MULTI-PHASE POWER MEASUREMENTS WITH AN OSCILLOSCOPE

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ROHDE&SCHWARZ

Make ideas real



AGENDA

- Types of Multi-phase Measurements
- Power Measurements on an Oscilloscope
- Multi-Phase Buck Converter
- 1 and 3 Phase Inverter Measurements

Types of Multi-phase Measurements

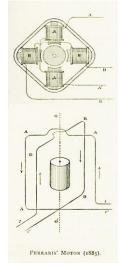
MULTI-PHASE APPLICATIONS

Oscilloscopes provide multiple channels that are time aligned, allowing easy measurement of timing events between different signals

In Power Applications, multiple phases are used in both power transmission and power conversion

AC Line Power – 3 phase (may be moving to 6 phase)

Inverters and Motor Drives – single and three phase are both common





https://en.wikipedia.org/wiki/Three-phase_electric_power

MULTI-PHASE APPLICATIONS

Buck Converters – Multiple Phases in a single converter to provide more current output

2 Multiphase Buck Regulator Overview

A multiphase buck regulator is a parallel set of buck power stages as shown in Figure 2-1 and Figure 2-2, each with its own inductor and set of power MOSFETs. Collectively, these components are called a phase. These phases are connected in parallel and share both input and output capacitors. During steady-state operation, individual phases are active at spaced intervals equal to 360° / n throughout the switching period where n is the total number of phases. Figure 2-2 shows a TPS53679 multiphase controller demonstration board and TI power stages for a six-phase design.

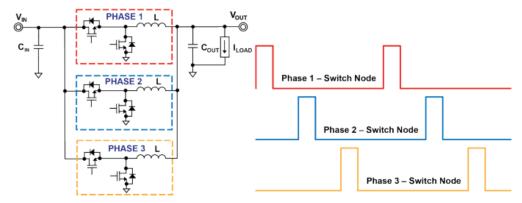


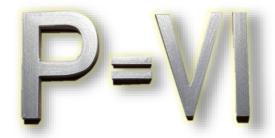
Figure 2-1. Multiphase Regulator Example

https://www.ti.com/lit/an/slva882/slva882.pdf



Power Measurements on an Oscilloscope

POWER BASICS

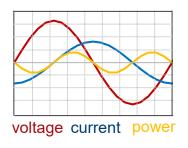


- ▶ What Voltage, and Current are used? (DC? Peak? Peak-to-Peak? Max? RMS?)
- ▶ What units is P given in?
- ▶ What if my supplied voltage is not DC or sinusoidal?
- ▶ What if my Load is not purely resistive?

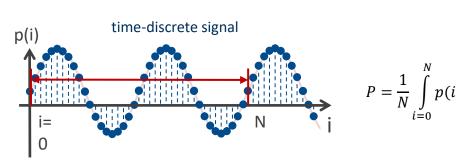
Oversimplification leads to errors. A DVM or DMM is not always an appropriate tool to make these measurements. You need an Oscilloscope!

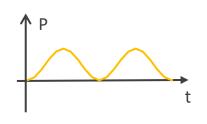
POWER BASICS

Oscilloscopes and Power Analyzers take advantage of ADCs that digitize the signal, and allow for analysis on full waveforms, characterizing correctly RMS values for current and voltage for non-ideal waveforms.



Yes, but!





ideal world

no phase shift & no distortion



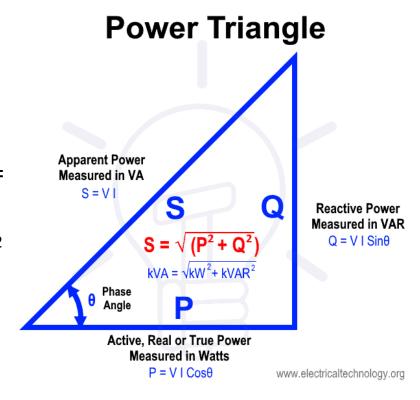
! real world!

phase shift & distortion

POWER TRIANGLE – A MORE COMPLETE LOOK

These values can be manually measured with an Oscilloscope. Measurements made across 1 cycle.

