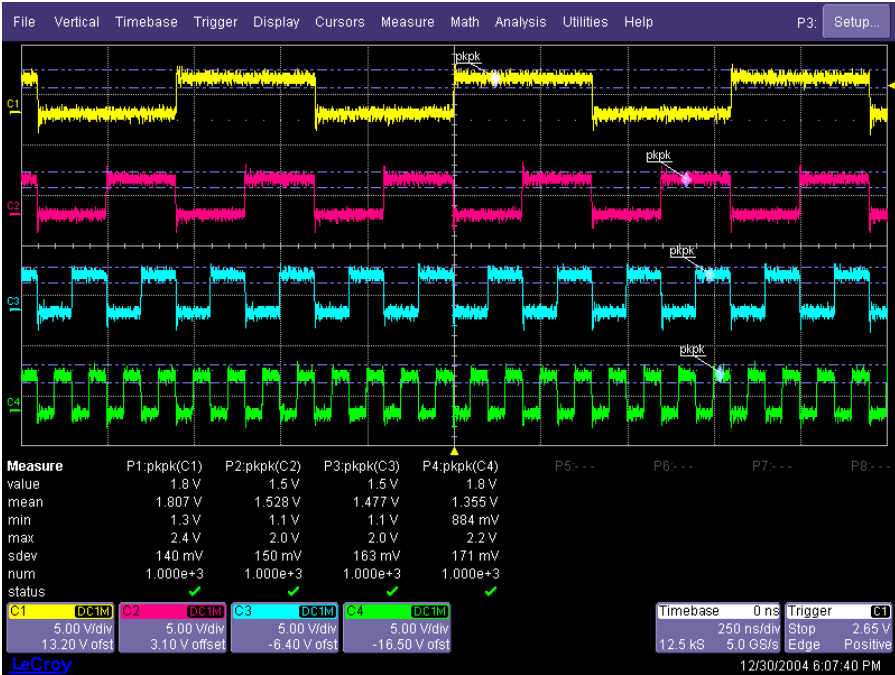
Timebase	0 ns	Trigger	C1
	250 ns/div	Stop	2.64 V
12.5 kS	5.0 GS/s	Edge	Positive

Comparing Single Grid and Multigrid:

Shown below, the difference in noise level is apparent when acquiring the identical signal using Single Grid and Multigrid settings. The dynamic range improvement of Multigrid significantly reduces quantization noise.



Multigrid Display

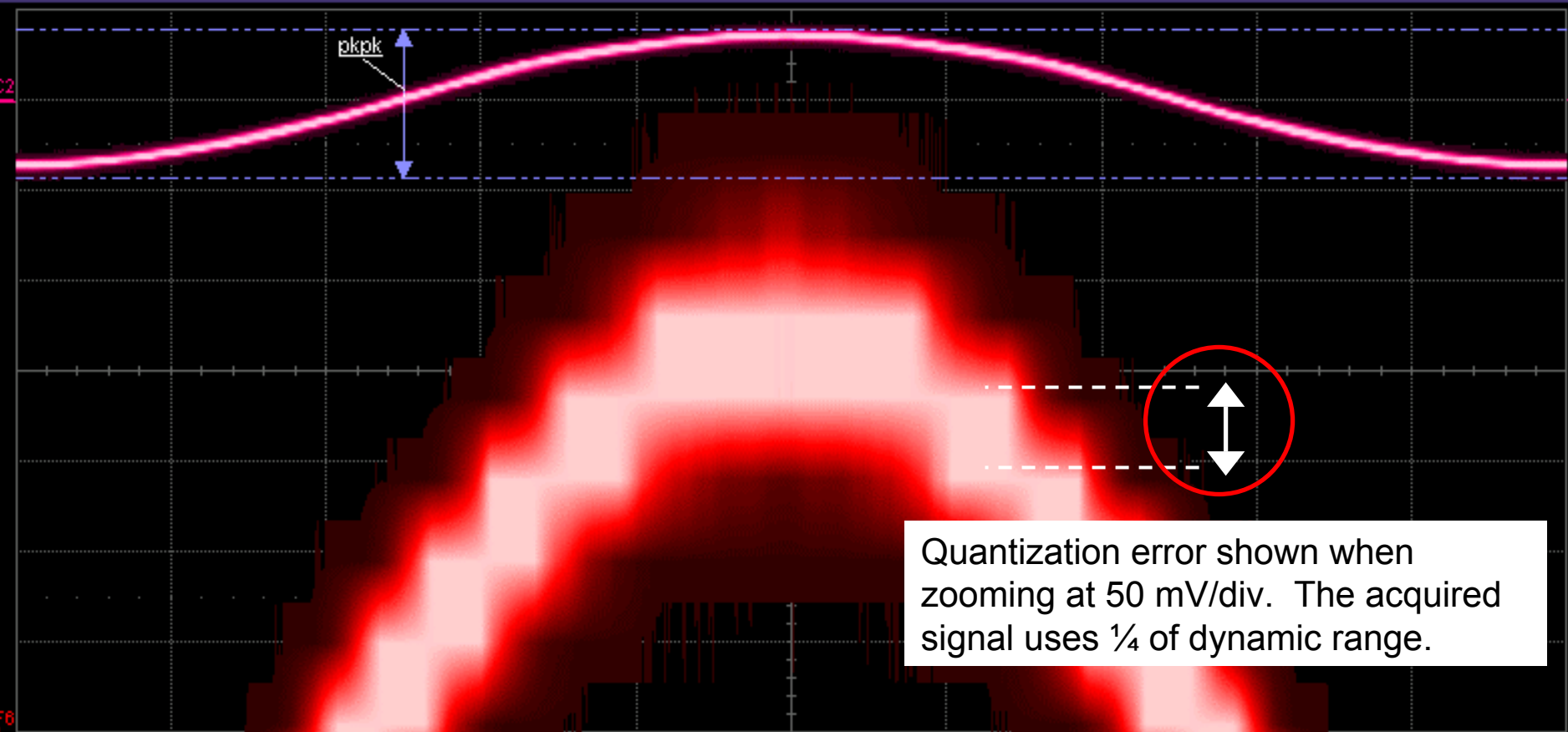


Single grid display

Measure	P1:pkpk(C1)	P2:pkpk(C2)	P3:pkpk(C3)	P4:pkpk(C4)
value	796 mV	619 mV	486 mV	486 mV
mean	887.1 mV	545.4 mV	548.1 mV	505.8 mV
min	751 mV	442 mV	398 mV	398 mV
max	1.10 V	707 mV	707 mV	707 mV
sdev	51.2 mV	39.8 mV	50.6 mV	50.1 mV
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3
status	✓	✓	✓	✓

Measure	P1:pkpk(C1)	P2:pkpk(C2)	P3:pkpk(C3)	P4:pkpk(C4)
value	1.8 V	1.5 V	1.5 V	1.8 V
mean	1.807 V	1.528 V	1.477 V	1.355 V
min	1.3 V	1.1 V	1.1 V	884 mV
max	2.4 V	2.0 V	2.0 V	2.2 V
sdev	140 mV	150 mV	163 mV	171 mV
num	1.000e+3	1.000e+3	1.000e+3	1.000e+3
status	✓	✓	✓	✓

Viewing Quantization Noise



Measure	P1:pkpk(C2)	P2:rise(C2)	P3:width(C2)	P4:---	P5:---	P6:---	P7:---	P8:---
value	1.64 V	21.50836 μ s	49.90600 μ s					
mean	1.6398 V	22.0343972 μ s	49.4335756 μ s					
min	1.59 V	20.46447 μ s	47.42000 μ s					
max	1.72 V	23.09147 μ s	51.07100 μ s					
sdev	20.0 mV	408.0156 ns	903.0980 ns					
num	1.000e+3	1.000e+3	1.000e+3					
status	✓	✓	✓					

C2

DC50

1.00 V/div

2.960 V offset

F6

zoom(C2)

50.0 mV/div

5.00 μ s/div

Timebase

-224.4 μ s

10.0 μ s/div

100 kS

1.0 GS/s

Trigger

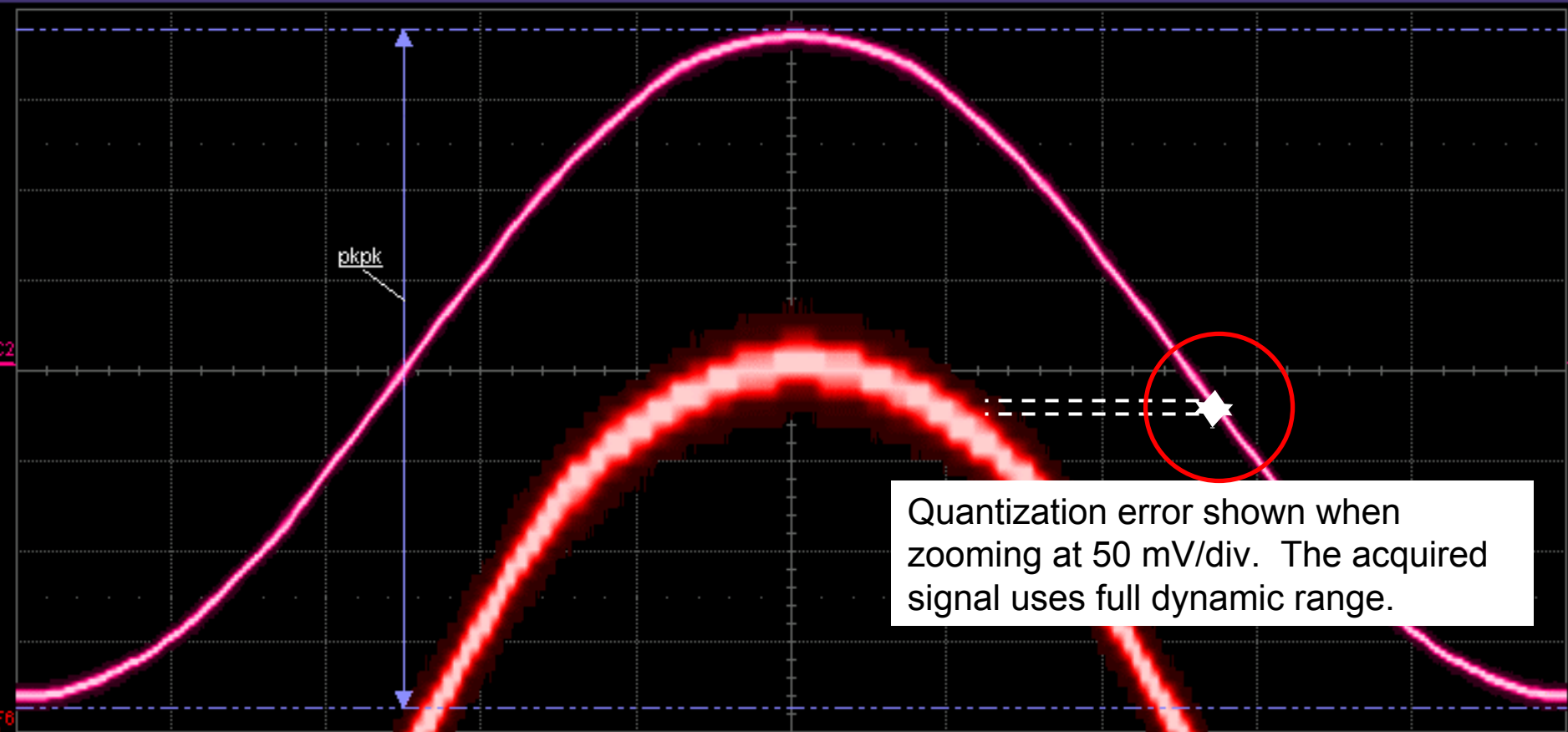
C2

Stop

20 mV

Edge

Positive



Measure	P1:pkpk(C2)	P2:rise(C2)	P3:width(C2)	P4:---	P5:---	P6:---	P7:---	P8:---
value	1.49 V	27.86844 μ s	50.04100 μ s					
mean	1.4939 V	27.7937839 μ s	50.0161130 μ s					
min	1.48 V	27.29021 μ s	49.71400 μ s					
max	1.50 V	28.08711 μ s	50.35300 μ s					
sdev	4.6 mV	120.7061 ns	89.6065 ns					
num	1.000e+3	1.000e+3	1.000e+3					
status	✓	✓	✓					

C2

DC50

200 mV/div

15.0 mV offset

F6

zoom(C2)