- Apparent Power (S, in V*A) = Vrms * Irms
- Real (or Active or True) Power (P, in Watts) =
 Mean (V*I)
- Reactive Power (magnitude in Q) = $\sqrt{S^2 P^2}$
- Power Factor (λ) = P/S
- Phase Angle = cos⁻¹ λ



Multi-Phase Buck Converter

IN-SITU INDUCTOR CURRENT MEASUREMENT IN MULTI-PHASE BUCK CONVERTERS

Application

- Measure current loading of multi-phase buck converter
- Observe PMIC control function

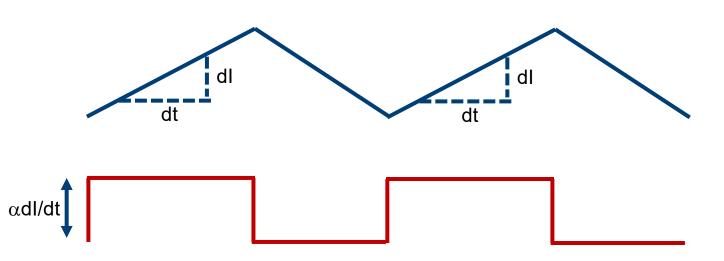
▶ Problem

- Access is generally limited due to the placement of many PMIC's and inductors
- Standard probes such as clamp-on, Rogowski, shunt resistor, etc. cannot be used

▶ Solution

- Measure H-field using a near-field probe (non-invasive)
- Signal is a pulse proportional to the inductor current slope

MEASURING CURRENT USING A NEAR FIELD PROBE



 α is a function of the probe geometry and gain

EXAMPLE MEASUREMENT ON A 10-PHASE BUCK CONVERTER

Wire loops used to sense H-field

Passive voltage probes



Differential voltage probe

Load step generator board

Pulse generator input to gate drivers

MEASUREMENT RESULTS – LOAD STEP



Near field signal for each phase (7 phases measured)

Track of pulse width

Slope times increase in response to load step. Track amplitude shows imbalance

MEASUREMENT RESULTS – LOAD STEP REMOVED



Near field signal for each phase (7 phases measured)

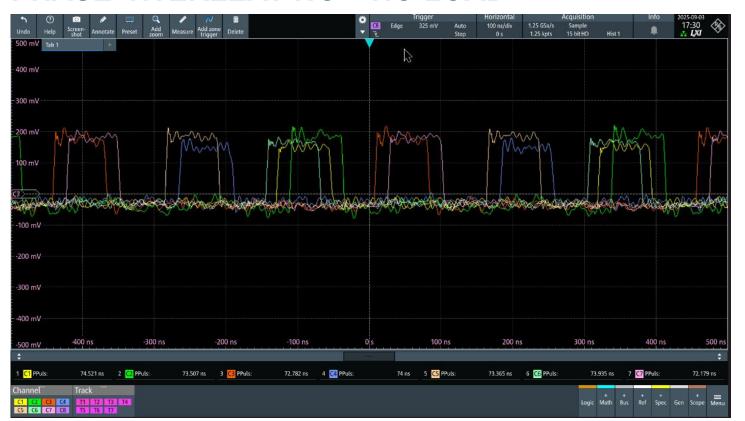
Track of pulse width

Switching stops when load is removed (discontinuous conduction)