50.0 mV/div

5.00 μ s/div

Timebase

-224.4 μ s

10.0 μ s/div

100 kS

1.0 GS/s

Trigger

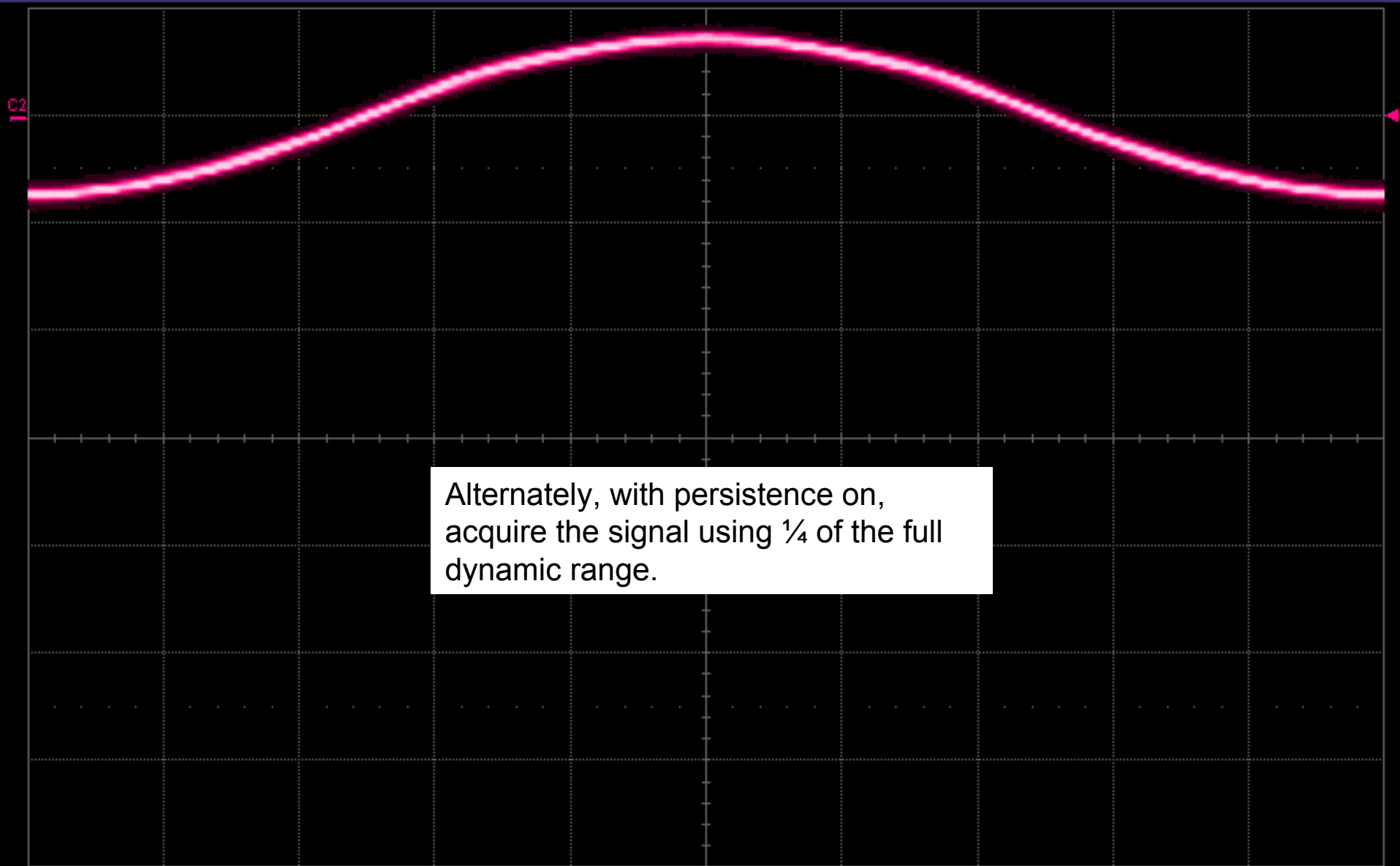
C2

Stop

4 mV

Edge

Positive



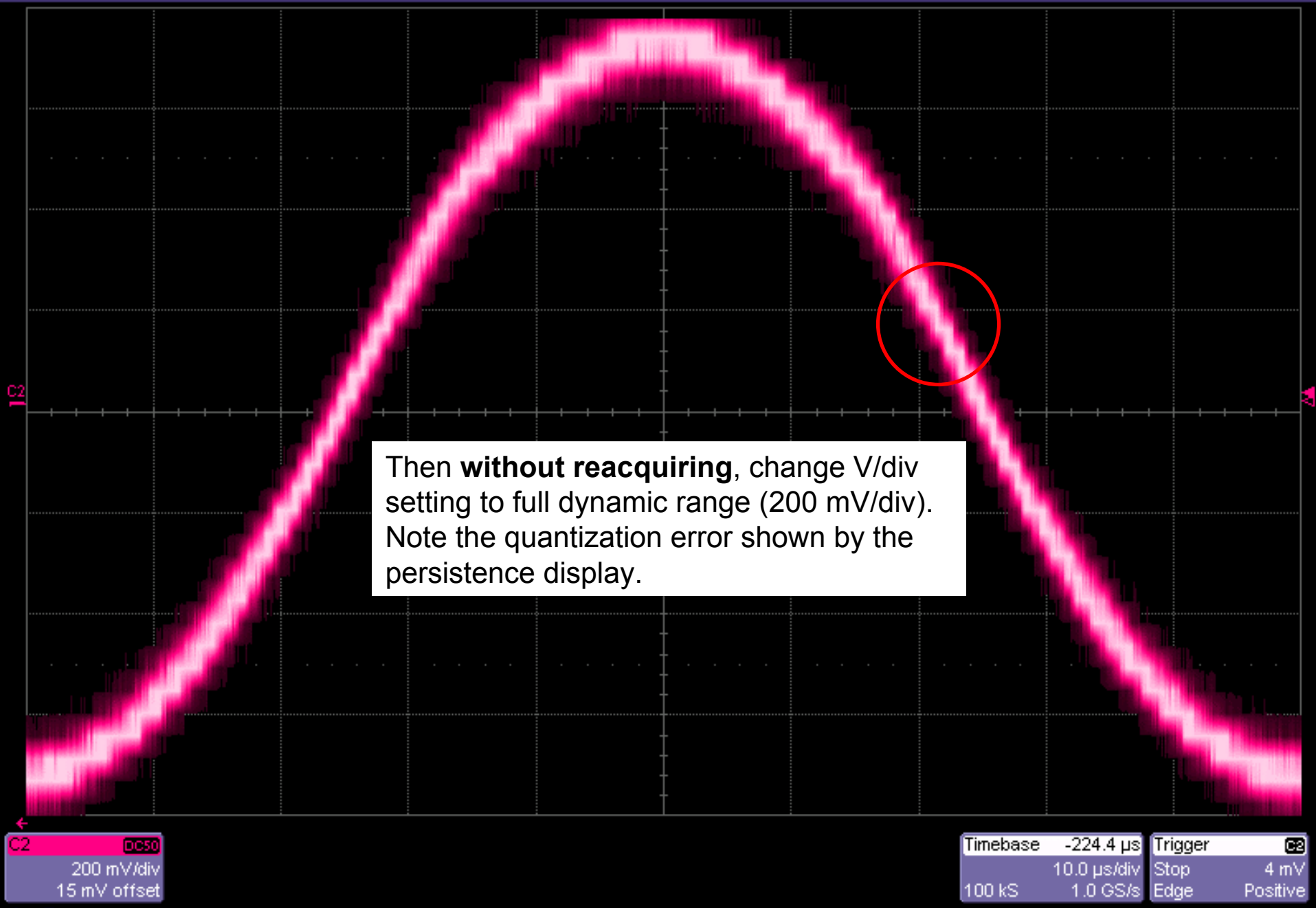
C2

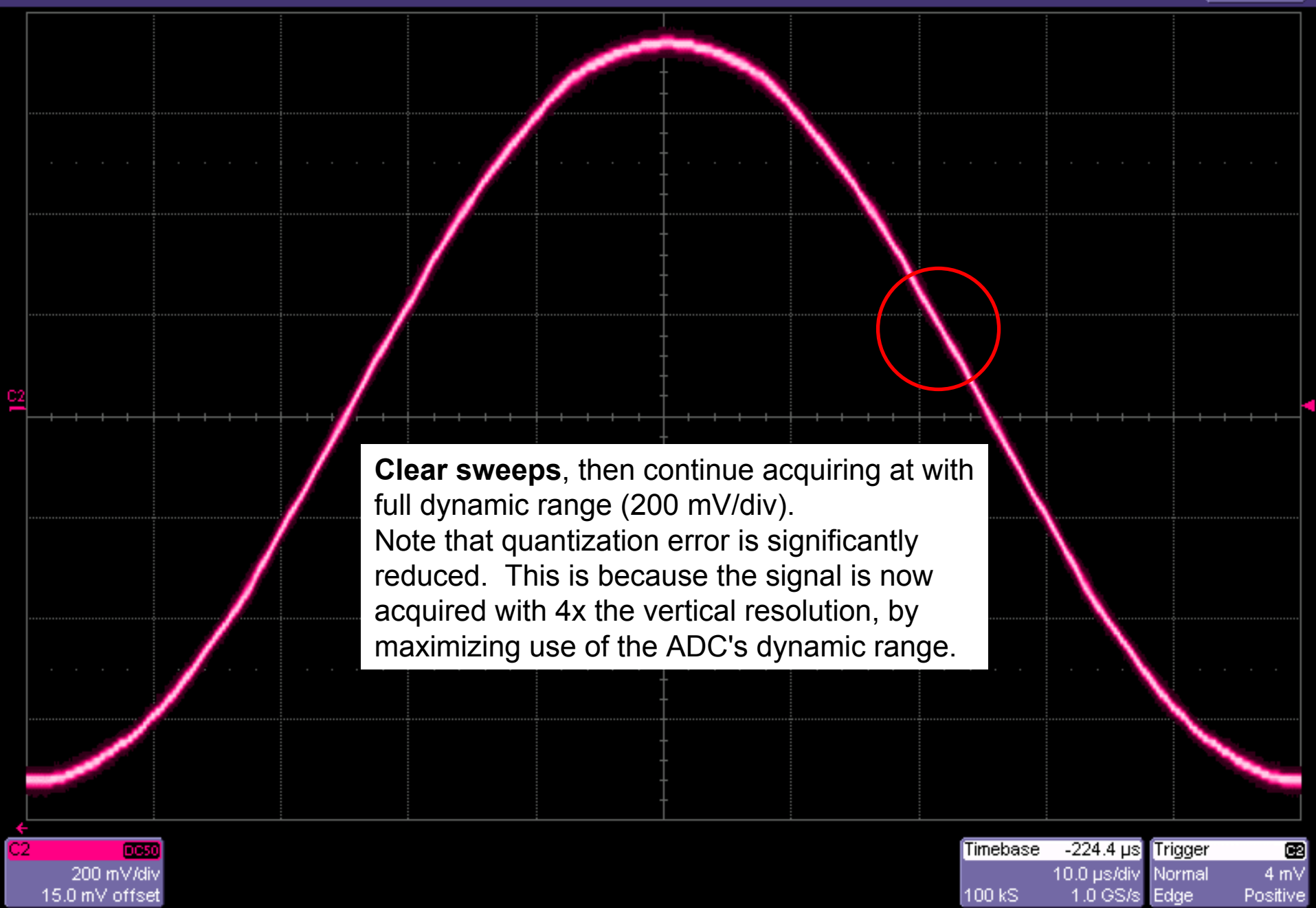
DC50

990 mV/div

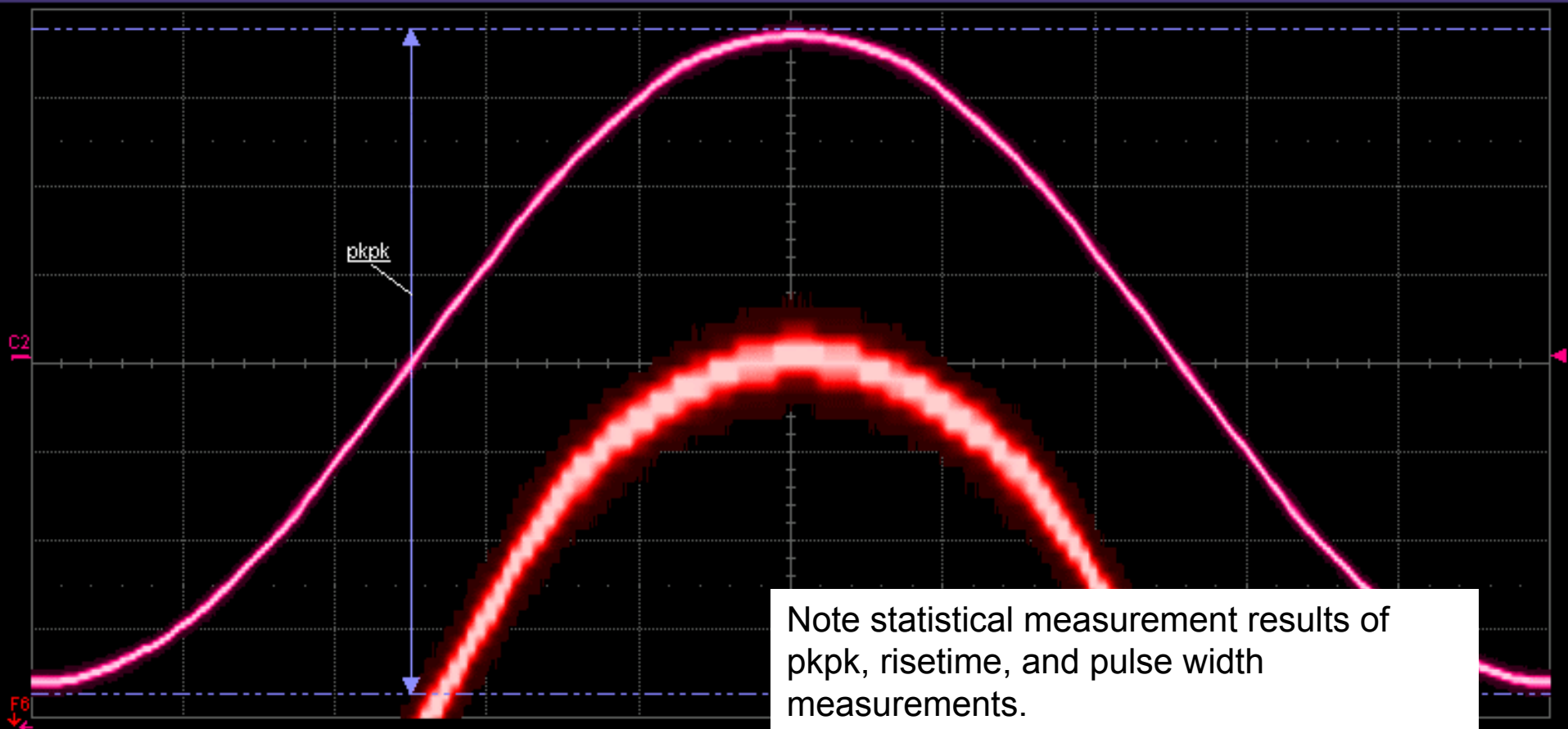
2.940 V offset

Timebase	-224.4 μ s	Trigger	C2
	10.0 μ s/div	Stop	20 mV
100 kS	1.0 GS/s	Edge	Positive





Clear sweeps, then continue acquiring at with full dynamic range (200 mV/div). Note that quantization error is significantly reduced. This is because the signal is now acquired with 4x the vertical resolution, by maximizing use of the ADC's dynamic range.