MEASUREMENT RESULTS – NO LOAD



PHASE INTERLEAVING - NO LOAD

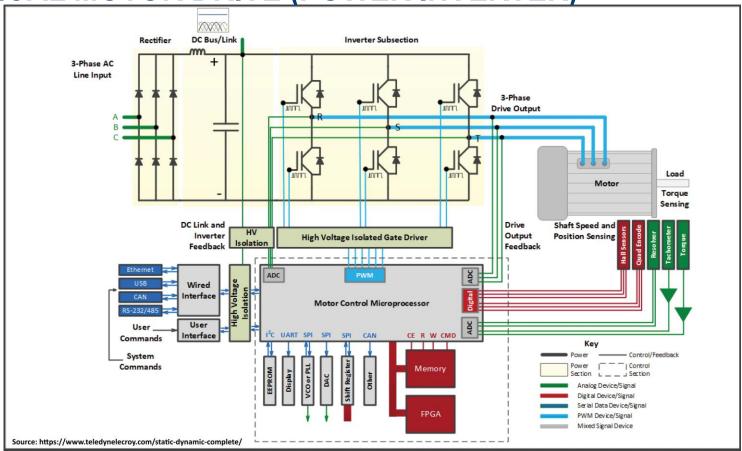


Not all phases measured



1 and 3 Phase Inverter Measurements

TYPICAL MOTOR DRIVE (POWER INVERTER)



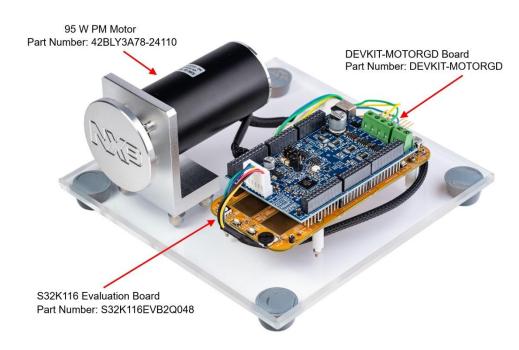
3-PHASE PMSM MOTOR S32K116 BLDC/PMSM DEVELOPMENT KIT

Motor

 42BLY3A78-24110: 3-phase PM motor, 24 V, 95 W, 9000 rpm, 6 A, 2 pole pairs

Power supply

 PSD-1270APL05: 12 V, 7 A + universal AC plug adapter



Permanent-Magnet Synchronous Motors

3-PHASE PMSM MOTOR S32K116 BLDC/PMSM DEVELOPMENT KIT

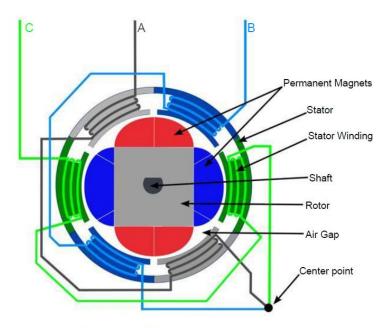


Figure 1. BLDC motor - cross-section

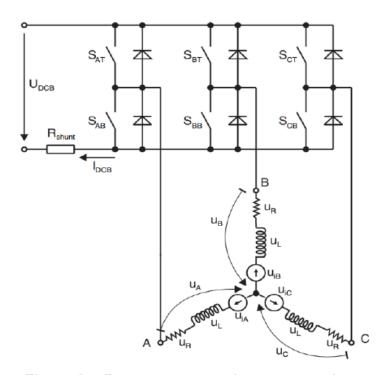
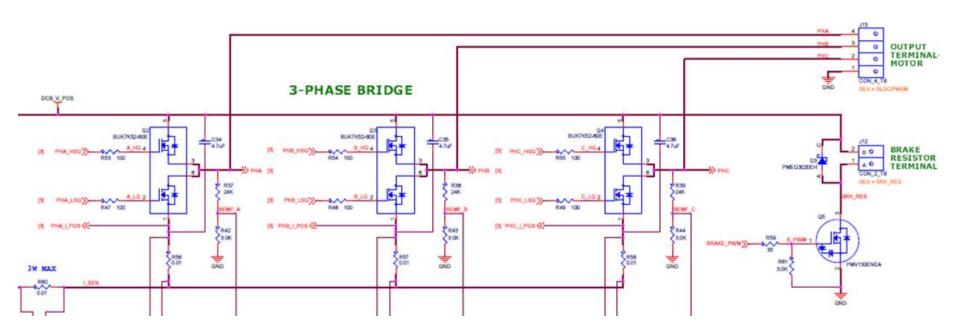