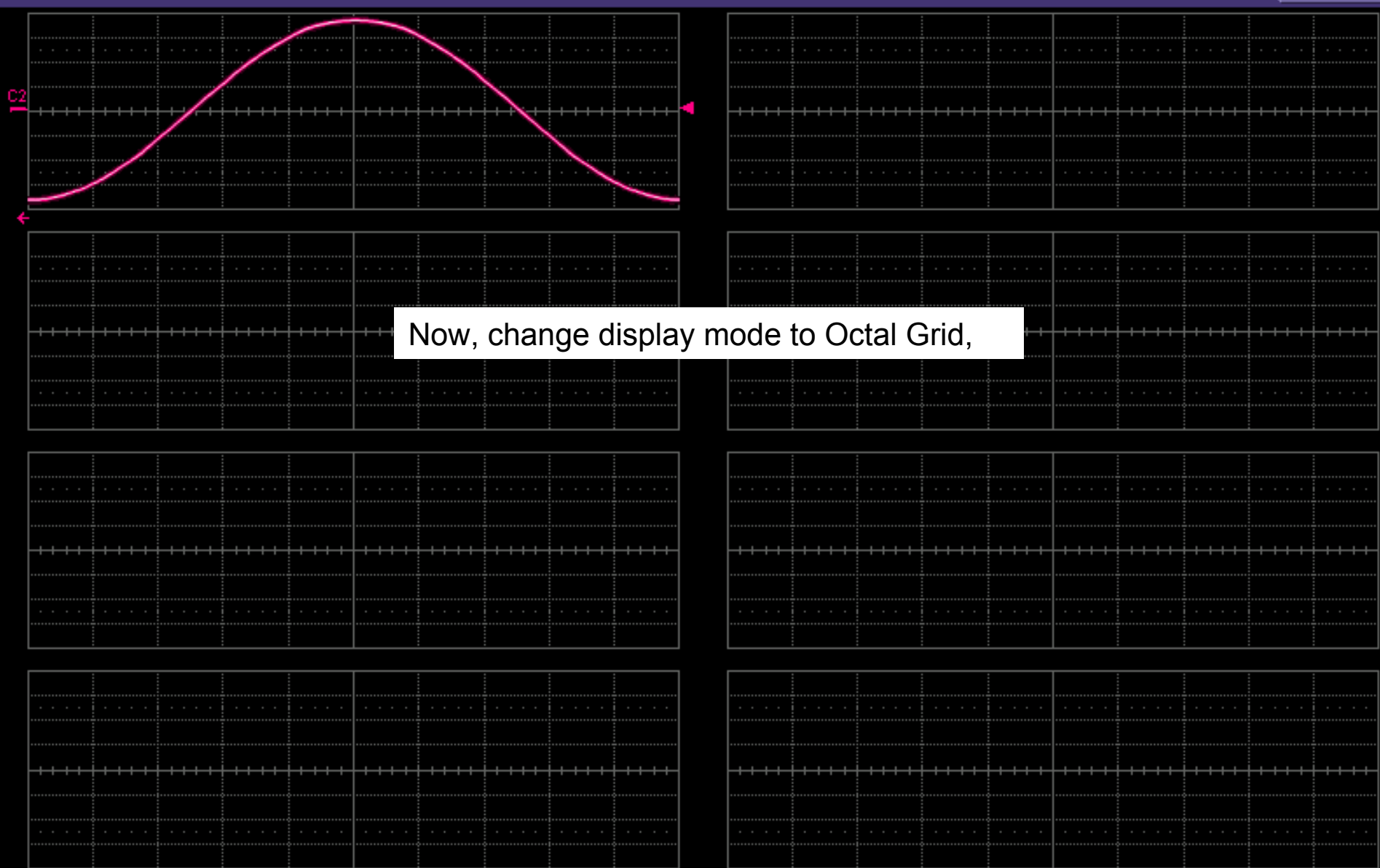
Measure	P1:pkpk(C2)	P2:rise(C2)	P3:width(C2)	P4:---	P5:---	P6:---	P7:---	P8:---
value	1.49 V	27.86844 μ s	50.04100 μ s					
mean	1.4939 V	27.7937839 μ s	50.0161130 μ s					
min	1.48 V	27.29021 μ s	49.71400 μ s					
max	1.50 V	28.08711 μ s	50.35300 μ s					
sdev	4.6 mV	120.7061 ns	89.6065 ns					
num	1.000e+3	1.000e+3	1.000e+3					
status	✓	✓	✓					

C2
DC50
200 mV/div
15.0 mV offset

F6
zoom(C2)
50.0 mV/div
5.00 μ s/div

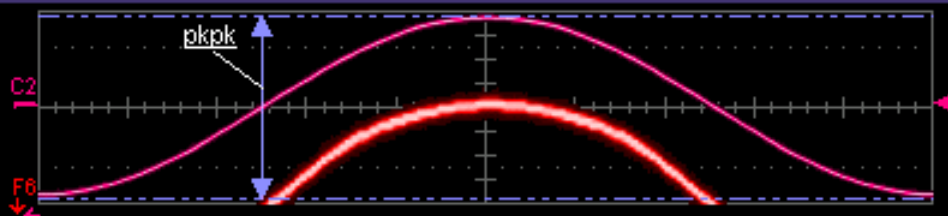
Timebase
-224.4 μ s
100 ks
10.0 μ s/div
1.0 GS/s

Trigger
C2
Stop
Edge
4 mV
Positive



C2 DC50
200 mV/div
15.0 mV offset

Timebase	-224.4 μ s	Trigger	C2
	10.0 μ s/div	Stop	4 mV
100 kS	1.0 GS/s	Edge	Positive



Measurement result accuracy remains identical when using Octal Grid. In both cases, dynamic range and vertical resolution are maximized.