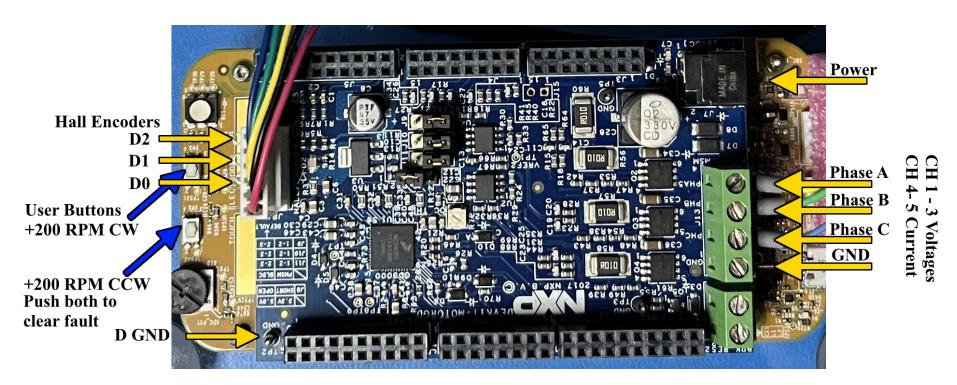
Figure 3. Power stage and motor topology

3-PHASE INVERTER OF THE S32K116

Note that this motor uses Half H-Bridge

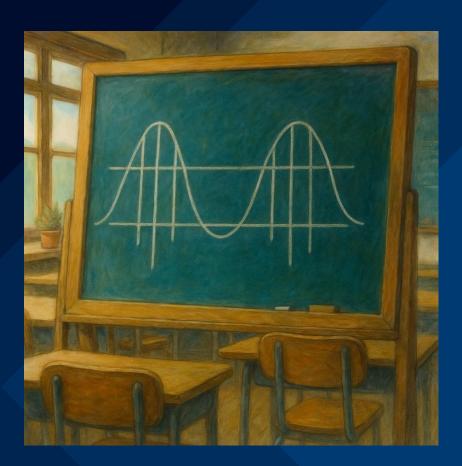


3-PHASE PMSM MOTOR S32K116 BLDC/PMSM DEVELOPMENT KIT



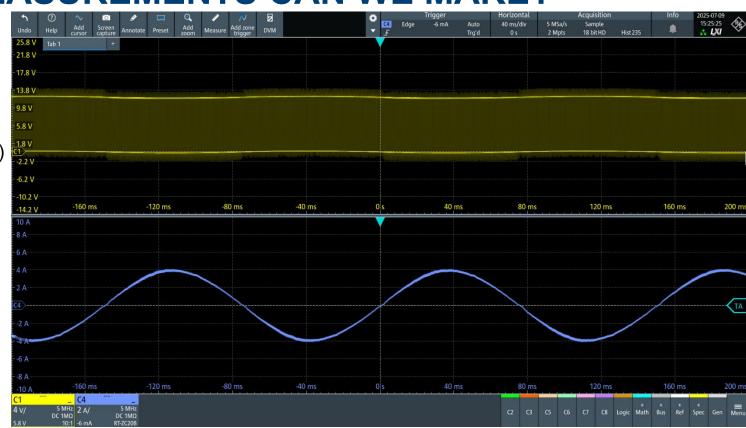
What Measurements Can We Make?