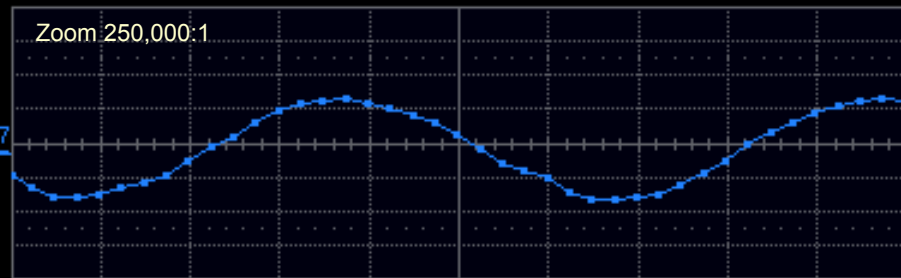
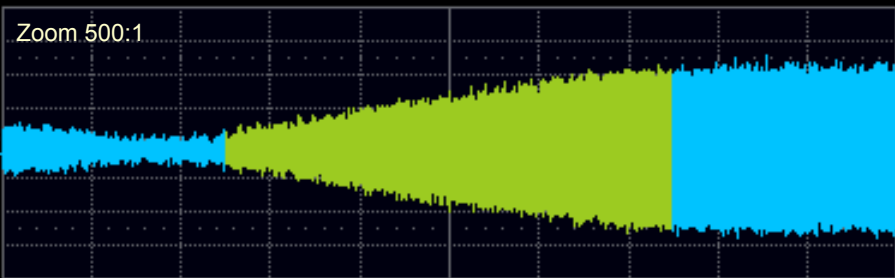
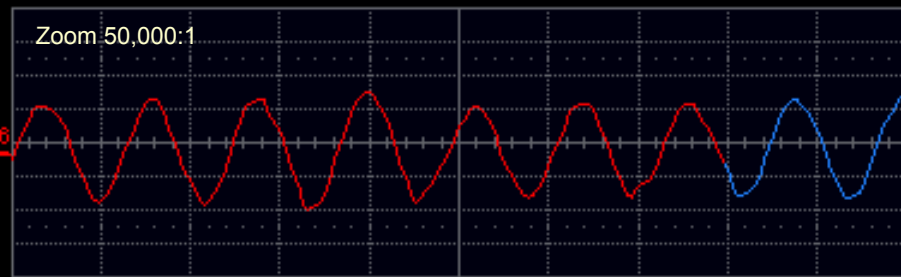
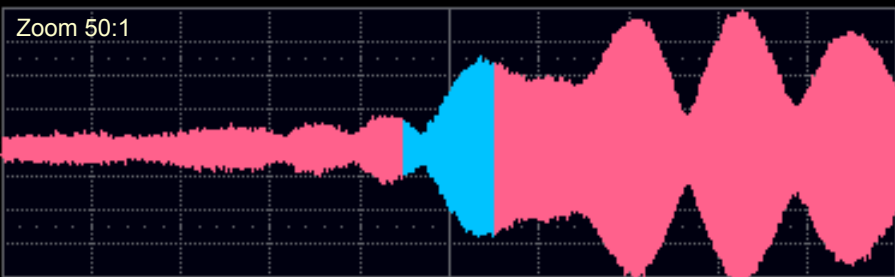
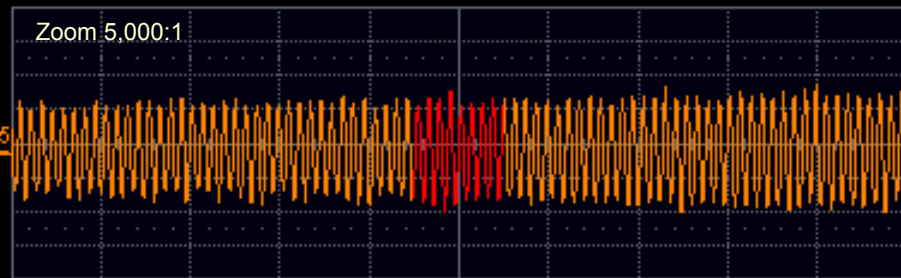
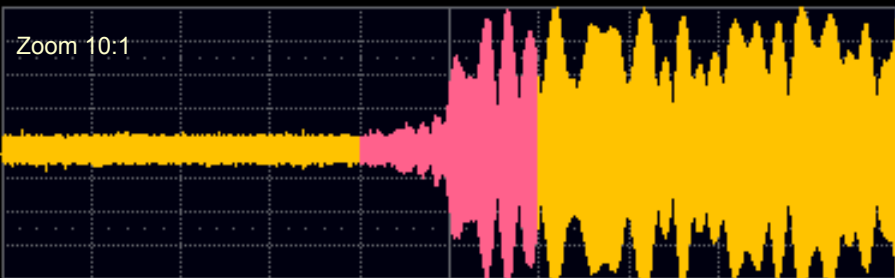
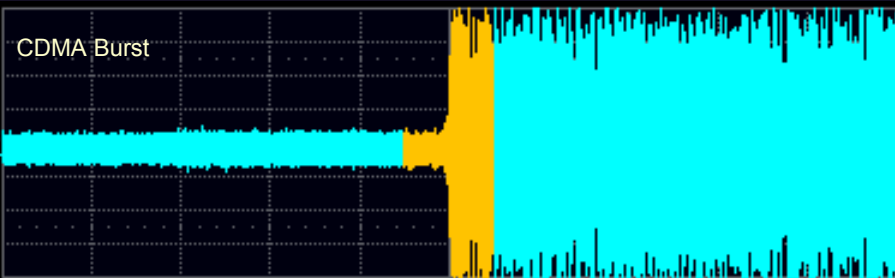
Measure	P1:pkpk(C2)	P2:rise(C2)	P3:width(C2)	P4:---	P5:---	P6:---	P7:---	P8:---
value	1.49 V	27.88913 μ s	49.90000 μ s					
mean	1.4934 V	27.8139441 μ s	50.0215980 μ s					
min	1.48 V	27.49650 μ s	49.74400 μ s					
max	1.51 V	28.14141 μ s	50.37700 μ s					
sdev	4.6 mV	109.1840 ns	90.8688 ns					
num	1.000e+3	1.000e+3	1.000e+3					
status	✓	✓	✓					

C2
DC50
200 mV/div
15.0 mV offset

F6
zoom(C2)
50.0 mV/div
5.00 μ s/div

Timebase
-224.4 μ s
100 kS

Trigger
C2
Stop
Edge
4 mV
Positive

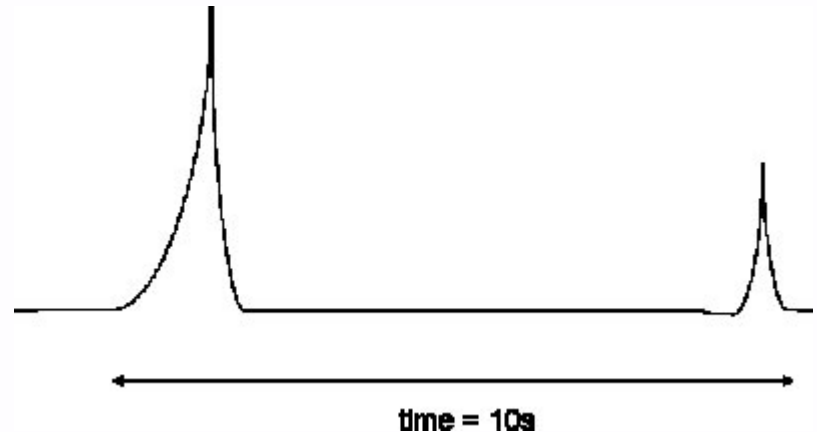


C3	F1 zoom(C3)	F2 zoom(F1)	F3 zoom(F2)	F4 zoom(F3)	F5 zoom(F4)	F6 zoom(F5)	F7 zoom(F6)	Timebase	0 μ s	Trigger	Stopped
10.0 mV	10.0 mV	10.0 mV	10.0 mV	10.0 mV	10.0 mV	10.0 mV	10.0 mV	50.0 μ s/div	DC	C3	13.3 mV
-3 mV	5.00 μ s	1.000 μ s	100 ns	50.0 ns	10.0 ns	1.00 ns	200 ps	10.0 MS	20 GS/s	Edge	Positive

Reference Slides

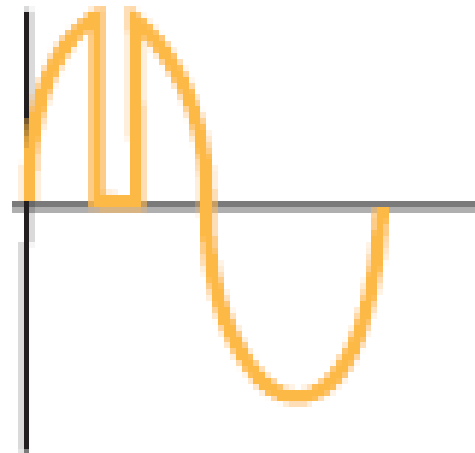
Transient Testing (Automotive)

- Pulse Characteristics
 - Capacitive load dump
 - Inductive kickback/spike (back EMF from motor turn off)
- Measurement Needs
 - Capture Time – longer the better:
 - Relay bounce (μs to ms)
 - Transient time
 - μs (motor)
 - ns (FET switch)
 - Measure 50-100 MHz transient
 - 10s capture = 2Mpts at 100 MHz Sample Rate



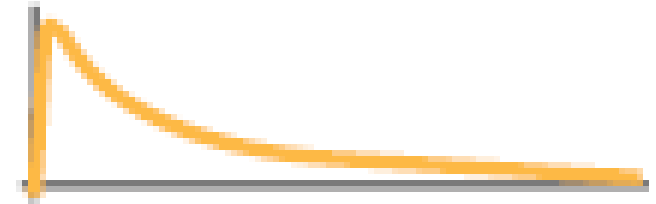
Dropout and Interrupt Testing

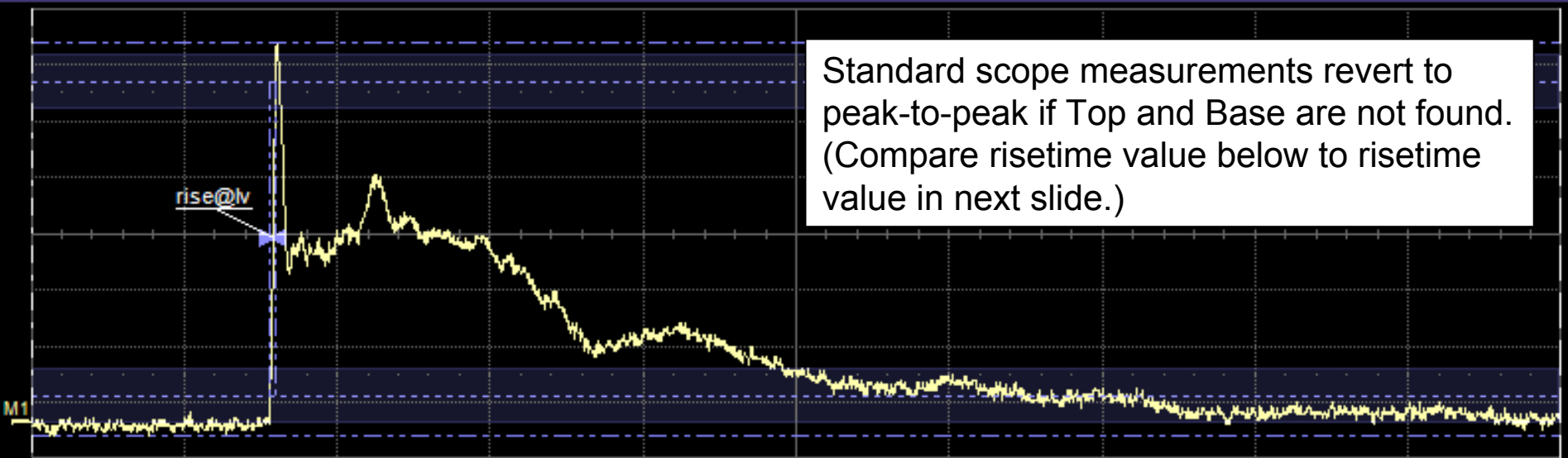
- Monitor AC or DC voltage line with oscilloscope during EMC testing
- Verify that dropout or interrupt occurred, and that device under test was unaffected



Surge Testing

- Pulse Characteristics
 - T_{rise} = typically 1.2 to 10 μs
 - T_{fall} = typically 20 to 10,000 μs
- Measurement Needs
 - Capture a Single Pulse
 - Measure one pulse, verify rise and fall time





Measure	P1:rise@lv(M1)	P2:---	P3:---	P4:---	P5:---	P6:---	P7:---	P8:---
value	896 ps							
status								

M1

50 V/div

25.0 ns/div

Timebase	0 ns	Trigger	C1
	50.0 ns/div	Stop	0.0 mV
5.00 kS	10 GS/s	Edge	Positive

Measure P1 P2 P3 P4 P5 P6 P7 P8

☒ On

Type

measure on waveforms

math on parameters

advanced web edit

Source1

M1

Measure

Rise@level

Summary

rise@lv(M1)

Actions for P1

Histogram

Trend

Track

Help

Markers

Always On

☒

Detailed

Rise at level Gate Accept Close

Slew Rate for % or absolute levels of rising or falling edges.

Levels are

Percent

High percent

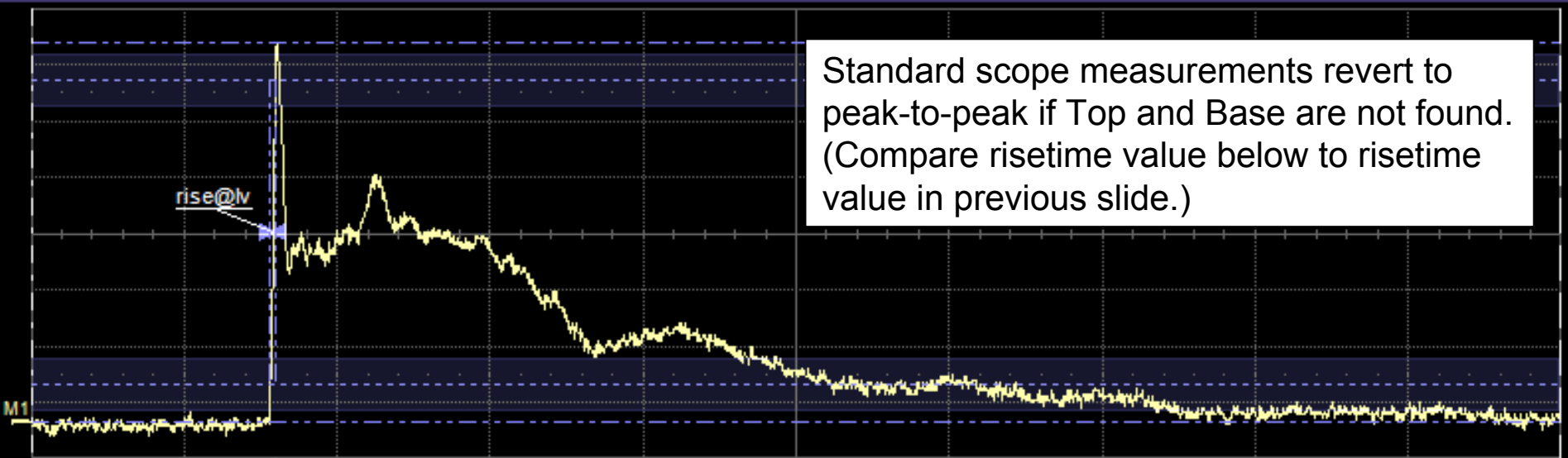
90 %

Set Levels to 10% and 90%

Set Levels to 20% and 80%

Low percent

10 %



Measure value status

P1:rise@lv(M1)
854 ps

P2: --- P3: --- P4: --- P5: --- P6: --- P7: --- P8: ---

M1

50 V/div
25.0 ns/div

Timebase 0 ns
50.0 ns/div
5.00 kS

Trigger C1
Stop 0.0 mV
Edge Positive

Measure P1 P2 P3 P4 P5 P6 P7 P8

☒ On

Type

measure on waveforms

math on parameters

advanced web edit

Source1
M1

Measure
Rise@level

Summary
rise@lv(M1)

Actions for P1

Histogram

Trend

Track

Help

Markers

Detailed

Always On

Rise at level Gate Accept Close

Slew Rate for % or absolute levels of rising or falling edges.

Levels are

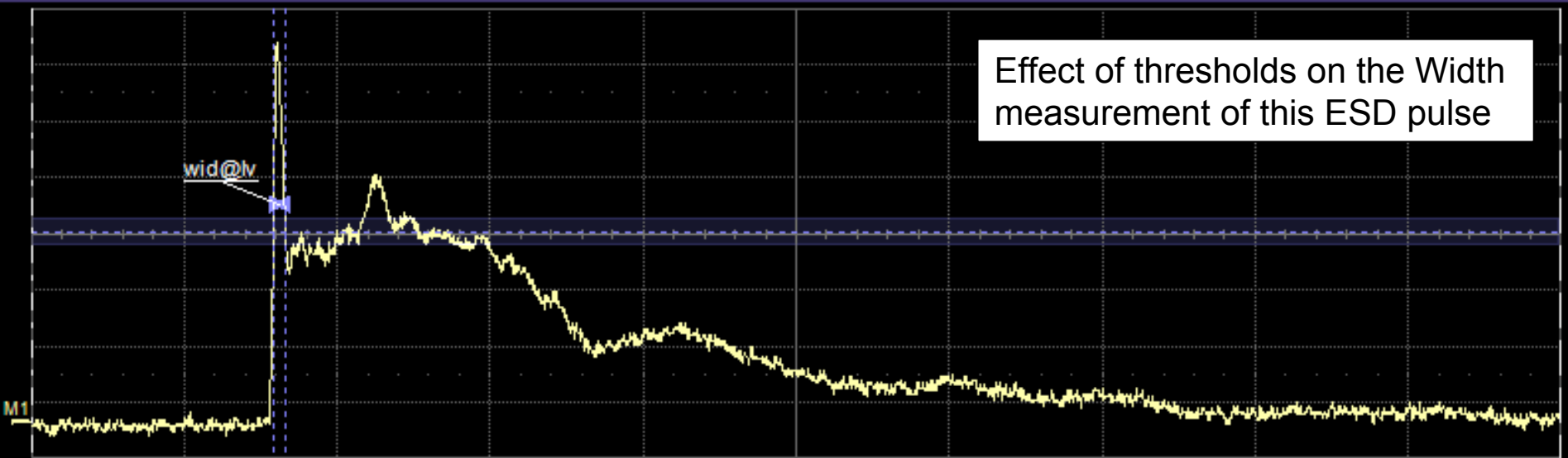
% 0-Max

High percent
90 %

Set Levels to 10% and 90%

Set Levels to 20% and 80%

Low percent
10 %



Effect of thresholds on the Width measurement of this ESD pulse

Measure
value
status

P1:wid@lv(M1)
13.246 ns
✓

M1
50 V/div
25.0 ns/div

Timebase 0 ns
50.0 ns/div
5.00 kS
Trigger C1
Stop 0.0 mV
Edge Positive

Measure P1 P2 P3 P4 P5 P6 P7 P8

☒ On

Type

measure on waveforms

math on parameters

advanced web edit

Source1 M1

Measure Width@level

Summary wid@lv(M1)

Actions for P1

Histogram Trend Track

Help Markers Always On Detailed ☒

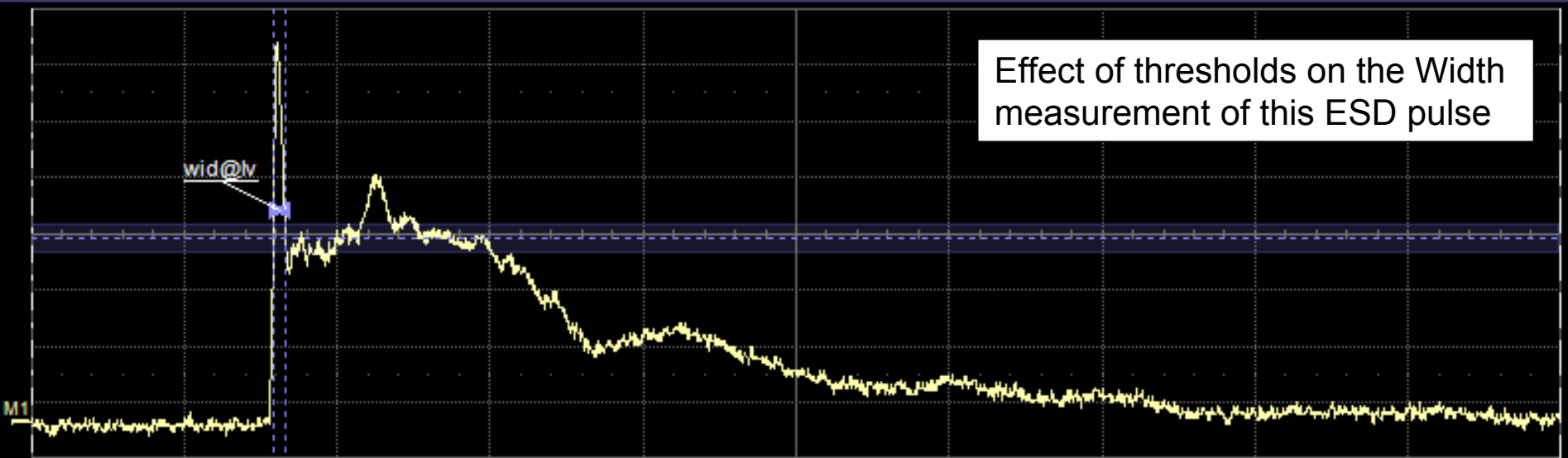
Width at Level Gate Accept Close

Time between two transitions of opposite slope at a specified level. (Slope specified for 1st transition)