1 Phase



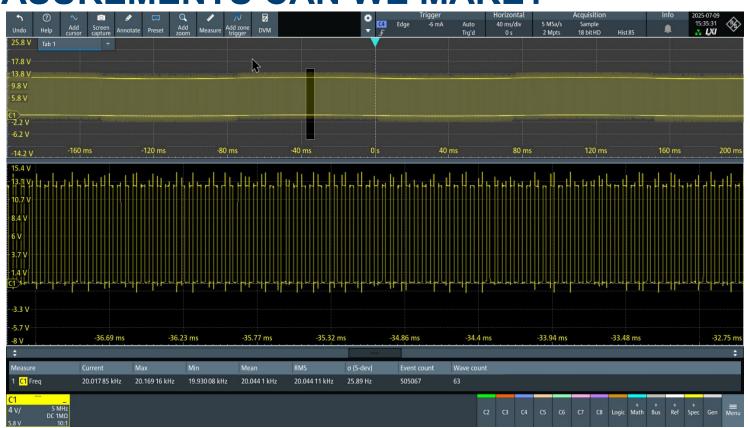
View of Phase A

- Carrier Frequency
- % Duty Cycle change
- Motor Speed (RPM)
- V rms
- I rms
- VA
- P



Carrier (Switching) Frequency

 Simple frequency measurement on CH1, zoomed in to show the square wave



% Duty Cycle change

- Positive Duty Cycle Measurement
- Add a Track
- + and values will be shown, but this can vary with the speed of the motor



Motor Speed (RPM)

- requires a frequency measurement to show electrical cycles. Could be the PDCyc measurement, Current Measurement, or even the output of the Hall Encoders
- 6.68 Hz in this setup.

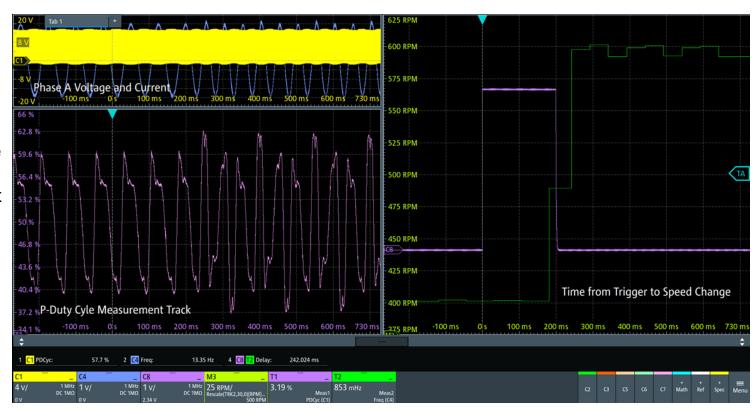


Motor Speed (RPM) – How do we get RPM from 6.68Hz?

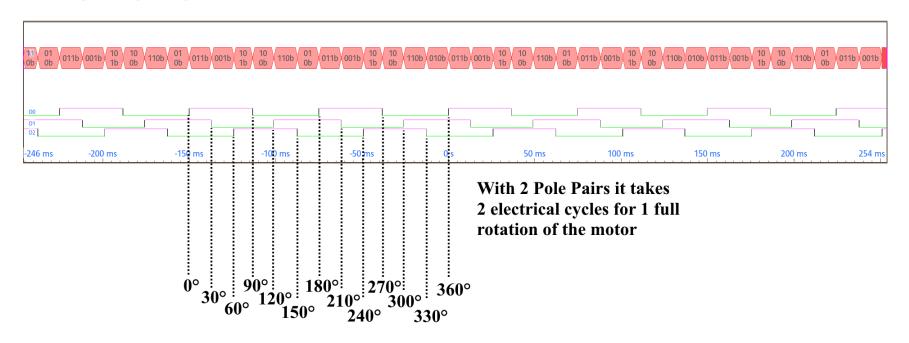
- We know from the Motor specifications that there are 2 Polar Pairs. This means that there will be 2 electrical cycles per 1 mechanical revolution.
- RPM = Frequency / (# Polar Pairs) * 60s = 6.68 / 2 * 60 = 200 RPM.
- We could make a math trace using this formula taking the track of a frequency measurement to show speed over time. (e.g. Rescale of Track * 30)
- AC Induction motor's speed are impacted by slip, and gear ratios, making the calculation more complex.