Level is % 0-Max Percent level 50 % Find level

Slope Pos

Hyst. Type Divisions Hysteresis 500 mdiv



Effect of thresholds on the Width measurement of this ESD pulse

Measure value status
P1:wid@lv(M1)
23.084 ns
✓

M1
50 V/div
25.0 ns/div

Timebase 0 ns
50.0 ns/div
5.00 kS
Trigger C1
Stop 0.0 mV
Edge Positive

Measure P1 P2 P3 P4 P5 P6 P7 P8

☒ On

Type

measure on waveforms

math on parameters

advanced web edit

Source1 M1

Measure Width@level

Summary wid@lv(M1)

Actions for P1

Histogram Trend Track

Help Markers Always On Detailed

Width at Level Gate Accept Close

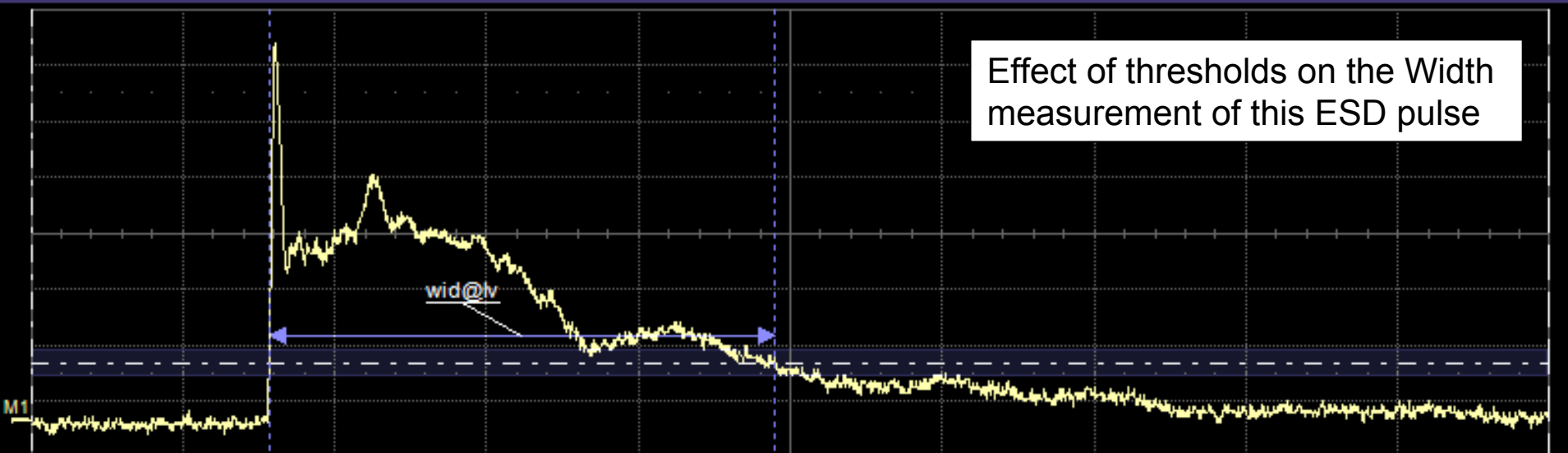
Time between two transitions of opposite slope at a specified level. (Slope specified for 1st transition)

Level is Percent level Find level

Percent 50 %

Slope Pos

Hyst. Type Hysteresis Divisions 500 mdiv



Measure
value
status

P1:wid@lv(M1)
83.106 ns

P2:---

P3:---

P4:---

P5:---

P6:---

P7:---

P8:---

M1
50 V/div
25.0 ns/div

Timebase 0 ns
50.0 ns/div
5.00 kS
Trigger C1
Stop 0.0 mV
Edge Positive

Measure

P1

P2

P3

P4

P5

P6

P7

P8

☒ On

Type



measure on
waveforms



math on
parameters



advanced
web edit

Source1

M1



Measure

Width@level

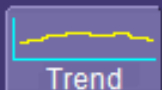
Summary

wid@lv(M1)

Actions for P1



Histogram



Trend



Track

Help

Markers

Detailed

Always On



Width at Level

Gate

Accept

Close

Time between two transitions of opposite slope at a specified level. (Slope specified for 1st transition)

Level is

Absolute

Absolute level

52.2 V

Find level

Slope

Pos

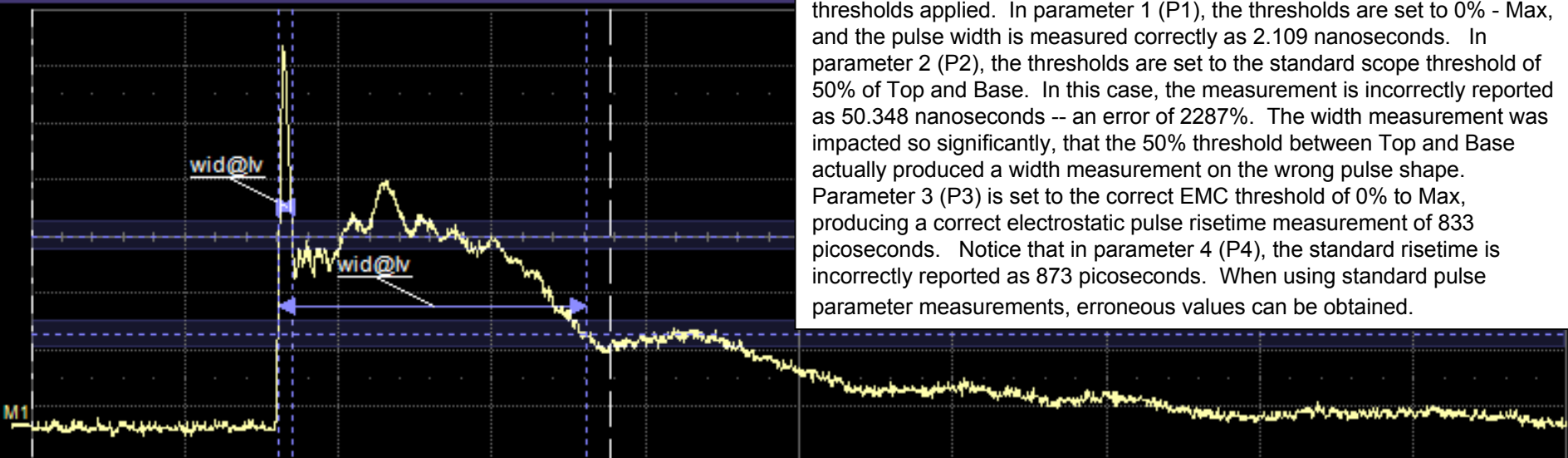
Hyst. Type

Divisions

Hysteresis

500 mdiv





The pulse width and risetime are measured, both with and without EMC thresholds applied. In parameter 1 (P1), the thresholds are set to 0% - Max, and the pulse width is measured correctly as 2.109 nanoseconds. In parameter 2 (P2), the thresholds are set to the standard scope threshold of 50% of Top and Base. In this case, the measurement is incorrectly reported as 50.348 nanoseconds -- an error of 2287%. The width measurement was impacted so significantly, that the 50% threshold between Top and Base actually produced a width measurement on the wrong pulse shape. Parameter 3 (P3) is set to the correct EMC threshold of 0% to Max, producing a correct electrostatic pulse risetime measurement of 833 picoseconds. Notice that in parameter 4 (P4), the standard risetime is incorrectly reported as 873 picoseconds. When using standard pulse parameter measurements, erroneous values can be obtained.