Time to Change Speed

- Using a rescale of the track of the frequency measurement of the track of the Pduty Cycle measurement of Phase A, we can plot the RPM of the motor
- Trigger on the Speed Change button, and measure delay until RPMs change



Motor Speed (RPM) -Hall Encoder



V and I rms

 To Accurately measure V rms or I rms, we need either a Cycle RMS measurement, or to capture enough cycles that a partial cycle in the measurement does not skew the results. Both have challenges.

Cycle RMS:

- Set up measurement Gate to cover 1 electrical cycle (can eyeball based on PDCyc track, of current measurement)
- Try to set up your total acquisition time to be an even multiple of an electrical cycle

Long Duration RMS measurement:

This would take a large amount of data to do so well on an Oscilloscope, but we have a built in DVM that
makes this easy. We can set its measurement period to a maximum of 1 second.

V rms

- P Both the gated RMS and the DC RMS with the Measurement time set to 1s agree
- 8.65V-ish



I rms

Easier to measure, since its cycle is correct. Could use a Cycle RMS measurement, or any of the other two method

2.76 A



Apparent Power in VA

- Apparent Power is the power required to drive the circuit
- Vrms * Irms

Scope Measurements:

8.65V * 2.76A = 23.874VA

DVM measurements

- 8.64V * 2.72A =
- 23.5VA

DVM is continuously running, so not including the waveform in acq memory



Active Power in W

- Active Power gets used up in the circuit
- Cycle Mean of the Power Waveform (V*I)

Same Cycle challenges as with Voltage. Use the Gates and a Mean Measurement

1.562W



DERIVED POWER MEASUREMENTS

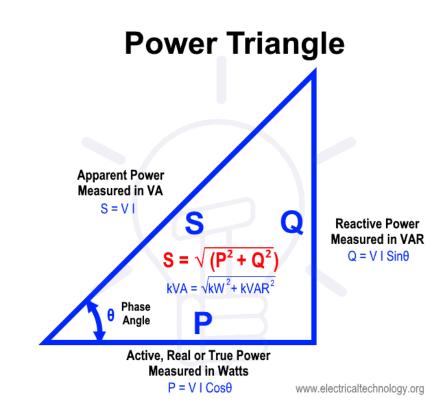
With a known Active and Apparent power, we can calculate the rest of the Power Triangle

$$S = 23.874VA, P = 1.562W$$

$$Q = \sqrt{S^2 - P^2} = \sqrt{23.874^2 - 1.562^2} = 23.82 \text{ VAR}$$

Power Factor = P / S =
$$1.562 / 23.874 = 0.065 \lambda$$

Phase Angle = $\cos^{-1} \lambda = \cos^{-1} 0.065 = 86.24$ degrees

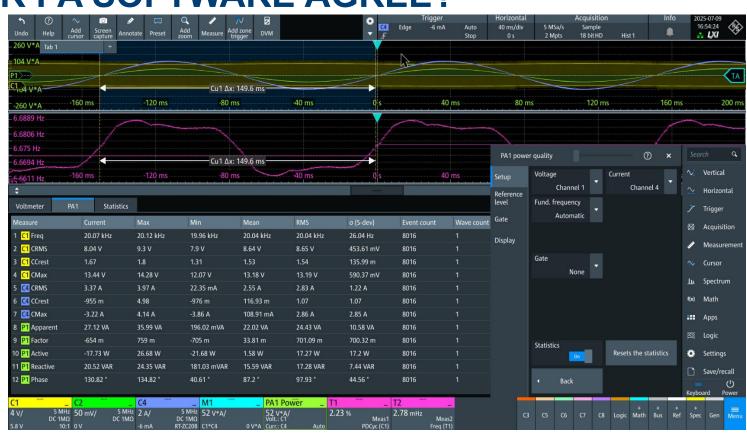


DOES OUR PA SOFTWARE AGREE?

That Pesky Cycle Issues creeps in again

The PA (Power Analyzer) software grabs the cycle from our carrier frequency on Ch1. The Mean and RMS measurements are closer, using all 8K events. Setting the Fund. Frequency manually doesn't change how the cycles are sliced and calculated.

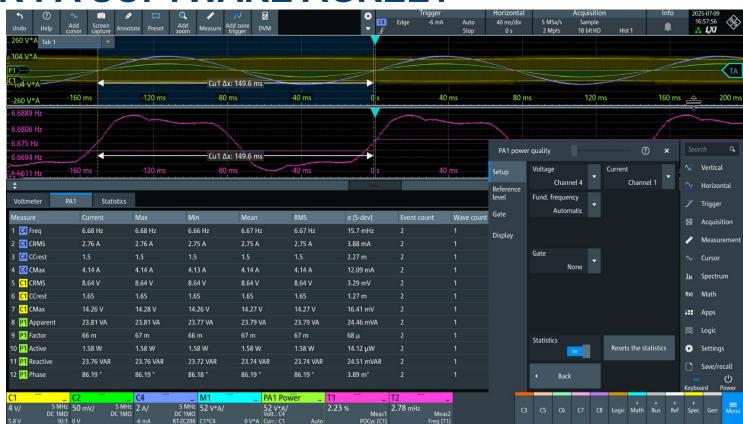
Solution – Trick* the PA software, swap sources for I and V



DOES OUR PA SOFTWARE AGREE?

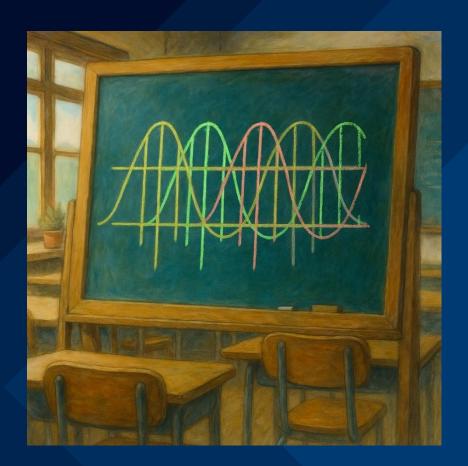
Compare to Calculated Results

V rms = 8.65V I rms = 2.76 A P = 1.562W S = 23.874VA Q = 23.82 VAR PF = 0.065 λ Phase = 86.24degrees



What Measurements Can We Make?

3 Phases



PHASE TO PHASE MEASUREMENTS

Compare the Phases of the Duty Cycle Tracks to the Current waveforms

We expect these to be 120 degrees apart for a balanced system. They are very close.



WHAT ABOUT TOTAL POWER OF ALL 3 PHASES

Three Wattmeter Method

The total power (P, S, Q) of the system is the Sum of all 3 together. If the system is balanced, we can assume it is 3x of any individual leg measurement.

Two Wattmeter Method

In many systems, the voltages cannot be measured for each phase from line-to-neutral. Instead we have to measure them line-to-line.

Let's test it out!

THREE WATTMETER METHOD



P total = 4.25W

S total = 71.39VA

Q total = 71.27VAR

TWO WATTMETER METHOD



P total = 4.8W

S total = 21.05VA

Q total = 20.41VAR

P total = 4.25W

S total = 71.39VA

Q total = 71.27VAR 3 Wattmeter Method

P total = 4.8W

S total = 21.05VA

Q total = 20.41VAR 2 Wattmeter Method

P is close (ish), but S and Q are very far off? What's going on?

Answer – Apparent power is heavily impact by the DC offset of the signals and the harmonic content of the carrier. This also impacts the viewed values of Q, but does not have as large of an impact on P.

In our Power Analyzers we handle this with a dual path A/D converter, one for narrow band and one for wideband.

Our Oscilloscope by default is Wideband, but it has tools that allow us to get a narrow band measurement.