Measure
value
status

P1:wid@lv(M1)

2.109 ns

P2:wid@lv(M1)

50.348 ns

P3:rise@lv(M1)

833 ps

P4:rise@lv(M1)

873 ps

P5:---

P6:---

P7:---

P8:---

M1
50 V/div
25.0 ns/div

Timebase -4.54 μ s
1.00 μ s/div
200 kS 20 GS/s
Trigger C1
Stop 1.440 V
Edge Positive

Measure

P1

P2

P3

P4

P5

P6

P7

P8



On

Type



measure on
waveforms



math on
parameters



advanced
web edit

Source1

M1



Measure

Width@level

Summary

wid@lv(M1)

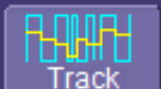
Actions for P2



Histogram



Trend



Track

Help

Markers

Always On

Detailed



Width at Level

Gate

Accept

Close

Time between two transitions of opposite slope at a specified level. (Slope specified for 1st transition)

Level is

Percent

Percent level

50 %

Find level

Slope

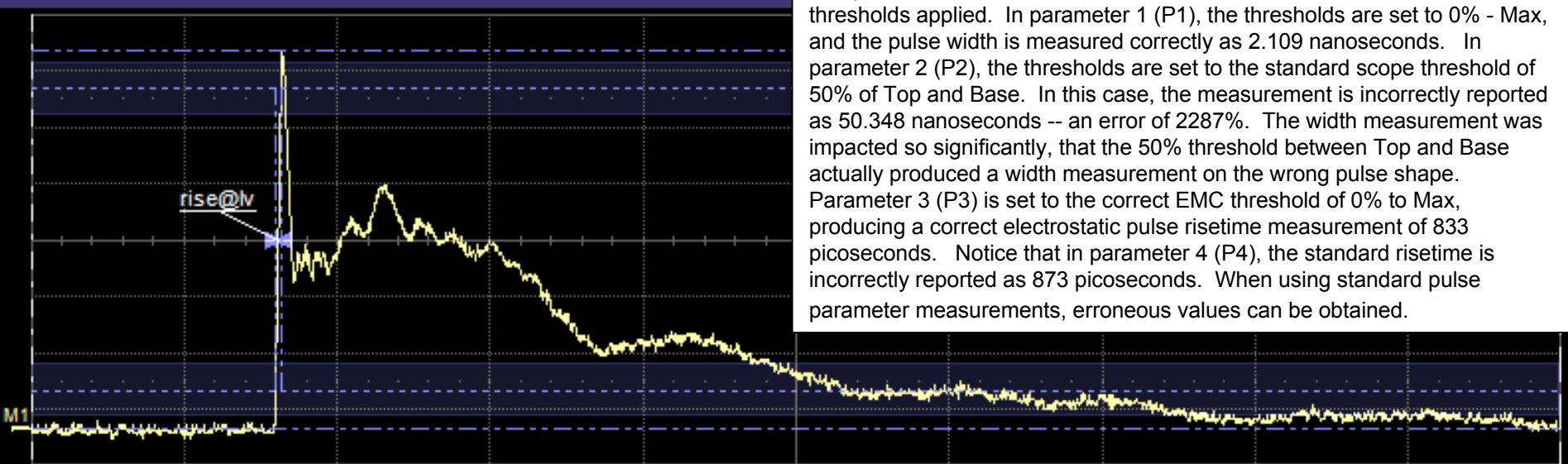
Pos

Hyst. Type

Divisions

Hysteresis

500 mdiv



The pulse width and risetime are measured, both with and without EMC thresholds applied. In parameter 1 (P1), the thresholds are set to 0% - Max, and the pulse width is measured correctly as 2.109 nanoseconds. In parameter 2 (P2), the thresholds are set to the standard scope threshold of 50% of Top and Base. In this case, the measurement is incorrectly reported as 50.348 nanoseconds -- an error of 2287%. The width measurement was impacted so significantly, that the 50% threshold between Top and Base actually produced a width measurement on the wrong pulse shape. Parameter 3 (P3) is set to the correct EMC threshold of 0% to Max, producing a correct electrostatic pulse risetime measurement of 833 picoseconds. Notice that in parameter 4 (P4), the standard risetime is incorrectly reported as 873 picoseconds. When using standard pulse parameter measurements, erroneous values can be obtained.

Measure	P1:wid@lv(M1)	P2:wid@lv(M1)	P3:rise@lv(M1)	P4:rise@lv(M1)	P5:---	P6:---	P7:---	P8:---
value	2.109 ns	50.348 ns	833 ps	873 ps				
status	✓	✓	✓	✗				

M1

50 V/div

25.0 ns/div

Timebase -4.54 μ s

1.00 μ s/div

200 kS

20 GS/s

Trigger C1

Stop 1.440 V

Edge Positive

Measure

P1

P2

P3

P4

P5

P6

P7

P8

☒ On

Type

measure on waveforms

math on parameters

advanced web edit

Source1

M1

Measure Rise@level

Summary

rise@lv(M1)

Help

Markers

Always On

Detailed

Actions for P3

Histogram

Trend

Track

Rise at level

Gate

Accept

Close

Transition time for % or absolute levels of all rising edges

Levels are

% 0-Max

High percent

90 %

Set Levels to 10% and 90%

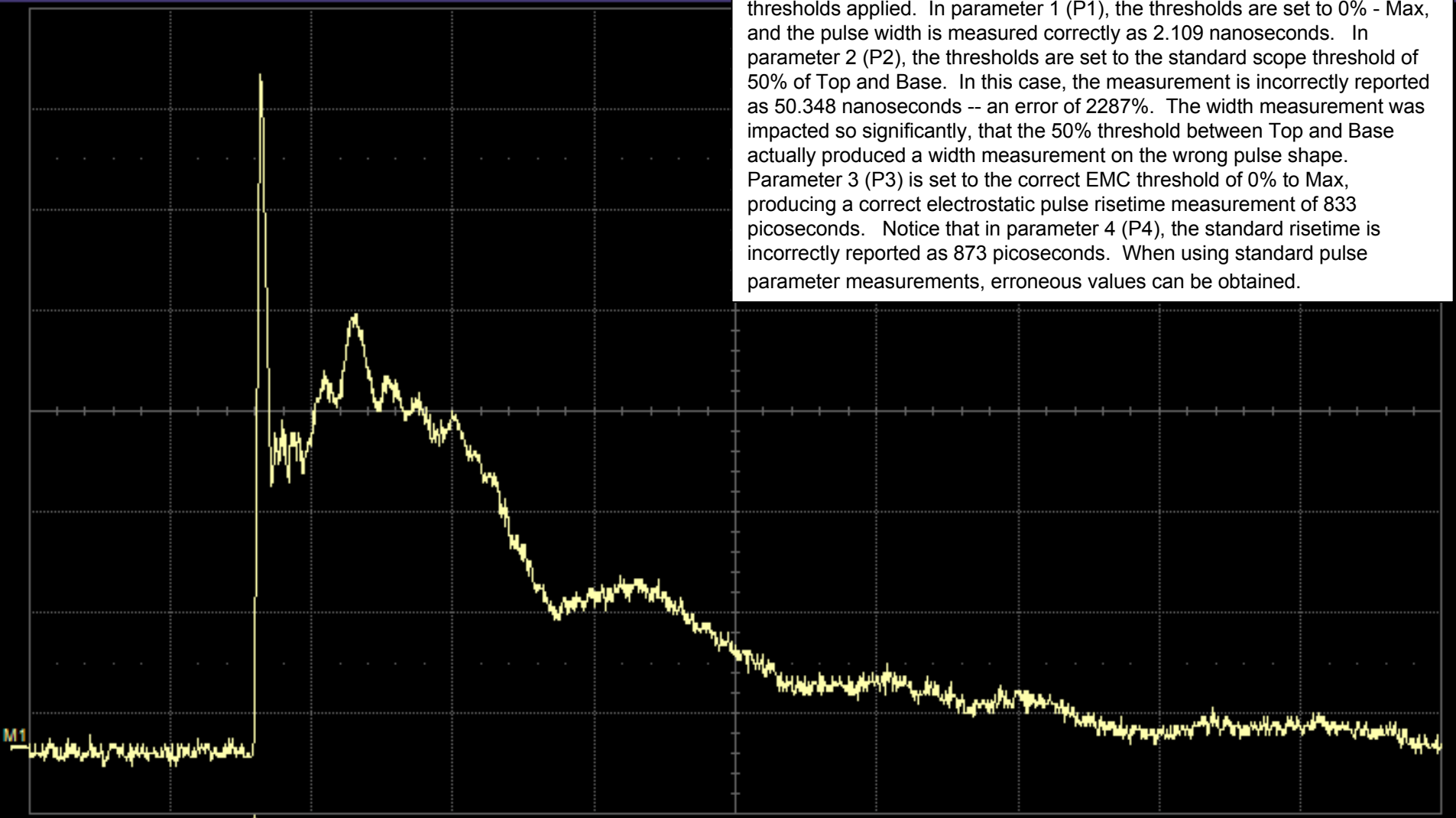
Set Levels to 20% and 80%

Low percent

10 %



The pulse width and risetime are measured, both with and without EMC thresholds applied. In parameter 1 (P1), the thresholds are set to 0% - Max, and the pulse width is measured correctly as 2.109 nanoseconds. In parameter 2 (P2), the thresholds are set to the standard scope threshold of 50% of Top and Base. In this case, the measurement is incorrectly reported as 50.348 nanoseconds -- an error of 2287%. The width measurement was impacted so significantly, that the 50% threshold between Top and Base actually produced a width measurement on the wrong pulse shape. Parameter 3 (P3) is set to the correct EMC threshold of 0% to Max, producing a correct electrostatic pulse risetime measurement of 833 picoseconds. Notice that in parameter 4 (P4), the standard risetime is incorrectly reported as 873 picoseconds. When using standard pulse parameter measurements, erroneous values can be obtained.



Measure	P1:wid@lv(M1)	P2:wid@lv(M1)	P3:rise@lv(M1)	P4:rise@lv(M1)	P5:---	P6:---	P7:---	P8:---
value	2.109 ns	50.348 ns	833 ps	873 ps				
status	✓	✓	✓	✗				

M1

50 V/div

25.0 ns/div

Timebase

-4.54 μ s

1.00 μ s/div

200 kS

Trigger

C1

Stop

1.440 V

Edge

Positive