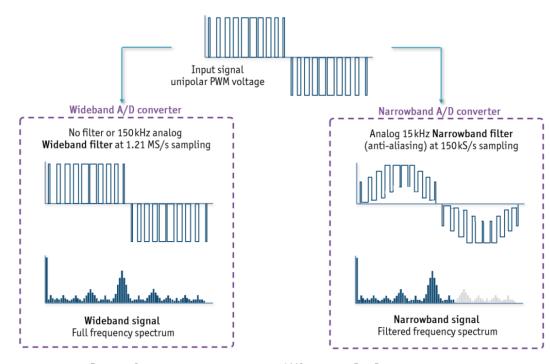


Figure 4: Schematic representation of the LMG600 series DualPath signal processing

Wideband spectrum of the Voltage for Phase A



Narrowband spectrum of the Voltage for Phase A

AC Coupling to remove DC component

HD Mode Filter set to 1KHz BW



THREE WATTMETER METHOD



P total = 4.71W

S total = 5.62VA

Q total = 2.89VAR

TWO WATTMETER METHOD



P total = 4.58W

S total = 5.71VA

Q total = 2.9VAR

RESULTS COMPARED AGAIN

P total = 4.71W S total = 5.62VA

Q total = 2.89VAR 3 Wattmeter Method

P total = 4.58W S total = 5.71VA

Q total = 2.9VAR 2 Wattmeter Method

These results are much closer!

RESULTS COMPARED WITH VARIOUS METHODS

In these measurements, LPF was with an FIR custom math filter, instead of using the HD mode filter

Note: R&S will be launching 3-phase and motor analysis software for the MXO Oscilloscopes over the next few firmware releasees

Part of that software features selecting a sync signal to correctly grab cycles even from PWM signals

				Filtered Waveforms	AC Coupled and Filterd Waveforms	
Two Wattmeter Method	VArms	8.5	5.98	5.47	0.542	
	VBrms	8.62	6.11	5.49	0.508	V
	VCrms	8.55	6.04	5.49	0.542	٧
	IArms	2.74	2.73	2.75	2.74	Α
	IBrms	2.77	2.78	2.78	2.79	Α
	ICrms	2.77	2.78	2.78	2.79	Α
	VArms * IArms	23.4	16.36	15.03	1.49	VA
	VBrms * IBrms	23.95	16.98	15.25	1.42	VA
	VCrms * ICrms	23.7	16.83	15.25	1.51	VA
	Total	71.05	50.17	45.53	4.42	VA
	Reactive (A)	23.47	16.49	15	0.655	VAR
	Reactive (B)	23.98	17.04	15.2	0.682	VAR
	Reactive (C)	23.89	17.68	15.22	0.917	
	Total	71.34	51.21	45.42	2.254	
		11.51	51.21			
	Mean (VArms * IArms)	1.7	1.52	1.44	1.34	w
	Mean (VBrms * IBrms)	1.59	1.43	1.39	1.25	w
	Mean (VCrms * ICrms)	1.25	1.36	1,11	1.2	
	Total	4.54	4.31	3.94	3.79	
100 100 100 100 100 100 100 100 100 100						
Two Wattmeter Method	V(A C)rms	3.64	3.55	0.96	0.92	V
	V(B C)rms	3.51	3.52	0.88	0.869	V
	(===)					-
	V(A C)rms * IArms	9.98	9.81	2.65	2.53	VA
	V(B C)rms * IArms	9.75	9.77	2.43		
	Total	19.73	19.58	5.08		
			10.00	5.55		
	Reactive (A-C)	9.73	9.71	0.803	0.562	VAR
	Reactive (B-C)	9.77	9.81	1.96		VAR
	Total	19.5	19.52	2.763	2.612	
Ž	1000	10.0	10.02	2.100	2.012	.,
	mean (V(A-C)rms * IArms)	2.85	2.8	2.52	2.47	w
	mean (V(B-C)rms * IBrms)	1.71	1.47	1.51	1.29	
	Total	4.56	4.27	4.03		
	Total	4.50	7.21	4.03	3.70	**